

• Some comments from last class

time [years]	qwell [Sm ³ /d]	Gp [Sm ³]	Z	RF	PR [bara]	pwf [bara]	pwh [bara]	ptemp [bara]	qtemp [Sm ³ /d]	qfield [Sm ³ /d]	Pplem [bara]	Psep [bara]	Deltapchoke [bara]
0	2.22E+06	000.0E+0	0.967	000.0E+0	276	271.95	245.568	83.96564	6.66E+06	2.00E+07	81	35	162
1	2.22E+06	7.3E+9	0.963	27.0E-3	268.548	264.3839	238.387	83.96564	6.66E+06	2.00E+07	81	35	154
2	2.22E+06	14.6E+9	0.957	54.0E-3	259.8348	255.5287	229.9684	83.96564	6.66E+06	2.00E+07	81	35	146
3	2.22E+06	21.9E+9	0.953	81.0E-3	251.0633	246.6041	221.4669	83.96564	6.66E+06	2.00E+07	81	35	138
4	2.22E+06	29.2E+9	0.948	108.0E-3	242.4487	237.8281	213.0883	83.96564	6.66E+06	2.00E+07	81	35	129
5	2.22E+06	36.5E+9	0.944	135.0E-3	234.0167	229.2262	204.8559	83.96564	6.66E+06	2.00E+07	81	35	121
6	2.22E+06	43.7E+9	0.941	162.0E-3	225.7596	220.79	196.7603	83.96564	6.66E+06	2.00E+07	81	35	113

no decimal points!

$$q = C_r \left(\frac{P_1^2}{e^S} - P_2^2 \right)^{0.5}$$

$$P_2 = \left(\frac{P_1^2}{e^S} - \left(\frac{q}{C_r} \right)^2 \right)^{0.5} \quad \text{will give error if}$$

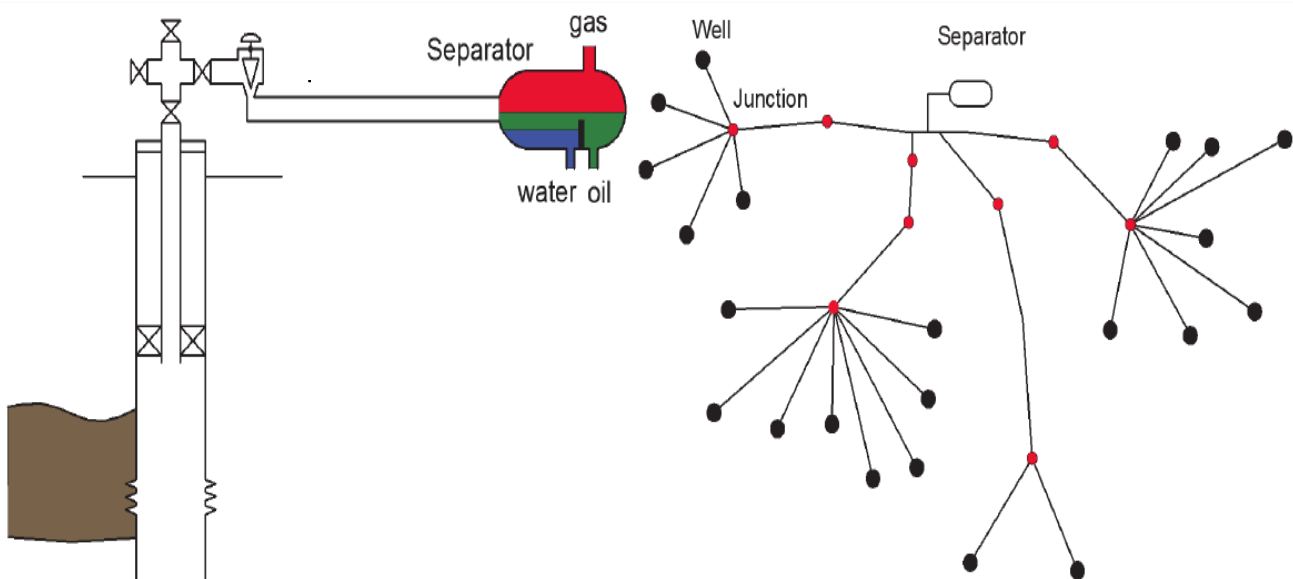
$$\frac{P_1^2}{e^S} < \frac{q^2}{C_r^2}$$

• be careful with initial assumptions of variables for calculating equilibrium!

might cause problems when computing co-current calculation of Δp !

//

Architecture of a production system.

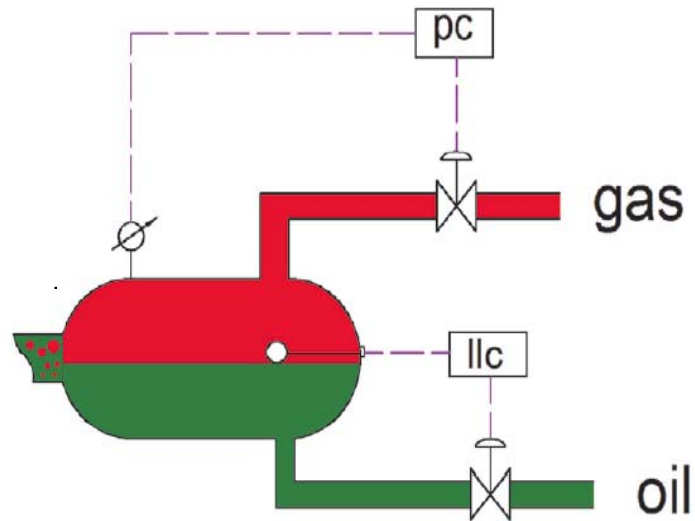
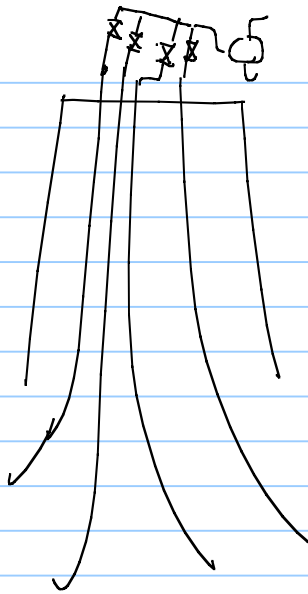


(a)

standalone wells

(b)

commingling network



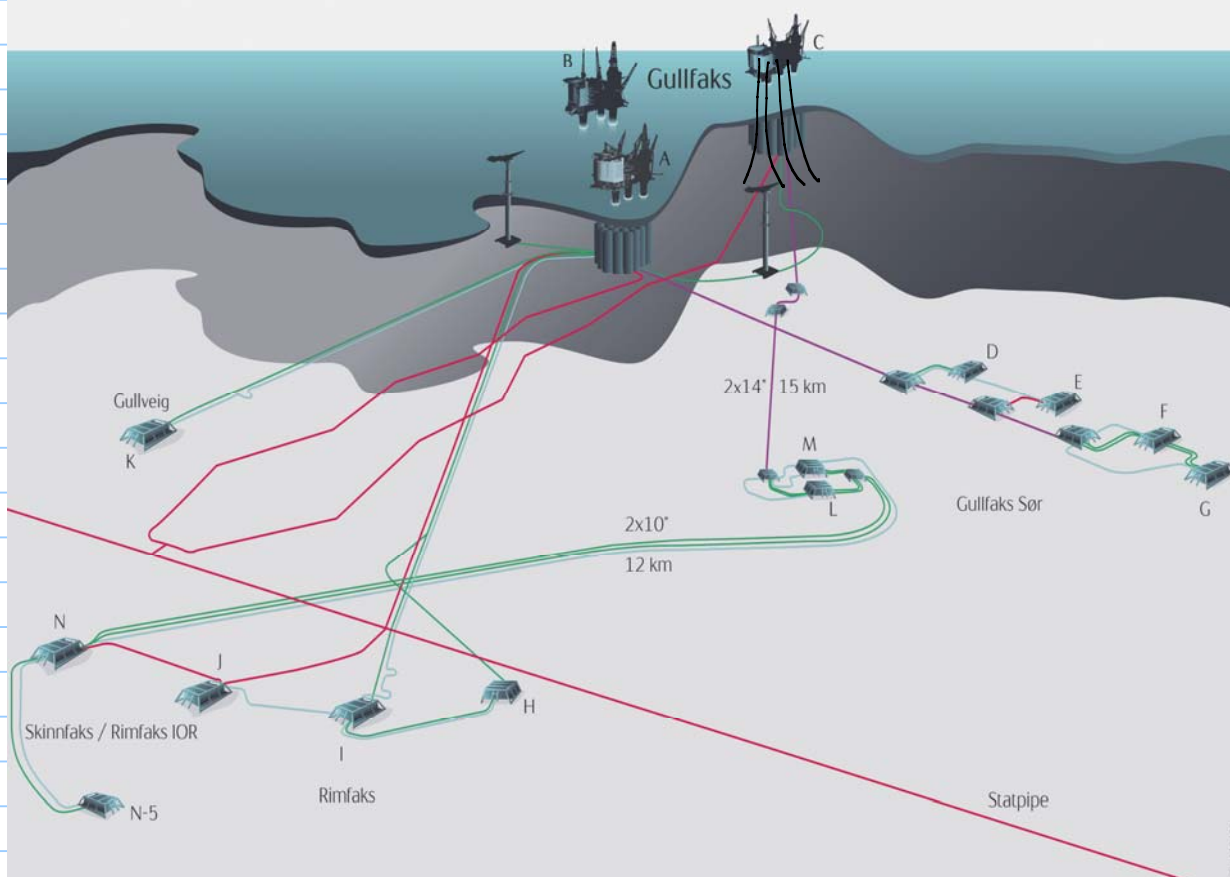
pc ...pressure controller
llc ...liquid level controller

hydraulic dependency ends up at the separator.

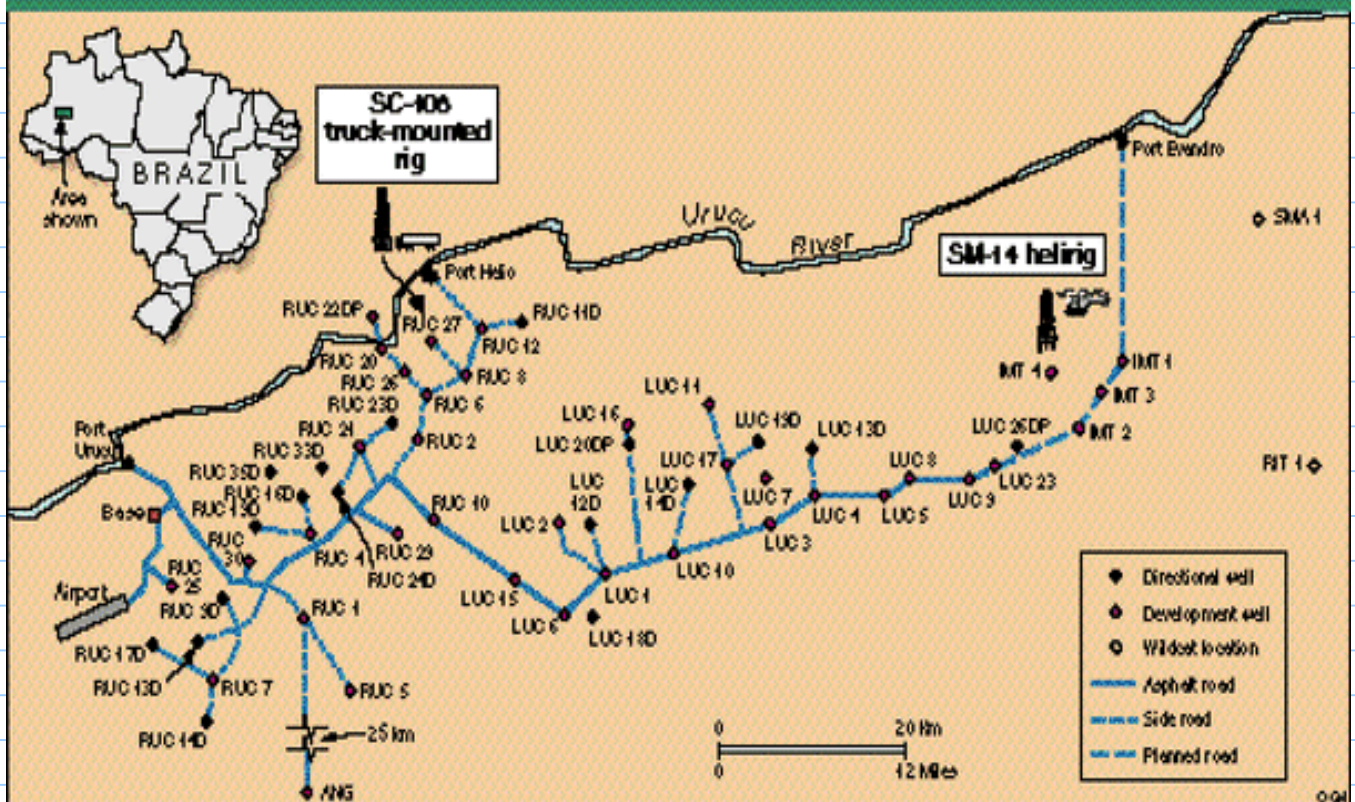


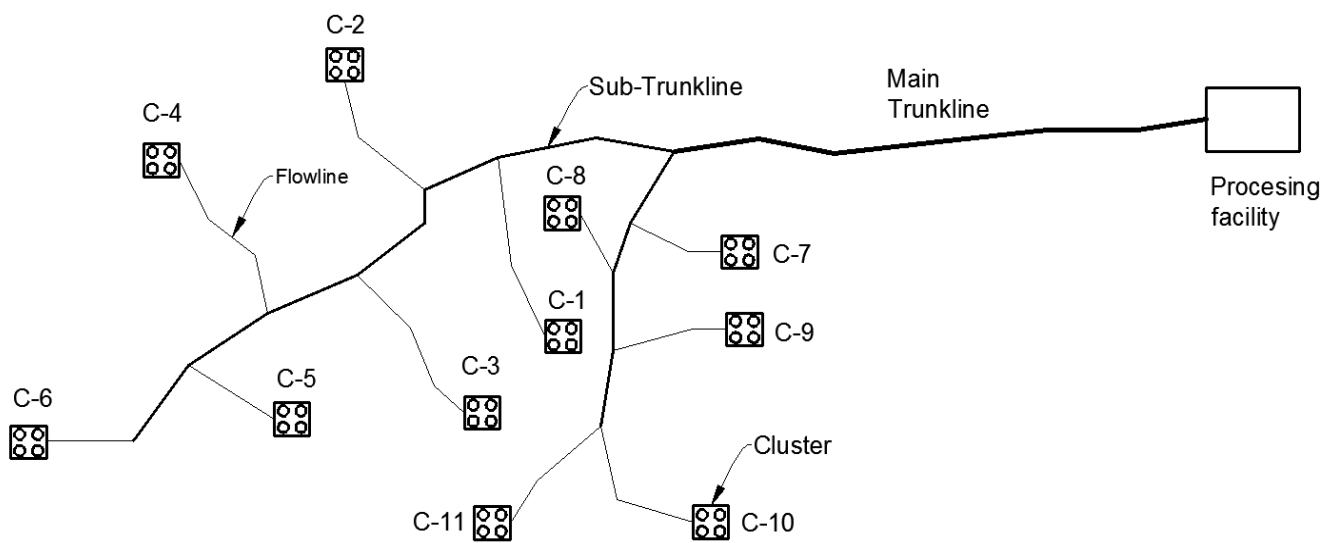
Salym

Gullfaks field lay out



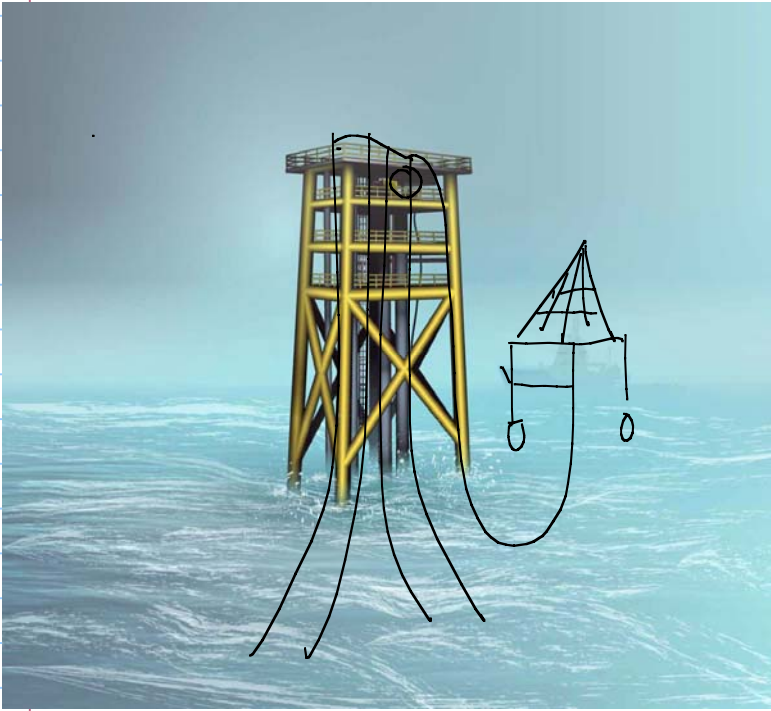
RIO URUCU GAS DEVELOPMENT LAYOUT



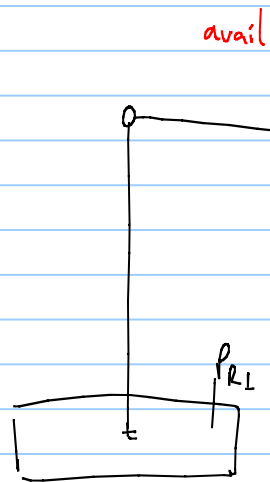
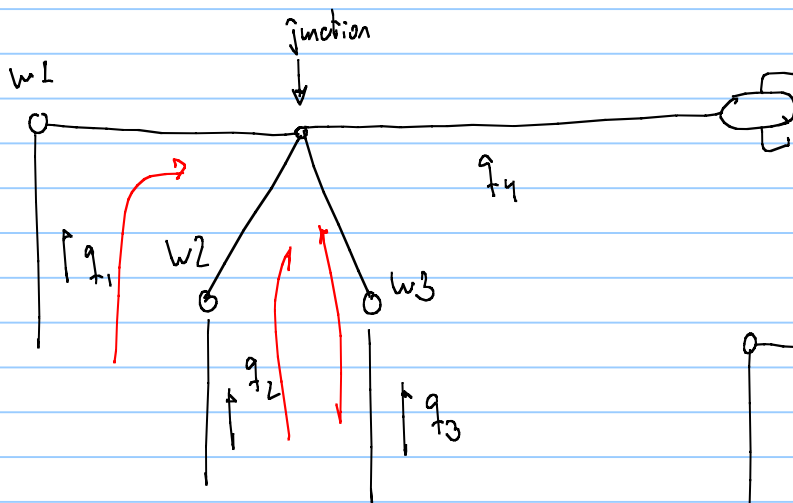




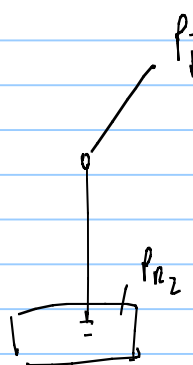
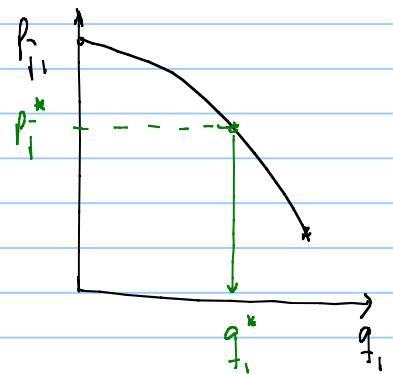




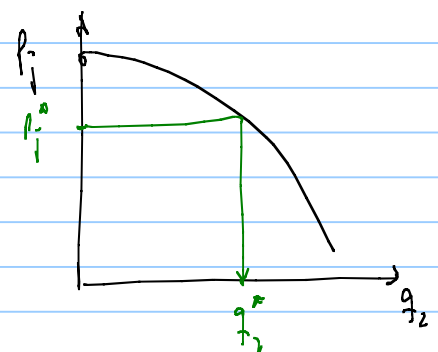
Hydraulic performance of production networks.

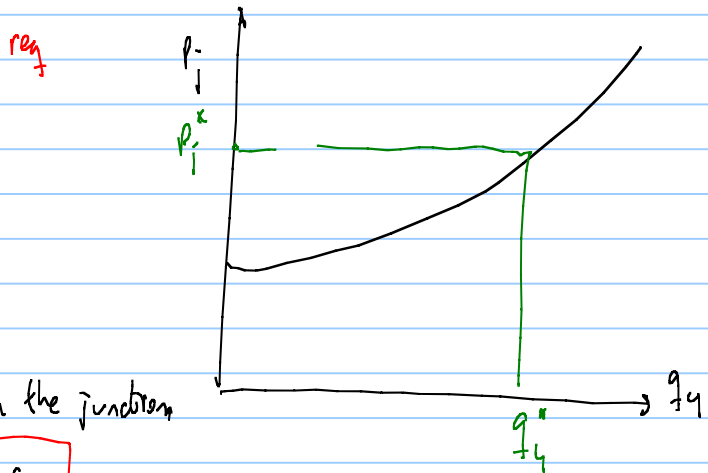
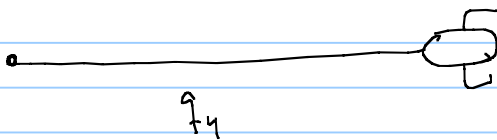
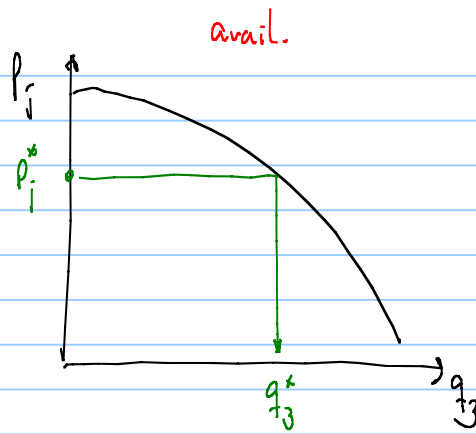
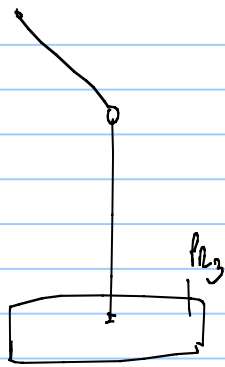


avail.



avail.





mass conservation in the junction

$$q_4 = q_1 + q_2 + q_3$$

assumed Method to solve

1. Assume p_j^*

$$p_{j1} = p_{j2} = p_{j3} = p_{j4}$$

2. Read $q_1^*, q_2^*, q_3^*, q_4^*$

↓ ↓ ↓ ↓

avail avail avail required

3. Check for mass conservation $q_1^* + q_2^* + q_3^* - q_4^* = 0$

iterating with rate

1. Assume $q_1^* \rightarrow p_{j1}^*$

2. assume $q_2^* \rightarrow p_{j2}^*$

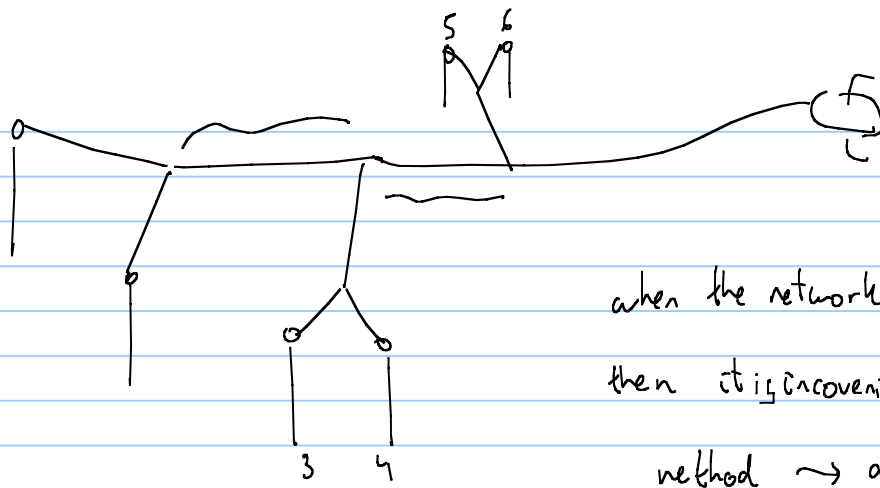
3. assume $q_3^* \rightarrow p_{j3}^*$

4. $q_4^* = q_1^* + q_2^* + q_3^*$

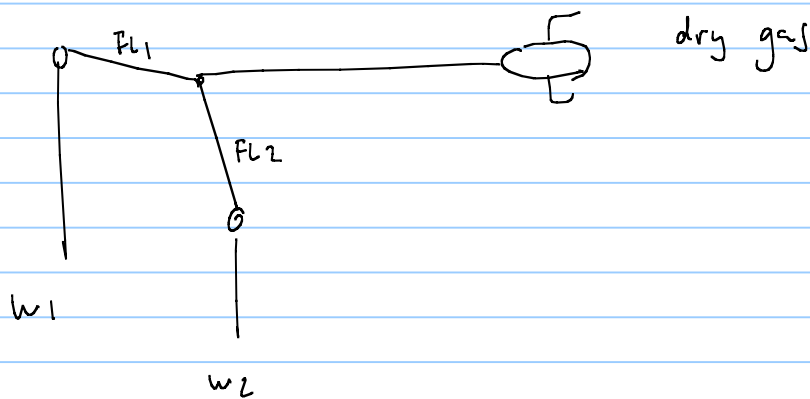
5. with q_4^* read p_{j4}^*

6. check if

$$p_{j1}^* = p_{j2}^* = p_{j3}^* = p_{j4}^*$$



when the network is too complex
then it is inconvenient to use the graphical
method $\rightarrow$ analytical method



eq	unk.			
2	4	IPR	$q_1 = C_{R1} (P_{R1}^2 - P_{wh1}^2)^{n_1}$	$q_2 = C_{R2} (P_{R2}^2 - P_{wh2}^2)^{n_2}$
2	2	tubing	$q_1 = C_{T1} \left(\frac{P_{wh1}^2 - P_{ah1}^2}{e^{fL_1}} \right)^{0.5}$	$q_2 = C_{T2} \left(\frac{P_{wh2}^2 - P_{ah2}^2}{e^{fL_2}} \right)^{0.5}$
2	1	flowlines	$q_1 = C_{FL1} (P_{wh1}^2 - P_j^2)^{0.5}$	$q_2 = C_{FL2} (P_{wh2}^2 - P_j^2)^{0.5}$
1	0	pipeline	$q_1 + q_2 = C_{PL} (P_j^2 - P_{sep}^2)^{0.5}$	
7	7			

$\rightarrow$ can solve this system of equations using a numerical method,

$\rightarrow$ Newton-Raphson for a system of equations

The graphical procedure is based on first-order Taylor series expansion

$$f(x_{i+1}) = f(x_i) + (x_{i+1} - x_i) f'(x_i)$$

One approach for solving a set of NLE is to use multi-dimensional version of Newton Raphson method *for one equation above;* this is based on multi-dimension

Taylor series expansion:

for example,

$$\frac{f_1(x_1, x_2)}{f_2(x_1, x_2)}$$

$$f_1^{i+1} = f_1^i + \underbrace{(x_1^{i+1} - x_1^i)}_{dx_1} \frac{\partial f_1^i}{\partial x_1} + \underbrace{(x_2^{i+1} - x_2^i)}_{dx_2} \frac{\partial f_1^i}{\partial x_2}$$

$$f_2^{i+1} = f_2^i + \underbrace{(x_1^{i+1} - x_1^i)}_{dx_1} \frac{\partial f_2^i}{\partial x_1} + \underbrace{(x_2^{i+1} - x_2^i)}_{dx_2} \frac{\partial f_2^i}{\partial x_2}$$

Recal for single equation

$$f'(x) \cdot dx = -f(x)$$

We can prove (soon) that this equation is valid for set of equations and can be written as an Array Formula As matrix

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix} \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix} = - \begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix}$$

$$\frac{\partial \bar{f}}{\partial \bar{x}} \cdot d\bar{x} = -\bar{f}$$

- The partial derivative matrix is called the Jacobian of the system. Thus

$$J \begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix} = - \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$\begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix} = -J^{-1} \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$\begin{bmatrix} dx_1 \\ dx_2 \end{bmatrix} = - \frac{\begin{bmatrix} f_1 \\ f_2 \end{bmatrix}}{J} =$$

In algebraic form:

$$dx_1 = \underbrace{x_1^{i+1} - x_1^i}_{dx_1} = - \frac{f_1 \frac{\partial f_2}{\partial x_2} - f_2 \frac{\partial f_1}{\partial x_2}}{\underbrace{\frac{\partial f_1}{\partial x_1} \frac{\partial f_2}{\partial x_2} - \frac{\partial f_1}{\partial x_2} \frac{\partial f_2}{\partial x_1}}_{\text{Determinant of the Jacobian}}}$$

$$dx_2 = x_2^{i+1} - x_2^i = - \frac{f_2 \frac{\partial f_1}{\partial x_1} - f_1 \frac{\partial f_2}{\partial x_1}}{\underbrace{\frac{\partial f_1}{\partial x_1} \frac{\partial f_2}{\partial x_2} - \frac{\partial f_1}{\partial x_2} \frac{\partial f_2}{\partial x_1}}_{\text{determinant of } J}}$$

in more general form (Jacobian form)

$$J = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \frac{\partial f_n}{\partial x_2} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix}$$

The array equation is then

$$\begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \dots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \dots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \frac{\partial f_n}{\partial x_2} & \dots & \frac{\partial f_n}{\partial x_n} \end{bmatrix} \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \\ \vdots \\ \Delta x_n \end{bmatrix} = - \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}$$

$$\{\bar{x}_i\}^T = [x_1^i, x_2^i, \dots, x_n^i]$$

$$\{\bar{x}_{i+1}\}^T = [x_1^{i+1}, x_2^{i+1}, \dots, x_n^{i+1}]$$

$$\{\bar{f}_i\}^T = [f_1^i, f_2^i, \dots, f_n^i]$$

$$[J] \{\bar{x}_{i+1}\} = -\{\bar{f}_i\} + [J] \{\bar{x}_i\}$$

This equation can be solved using technique such as Gauss Elimination.

$$\begin{array}{l|l} J_{ij} \Delta x_j = -f_i & 1. \text{ guess } x_i \\ \Delta x_j = -J_{ij}^{-1} \cdot f_i & 2. \text{ find } f(x) \text{ and } f'(x) \\ & 3. \text{ calculate } \Delta x = -\frac{f(x)}{f'(x)} \\ x^{n+1} = x^n + \Delta x & 4. \text{ update } x^{\text{new}} = x^{\text{old}} + \Delta x \\ & 5. \text{ go to 2 if necessary} \end{array}$$

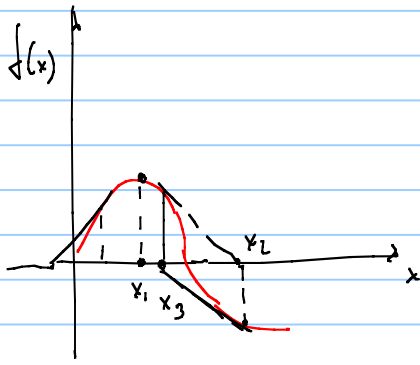
Another approach to solution of
a set of NLE

1. Formulate the non-linear system
as a single function

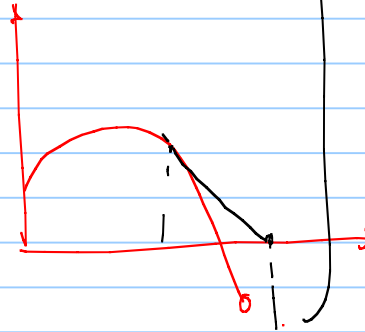
$$F(x) = \sum_{i=1}^n [w_i f_i(x_1, x_2, \dots, x_n)]^2$$

The value of $\bar{x}$ that minimize the
function represent the solution
of the non-linear system.

This formulation is a class of
problem call non-linear regression



$$|x_{i+1} - x_i| \leq \text{TOL}$$

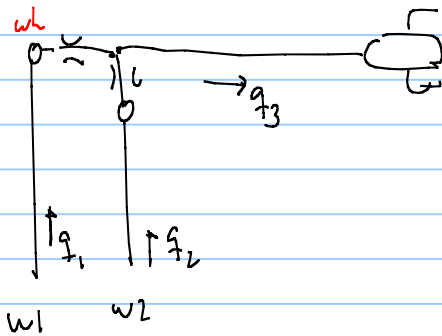


undefined function

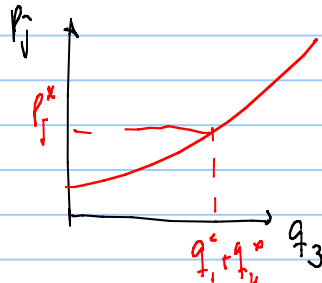
We have to make our equations "bulletproof" $\rightarrow$ avoid crashing of the solving algorithm

$\hookrightarrow$ useful for using commercial software !

// wells close to the junction $\rightarrow$ flowline can be neglected



e.g. with production rates from the reservoir engineer obtained to $\uparrow$ RF $\left\{ \begin{matrix} q_1^* \\ q_2^* \end{matrix} \right.$



- Use $q_1^* \leadsto P_{wh1}^*$
- use $q_2^* \leadsto P_{wh2}^*$
- use $q_1^* + q_2^* \leadsto P_j^*$

$$\Delta p_{choke1} = P_{wh1}^* - P_j^*$$

$$\Delta p_{choke2} = P_{wh2}^* - P_j^*$$

if the rates are feasible
the $\Delta p_{choke1} \geq 0$
 $\Delta p_{choke2} \geq 0$

• Calculate choke Δp

