



Rock physics and geomechanics of fluid-induced seismicity

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PHASE research project



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PHASE Research Project

Physics and Application of Seismic Emission

What is PHASE about?

The goals of the PHASE project are to improve the understanding of the physics of fluid induced microseismicity, to establish physical fundamentals for microseismic monitoring and to further develop the seismicity based reservoir characterization approach.

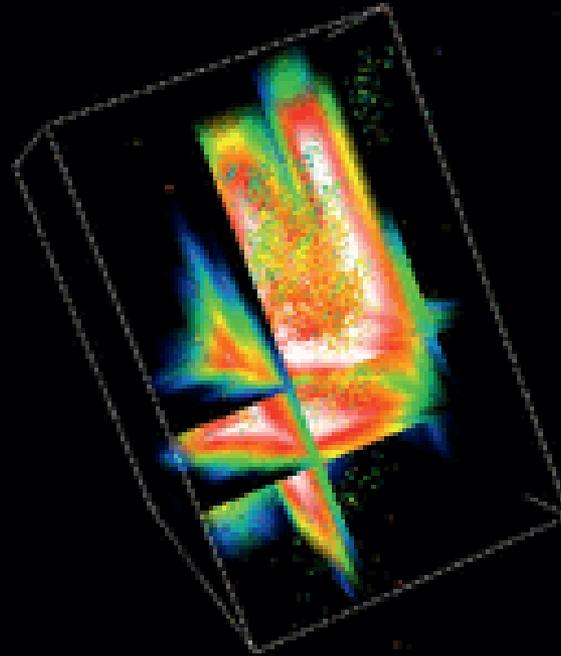
Read more on our [microseismicity page](#).

Research Directions of the PHASE Project

- Triggering mechanisms of induced seismicity
- Modelling of induced seismicity
- Imaging of microseismicity
- Interpretation and visualization of microseismic data combined with 3D reflection seismic images
- Seismicity-based methods for estimating hydraulic properties of rocks
- Estimating seismic criticality of rocks
- Physics and monitoring of hydraulic fracturing
- Physics and monitoring of poroelastic stress relaxation
- Seismicity-based estimation of stress and pore pressure
- Stress and pore pressure dependencies of physical properties of rocks

SERGE A. SHAPIRO

Fluid-Induced Seismicity



2015, Cambridge Univ. Press, 289pp.

www.cambridge.org/9780521884570

Outline

- Elasticity and seismic waves
- Porodynamics
- Earthquakes and faulting
- Induced seismicity in reservoirs:
 - linear pressure diffusion
 - classical hydraulic fracturing
 - non-linear pressure diffusion
 - induced seismic hazard

Porodynamics

There are 3 wave modes in poroelastic media:

one S-wave and two P-waves:

a fast P-wave and a slow P-wave

Properties of the slow P-wave

⇒ The solid and fluid movement are out of phase!

⇒ Slow wave is a diffusion-type wave:

For low frequencies it reduces to a diffusion process corresponding to the pore pressure relaxation

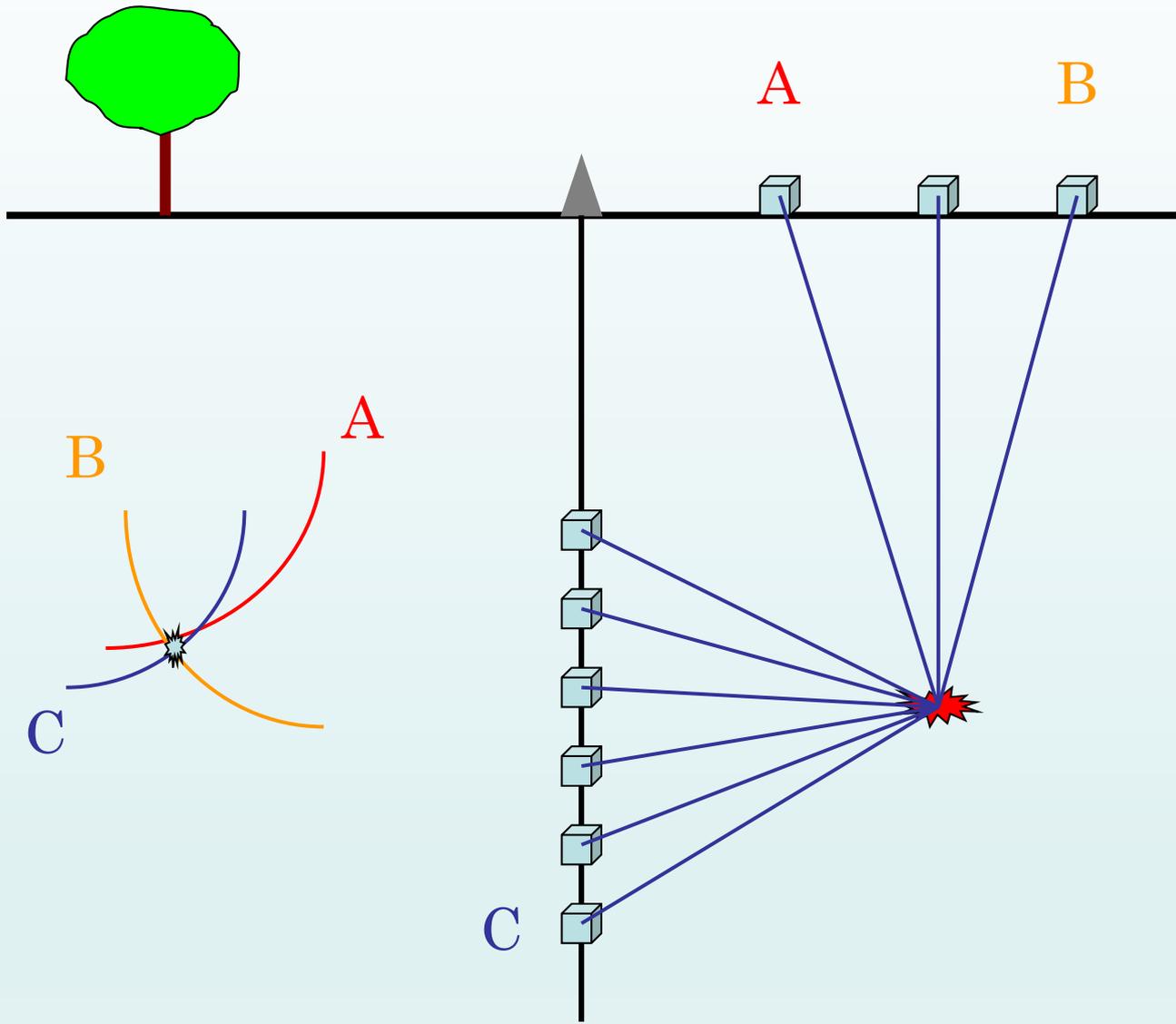
Coefficient of hydraulic diffusivity:

$$D = \frac{k}{\eta} M \frac{P_{\text{dry}}}{P_{\text{sat}}}$$

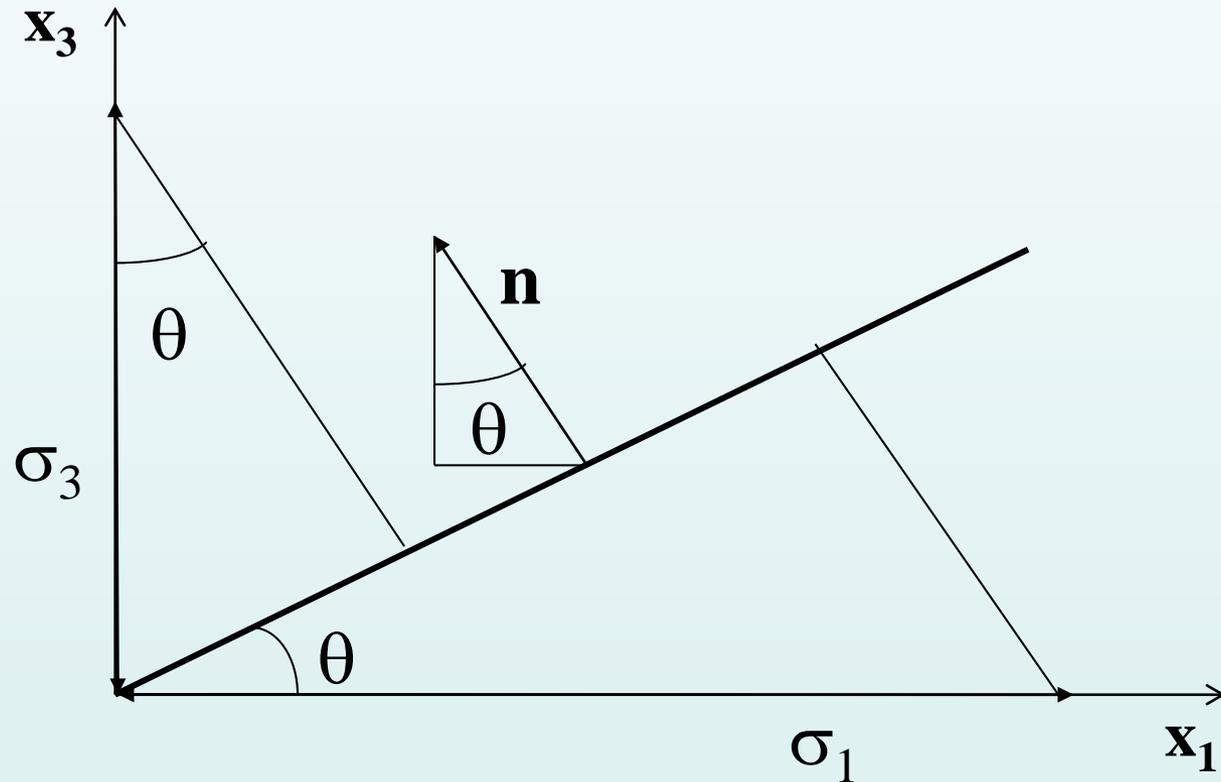
Summary 1.

- Elastic waves: P and S
- Slow wave: diffusion
- Global flow, squirt, mesoscopic flow
- Flow-related seismic wave attenuation
- Reservoir properties: permeability, porosity, fluid viscosity, fluid elasticity, rock elasticity

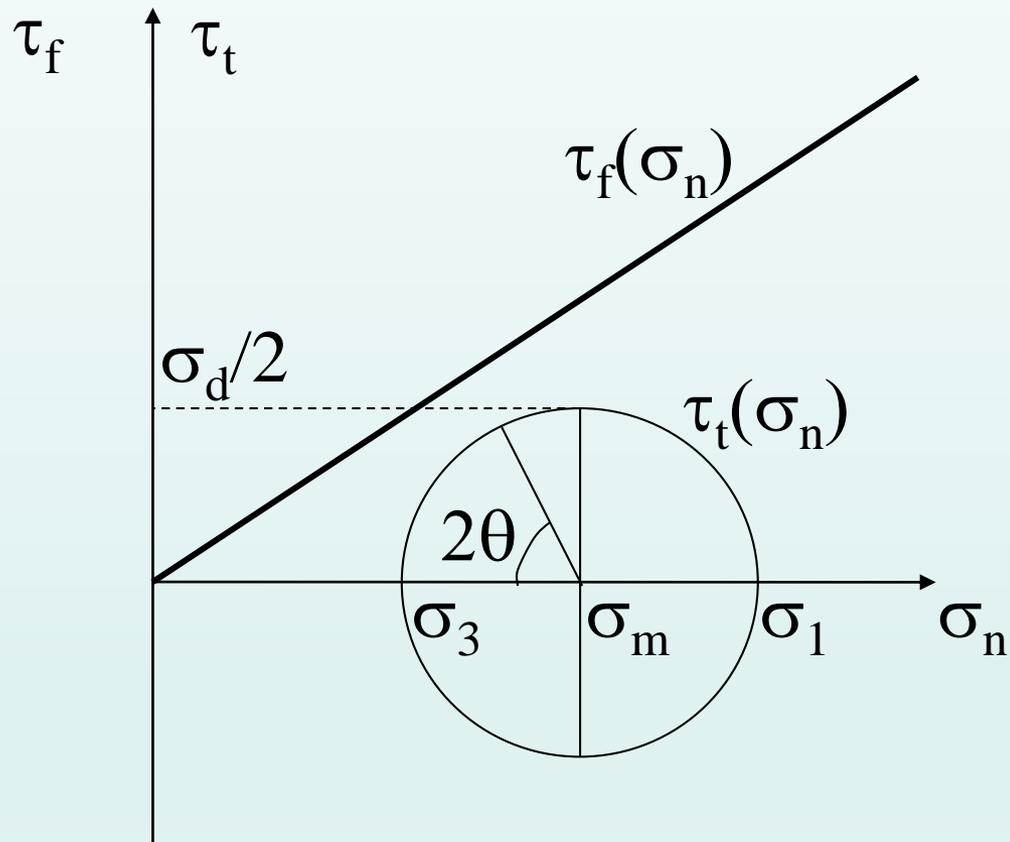
Earthquakes and faulting



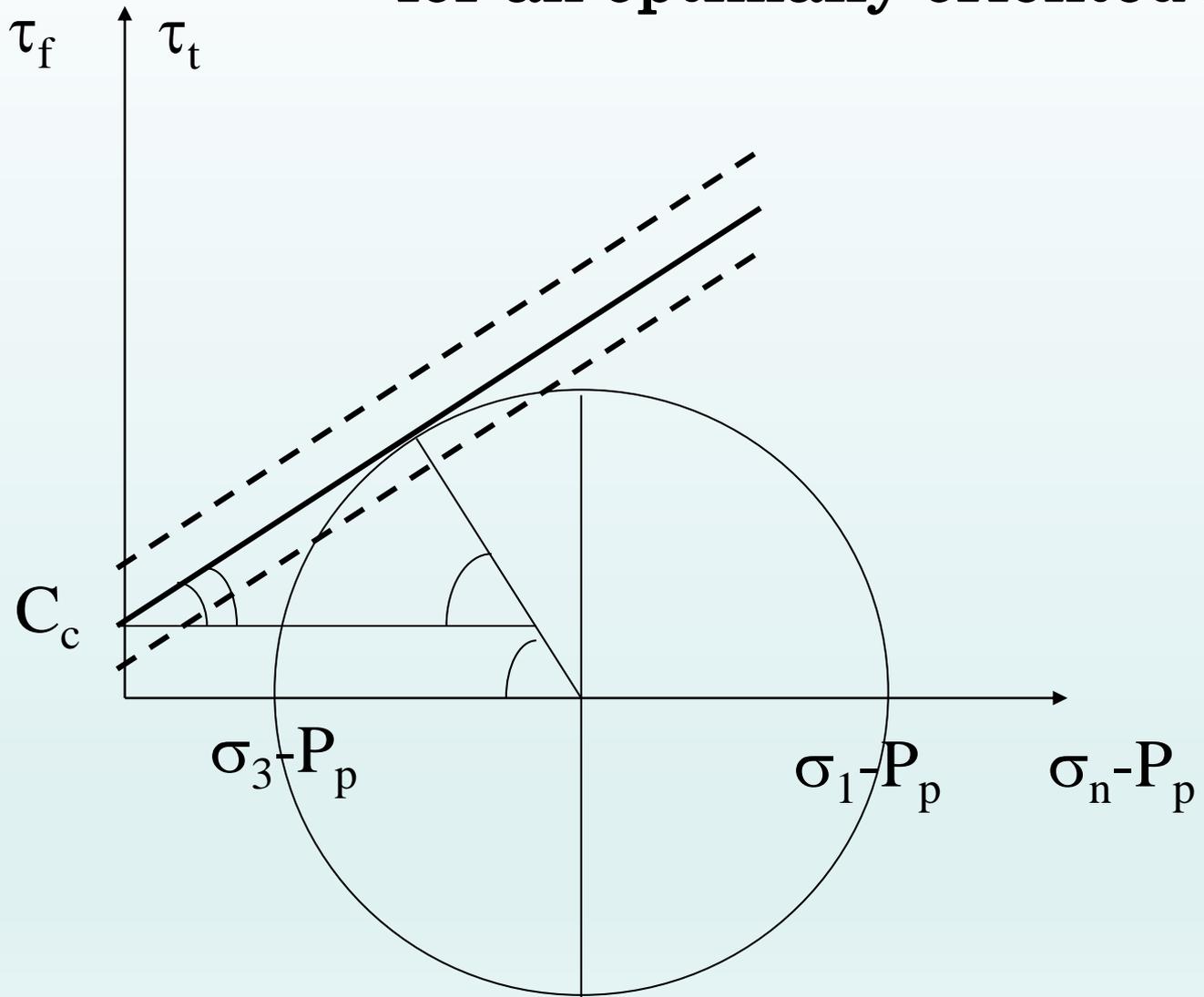
A fault normal to the plane of maximum and minimum stresses



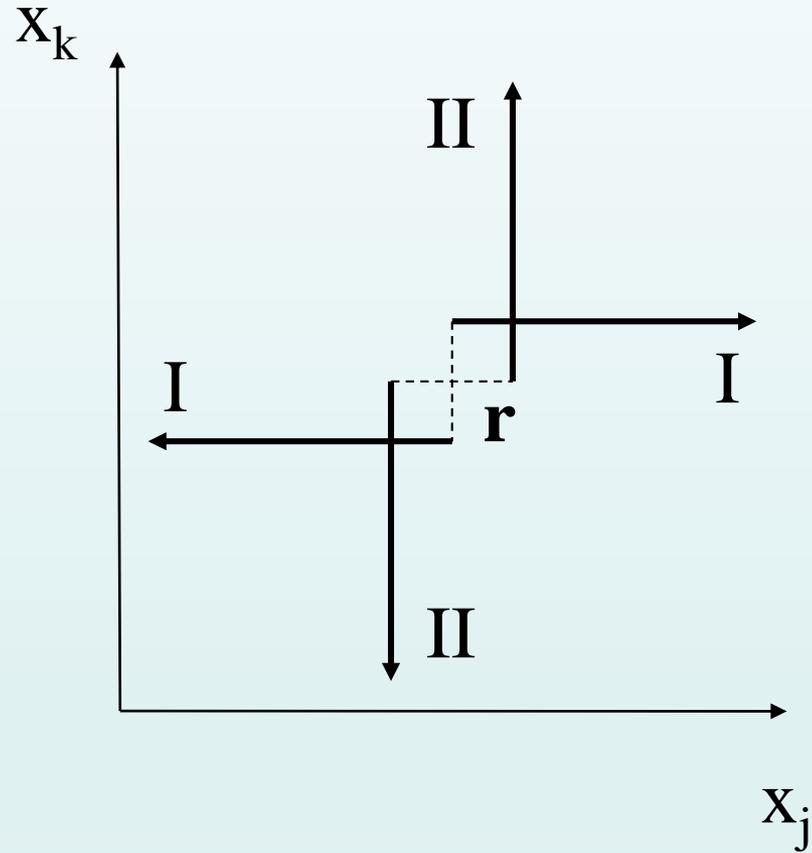
Friction force and shear stresses on a fault



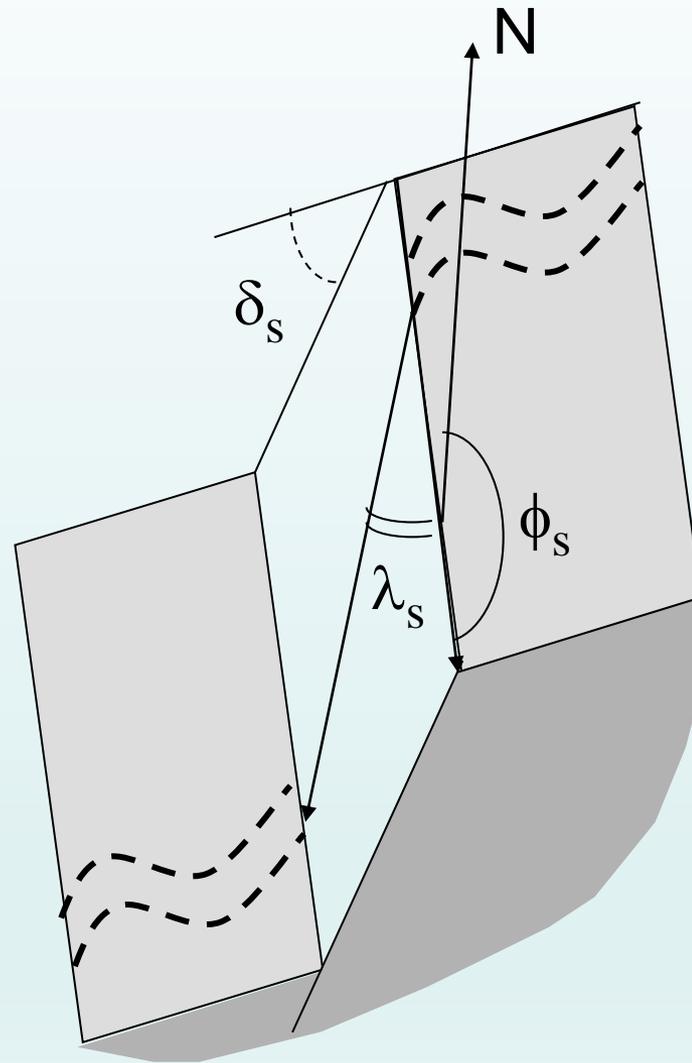
Shear stress and friction force for an optimally oriented fault



Double couple of forces



Parametrization of earthquake faults



Seismic moment and moment magnitude

Seismic Moment $M_0 = \mu * \text{Slip} * \text{Rupture Area}$

Moment Magnitude $M_w = 2 * (\log_{10} M_0 - 9.1) / 3$

Fault Length [m] is approx. $10^{**}(M_w/2 + 1)$

Stress drop of approx. 1 MPa is assumed.

Summary 2.

- Earthquake detection
- Earthquake location
- Earthquake mechanisms
- Earthquake magnitudes

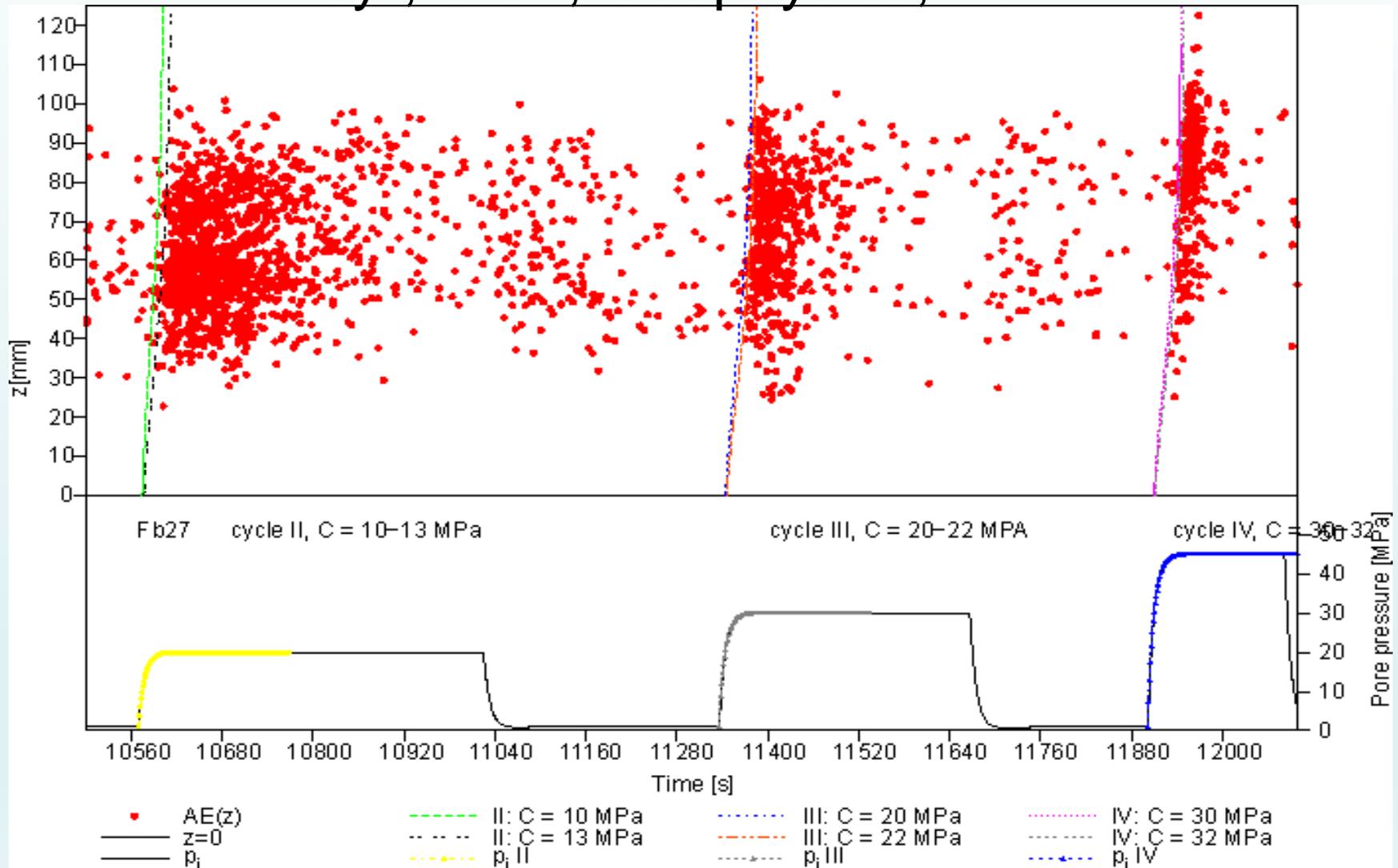
Types of fluid-induced seismicity

Two limiting cases of fluid-induced seismicity

- Diffusion-controlled triggering:
Injections in geothermic reservoirs.
- Volume-creation-controlled triggering:
Hydraulic fracturing of gas reservoirs.

Linear pore pressure diffusion and triggering fronts

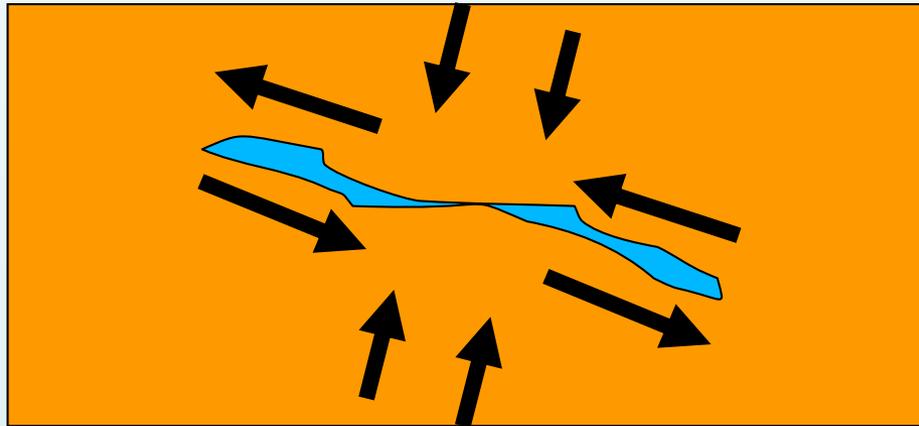
Fluid injection into a saturated sample: Mayr, et al., Geophysics, 2011



Physical Concept

- At some locations the state of stress is close to a critical one:

➔ A criticality field, $C(x,y,z)$: strength of pre-existing cracks (e.g., critical pore pressure).



- Seismicity triggering process is a dynamic perturbation of the stress state:

➔ Pore-pressure diffusion. A field of the hydraulic diffusivity, $D(x,y,z)$.

Poroelastic coupling

Poromechanics [Biot, 1962]

$$\frac{B}{3} \cdot \frac{\partial \sigma_{kk}}{\partial t} + \frac{\partial p}{\partial t} = \frac{DSBK_{dr}}{\alpha} \cdot \nabla^2 p$$

Hydraulic diffusivity:

$$D = 10^{-4} - 10 \text{ m}^2/\text{s}$$

[*Wang* 2000, *Scholz* 2002]

Pore-Pressure Diffusion

Pressure
diffusion:

$$\frac{\partial p}{\partial t} = D \cdot \nabla^2 p$$

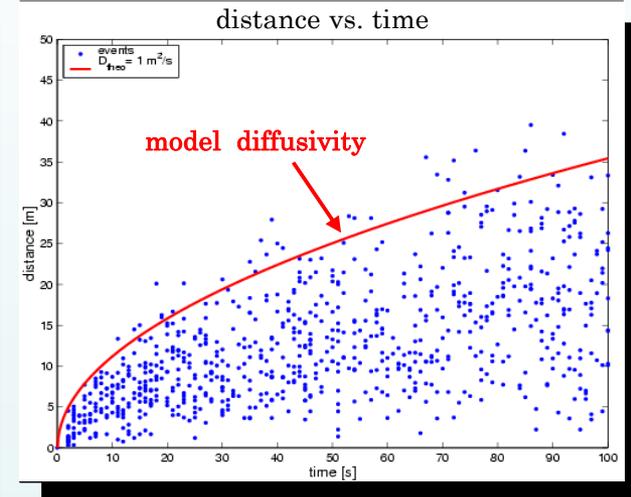
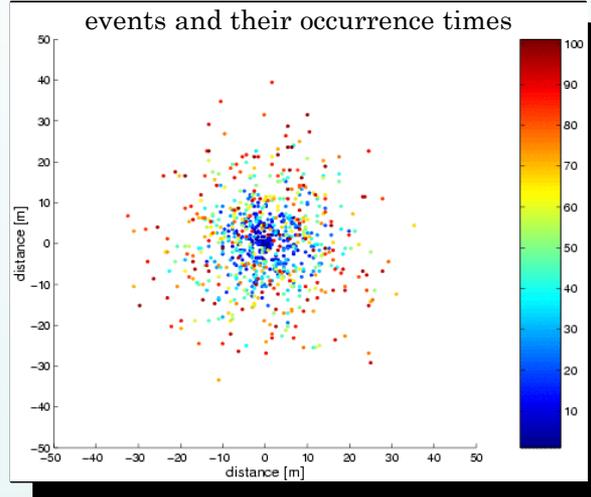
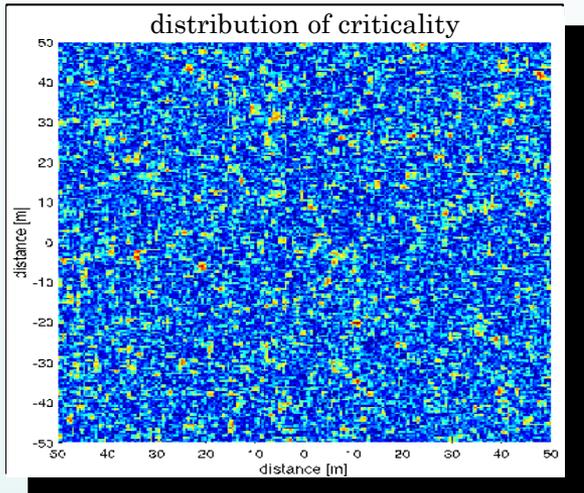
Hydraulic diffusivity:

$$D = k / (S \eta)$$

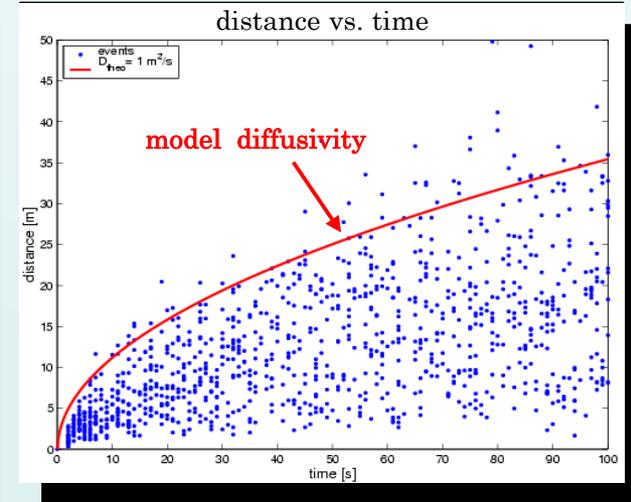
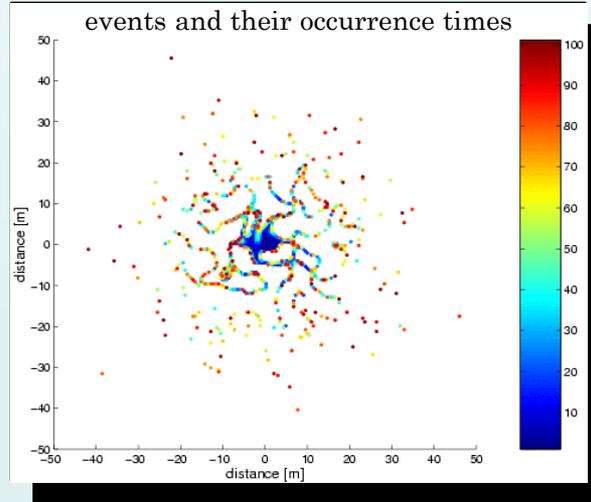
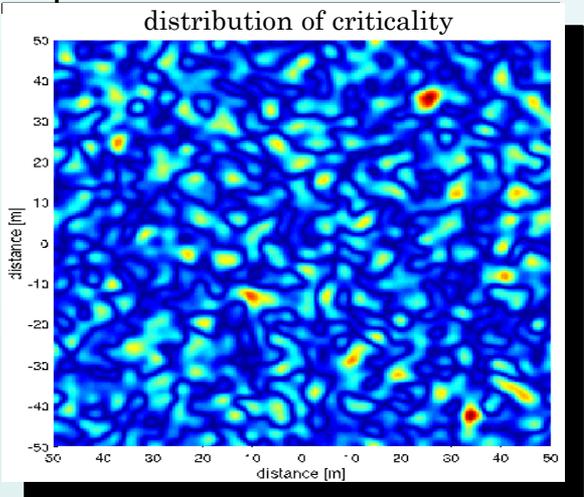
Triggering front:

$$r = \sqrt{4\pi Dt}$$

Numerical modelling of seismicity: linear diffusion



Exponential ACF



Gaussian ACF

Summary 3.

- Triggering of earthquakes
- Pore pressure diffusion
- Hydraulic diffusivity
- Triggering front
- Synthetic microseismic clouds
- Anisotropic diffusivity

Microseismicity after a termination of injection

$$p_a(r, t) = \frac{q}{4\pi D r} \cdot \left[\operatorname{erfc}\left(\frac{r}{\sqrt{4Dt}}\right) - \operatorname{erfc}\left(\frac{r}{\sqrt{4D(t-t_0)}}\right) \right]$$

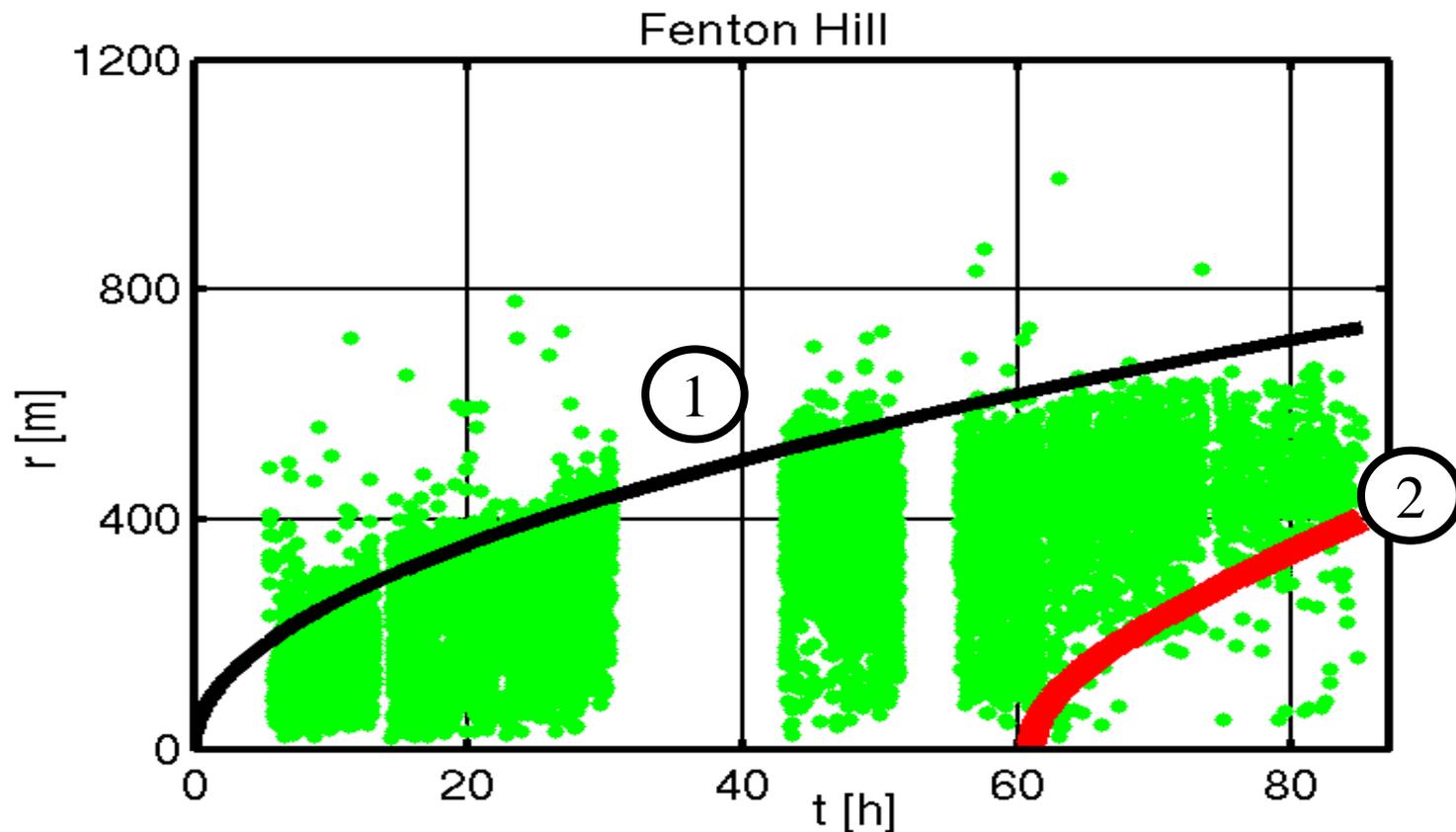
BACK FRONT

$$r = \sqrt{6 \cdot D \cdot t \cdot \left(\frac{t}{t_0} - 1\right) \cdot \ln\left(\frac{t}{t-t_0}\right)}$$

Triggering Front and Back Front: linear diffusion

$$r = \sqrt{4\pi Dt}$$

$$r_{bf} = \sqrt{6Dt(1-t/t_0)\ln(1-t_0/t)}$$

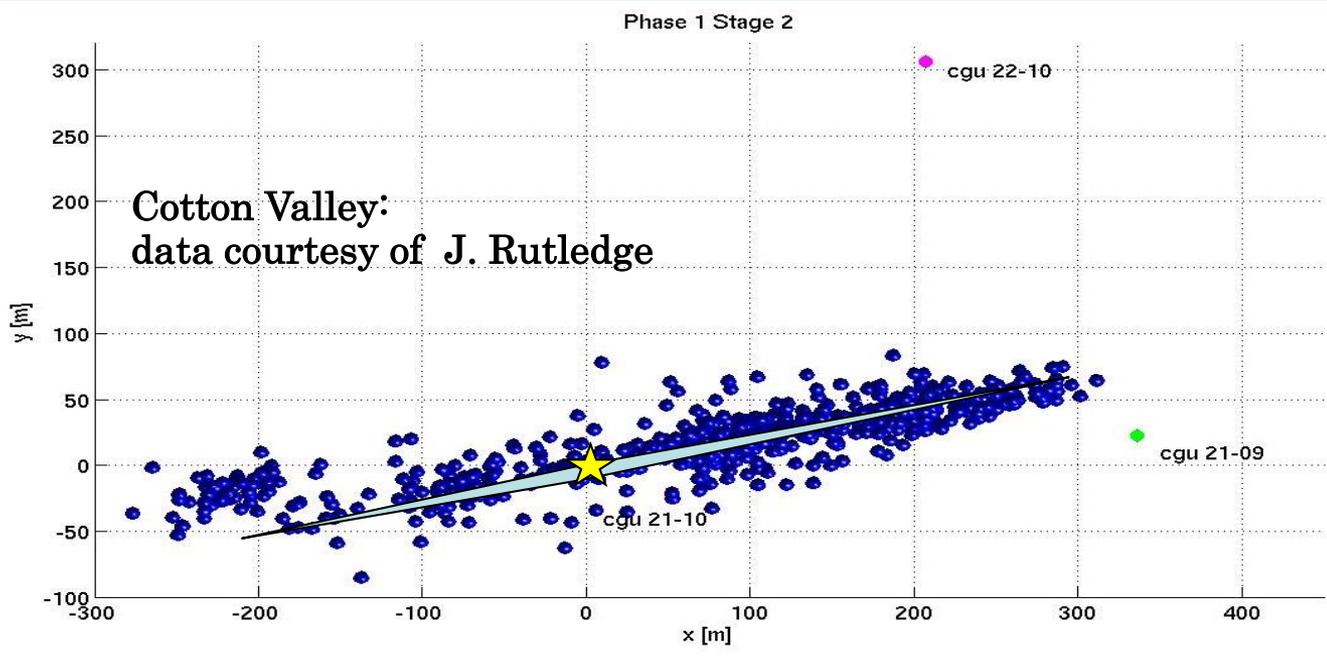
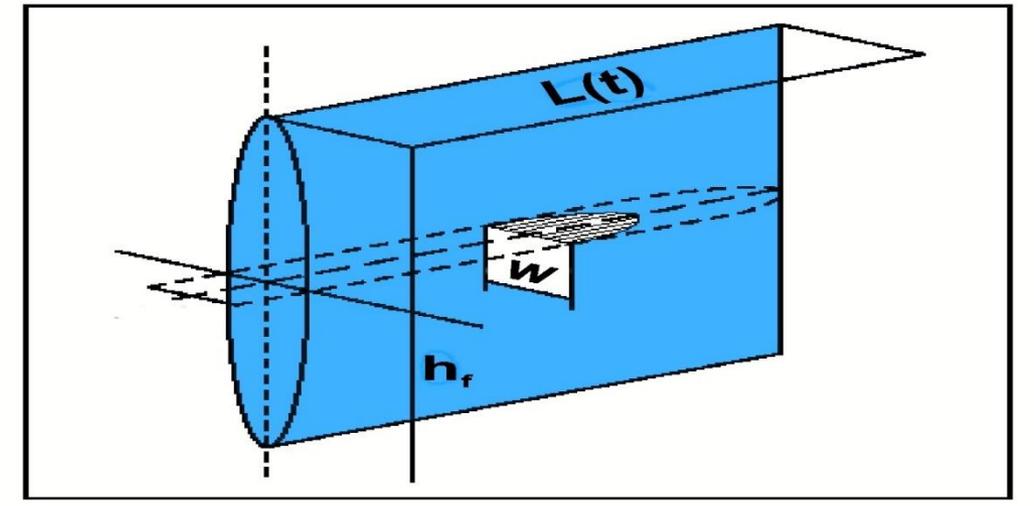


Summary 4.

- Back front of seismicity
- Event rate
- Spatial density of microseismic clouds
- Pore pressure diffusion explains spatio-temporal distributions of events
- It explains also statistics of events
- Characterization of hydraulic properties of rocks.
- Characterization of criticality (strength) of rocks.

Microseismicity by hydraulic fracturing

Perkins-Kern-Nordgren (PKN) Model of Hydraulic Fracture



Volume Balance Principle

Volume of injected fluid = fracture volume + lost fluid volume

$$Q_I t = 2 L G + 6 L h_f C_L t^{1/2}$$

t injection time,

Q_I average injection rate,

C_L fluid loss coefficient,

$G = w * h_f$ vertical cross section of the fracture.

Hydraulic Fracture Propagation

The half-length L of the fracture as a function of the injection time t :

$$L(t) = \frac{Q_I t}{S_L \sqrt{t} + G}$$

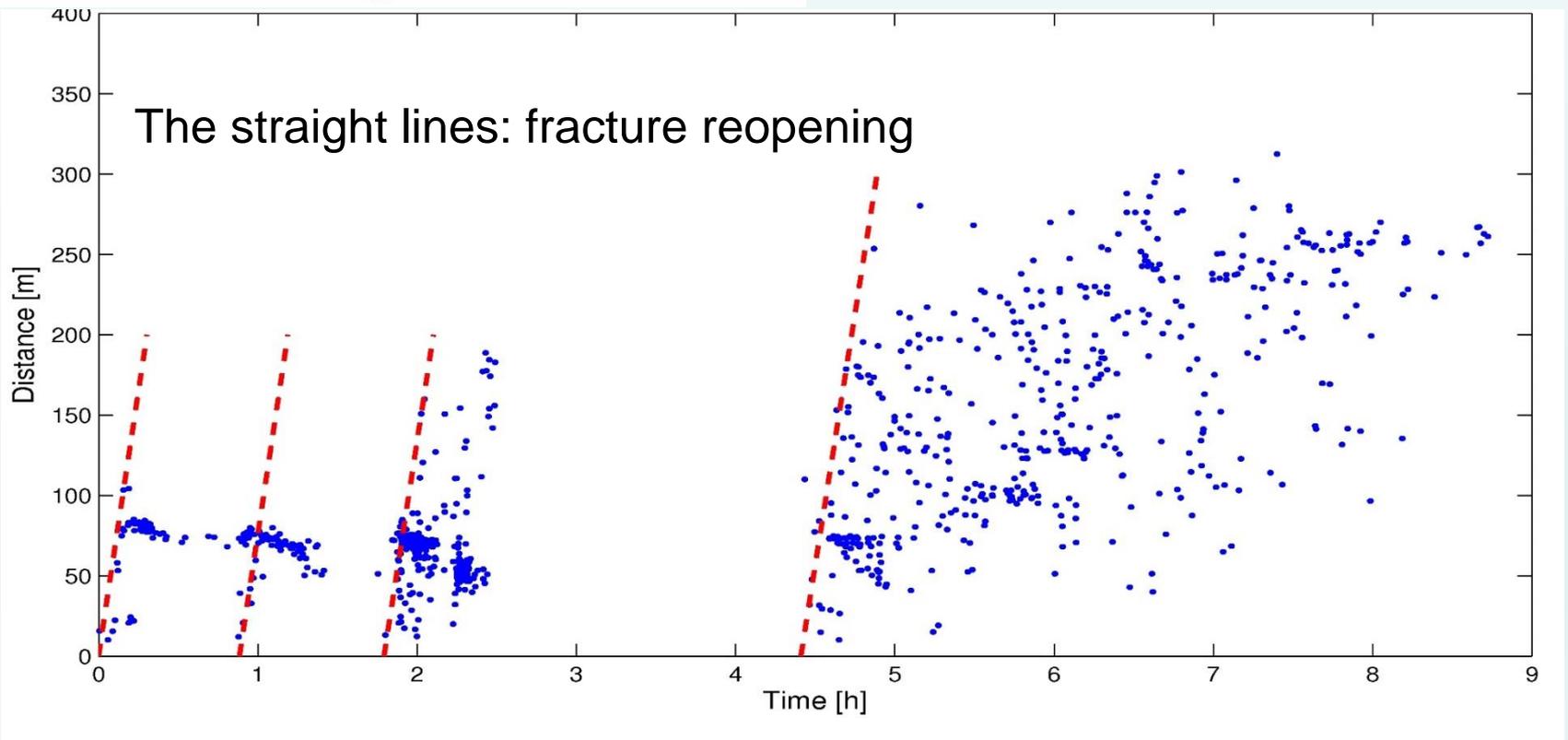
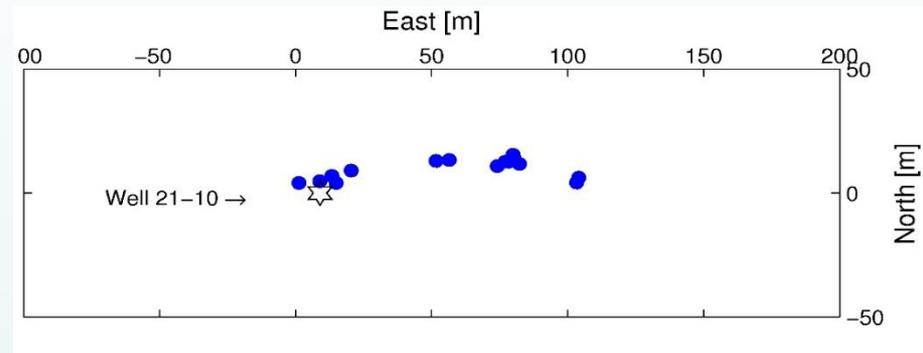
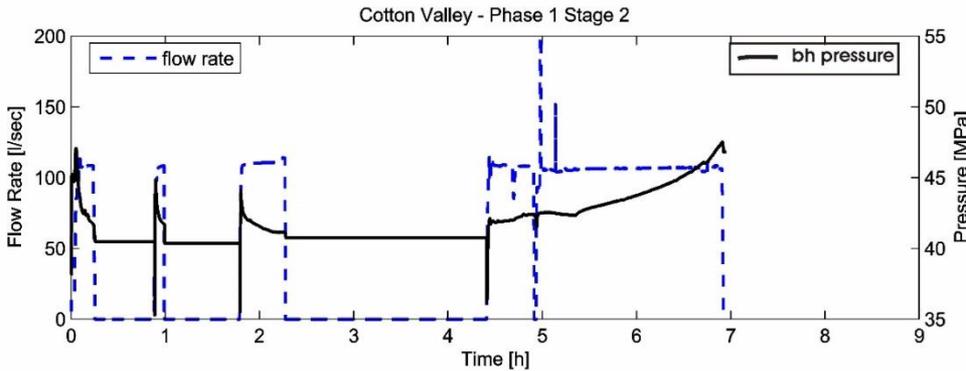
Q_I is the average injection rate,

S_L describes the fluid loss,

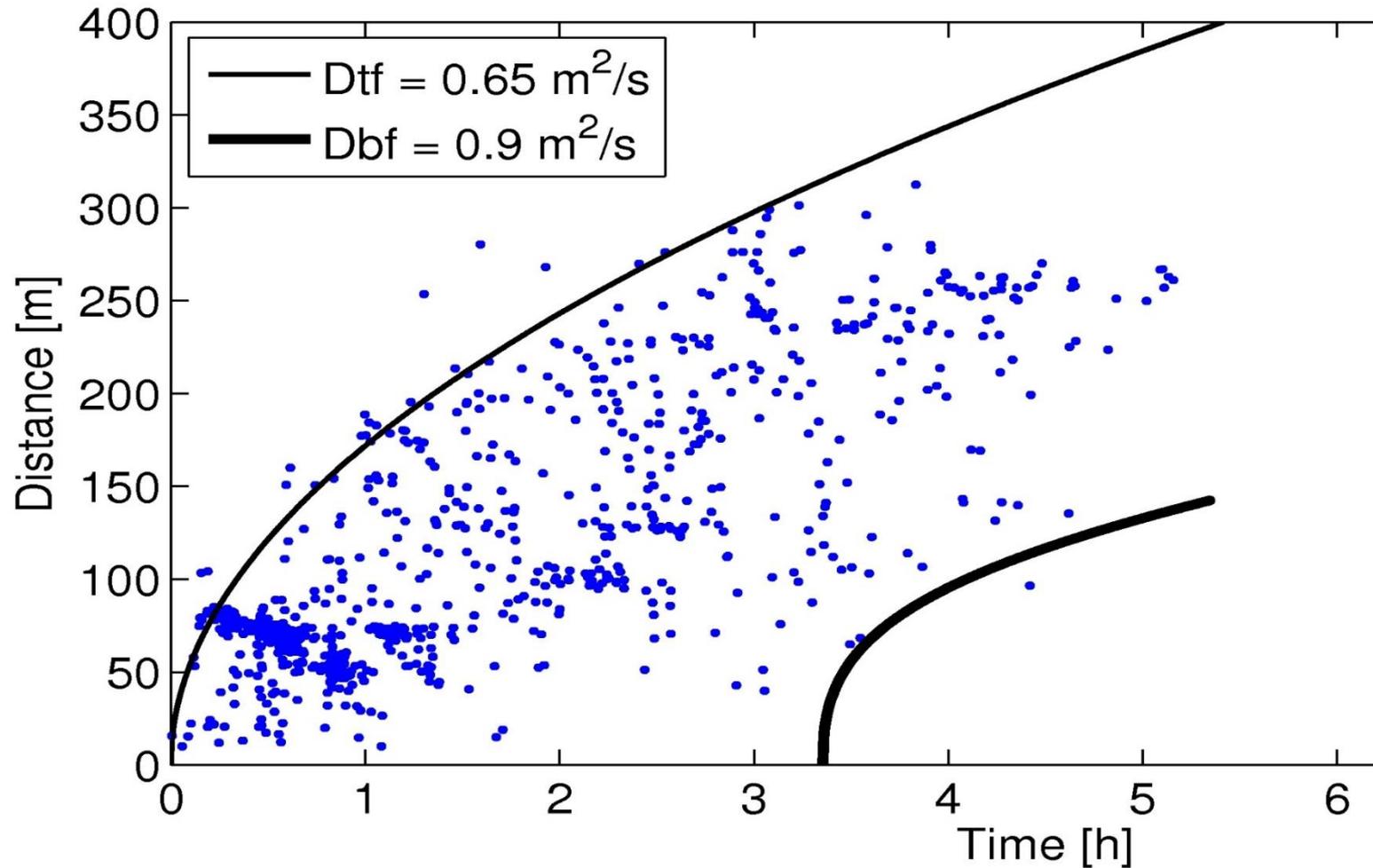
G represents the effective fracture volume contribution

Geometry- and Fluid-Loss- Controlled Fracture Growth

Microseismicity induced by hydraulic fracturing



Triggering Front and Back Front



Estimation of Fluid Loss and Permeability

Apparent hydraulic diffusivity characterizes fluid loss:

$$C_L = \frac{Q_I}{8h_f \sqrt{2\pi D_{tf}}}$$

Using fluid loss coefficient, porosity, compressibility and viscosity of the reservoir fluid we can estimate reservoir permeability:

$$C_L \approx \Delta p \sqrt{\frac{K\phi c_t}{\pi\eta}}$$

Summary 5.

- Spatio-temporal dynamics of microseismic clouds contributes to characterization of hydraulic fractures.
- r-t-plots show signatures of fracture volume growth, fracturing fluid loss, as well as diffusion of the injection pressure into rocks and inside the fracture.
- Diffusion controlled triggering: Kaiser effect is obeyed. Injections in geothermic reservoirs.
- New volume creation controlled triggering: Kaiser effect is violated. Hydraulic fracturing of gas reservoirs.

Non-Linear Diffusion and Triggering Front

Pressure
diffusion:

$$\frac{\partial p}{\partial t} = \nabla D \nabla p$$

Hydraulic diffusivity:

$$D \propto p^n$$

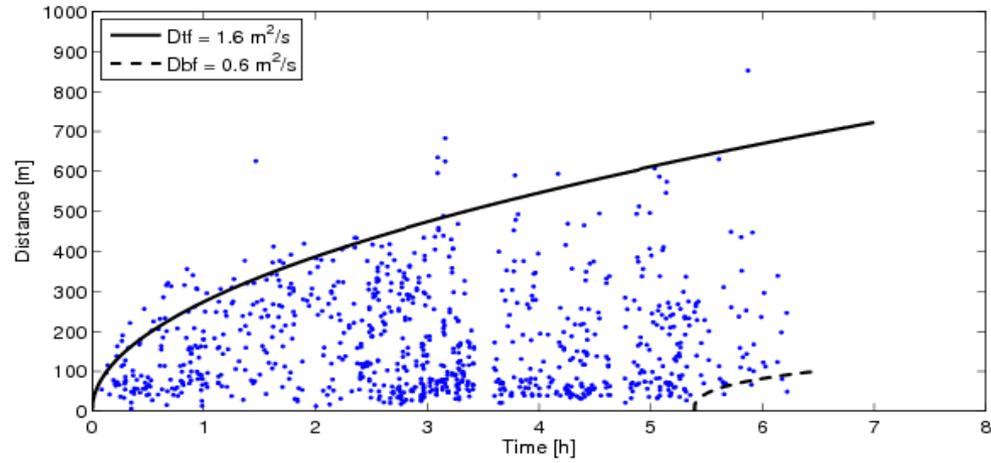
Triggering front:

$$r \propto \sqrt[3n+2]{D Q_I^n t^{n+1}}$$

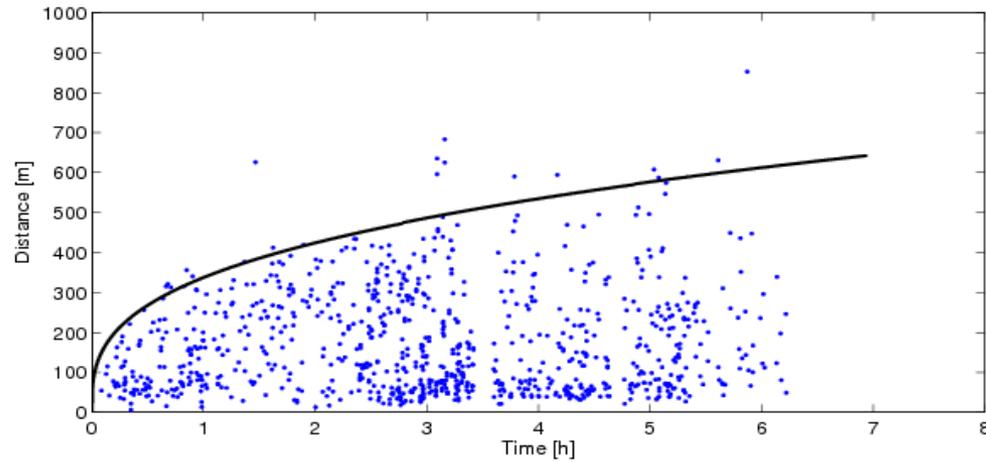
$$r = \sqrt{4 \pi D t}$$

$$r \propto \sqrt[3]{Q_I t}$$

$$r = At^{1/2}$$



$$r = At^{1/3}$$



Summary 6.

- A linear pore pressure relaxation and a hydraulic fracturing are end members of a set of non-linear diffusion phenomena responsible for seismicity triggering.
- A non-linear diffusion equation takes into account a strong enhancement of permeability. A linear pressure relaxation and hydraulic fracturing, can be obtained as limiting cases of such an equation.
- Triggering front of fluid induced seismicity can deviate from $t^{1/2}$ – behavior, in the case of a non-linear pore pressure diffusion.
- The Barnett Shale case study corresponds to a non-linear pressure diffusion with a very strong permeability enhancement. It is a 3-D opening of preexisting fractures embedded into impermeable compliant matrix. The triggering front shows a cubic-root parabolic behavior.

Magnitudes of seismicity

Magnitude distribution

Number of all events triggered till time t with magnitude larger than M

$$N_M(t) = N_{ev}(t) \times W(M)$$

The Gutenberg-Richter distribution:

$$\log W(M) = a - bM$$

$$\log N_M = \text{const} + \log Q_c(t) - bM$$

Seismogenic index

$$\log N_M(t) = \Sigma + \log Q_c(t) - bM$$

Seismogenic index:

$$\Sigma = a - \log SF_t$$

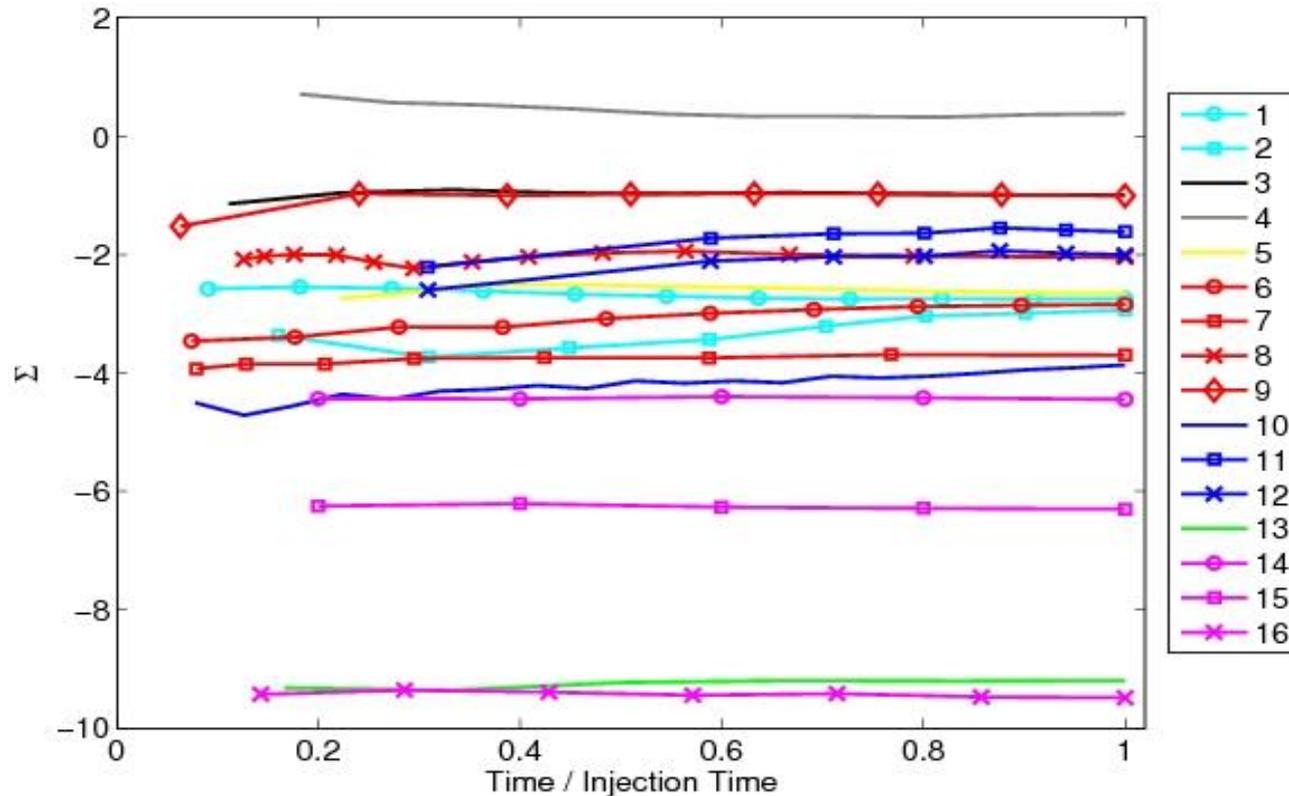
Tectonic potential:

$$F_t = C_{\max} / N$$

The classical

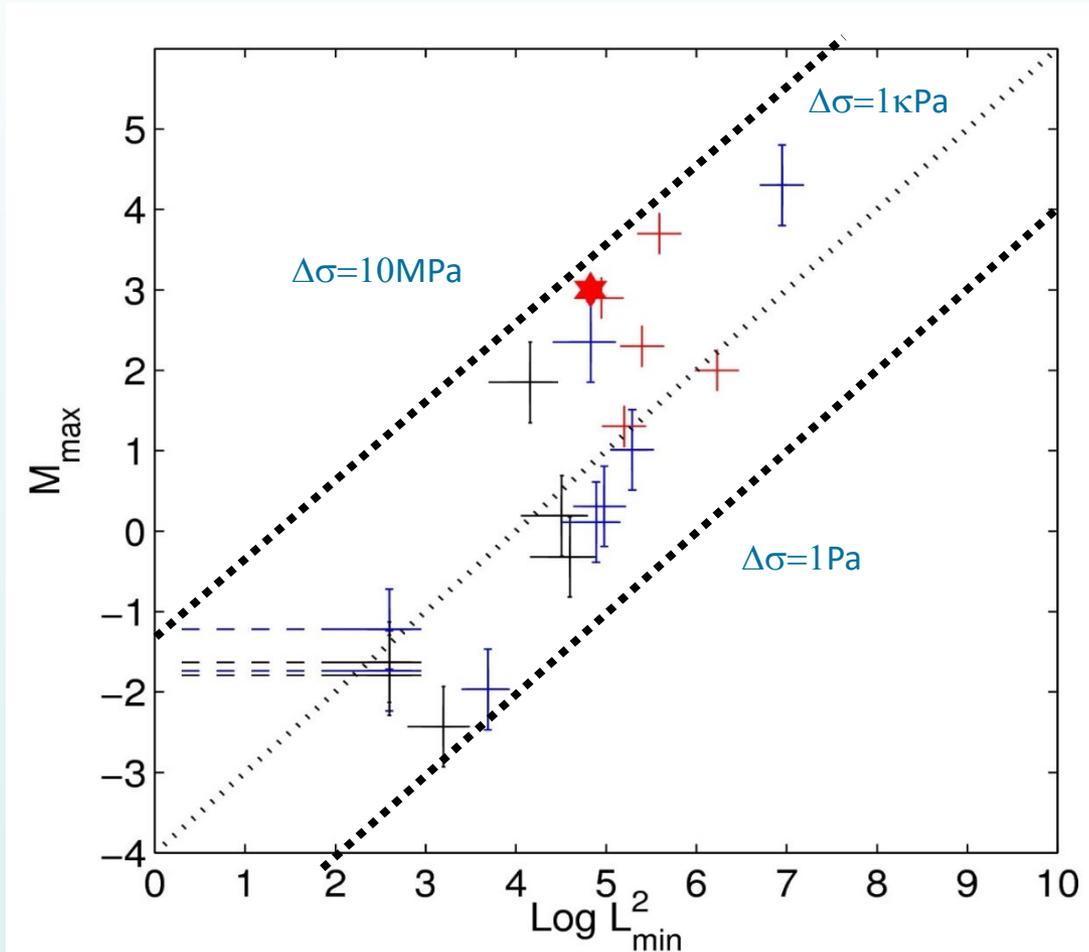
Gutenberg-Richter law: $\log N_M(t) = a(t) - bM$

Seismogenic index, Σ



1-2: Ogachi 1991/93, 3: Cooper Basin 2003, 4: Basel 2006, 5: Paradox Valley, 6-9: Soultz 1996/95/93/00. 10-12: KTB 2005/94. 13: Barnett Shale, 14-16: Cotton Valley stages A, B, C.

Maximum magnitude vs minimum axis



$$\text{MAX}\{M_{\max}\} \approx 2 \log L_{\min} - 1$$

Summary 7.

- Magnitude probability increases like the injected volume.
- Magnitude distribution are inherited from the statistics of preexisting fracture systems (Gutenberg-Richter law).
- Seismogenic index quantifies a seismic activity by fluid injections.
- The largest seismogenic index was observed at the Basel EGS. The smallest - at hydrocarbon reservoirs.
- Hydrocarbon reservoirs require more sensitive monitoring systems than geothermal reservoirs.
- Geometry of a stimulated volume influences statistics of induced seismicity

Selected references

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