

# Use of wavefront attributes for tomographic model building with active and passive seismic data

D. Gajewski, A. Bauer, B. Schwarz and J. Walda

Institute of Geophysics, University of Hamburg  
Wave Inversion Technology (WIT)



- ZO CRS stack is a powerful tool for data analysis

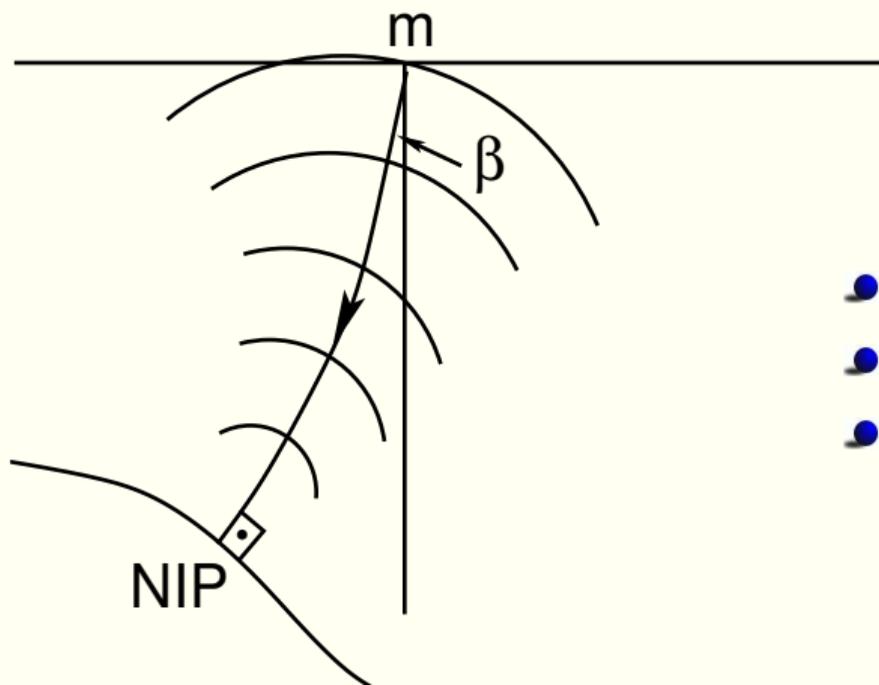


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# Wavefront Tomography



For a consistent velocity model NIP-waves focus at the NIP for zero traveltimes when propagated back to the subsurface (Duveneck, 2004).



- picking in stacked data
- ray tracing
- model update

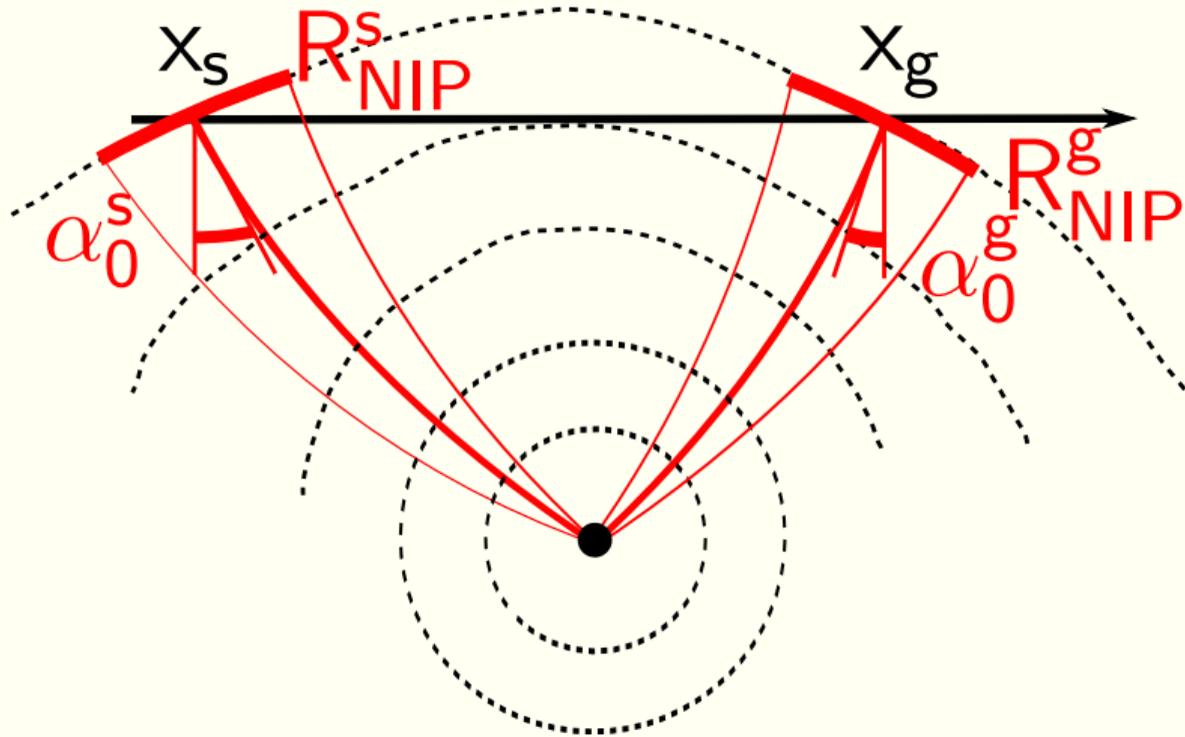


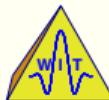
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# Decomposition Principle





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- Diffractions and passive events are strongly related



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  - Diffractions and passive events are strongly related
- Use diffracted and passive events for velocity inversion



- Wavefront attribute estimation

# Outline



- Wavefront attribute estimation
- Wavefront tomography



- Wavefront attribute estimation
- Wavefront tomography
- Simple synthetic data examples
  - Diffraction
  - Passive seismics



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- Simple synthetic data examples
  - Diffraction
  - Passive seismics
- Field data example



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  - Passive seismics
- Field data example
- Conclusions and outlook



- Active seismics: (nonhyperbolic) ZO CRS stack

$$t = t_s(t_0, \alpha, R_{NIP}, R_N) + t_g(t_0, \alpha, R_{NIP}, R_N)$$



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- Diffractions: Only one wavefront ( $R_N = R_{NIP} \stackrel{!}{=} R$ )

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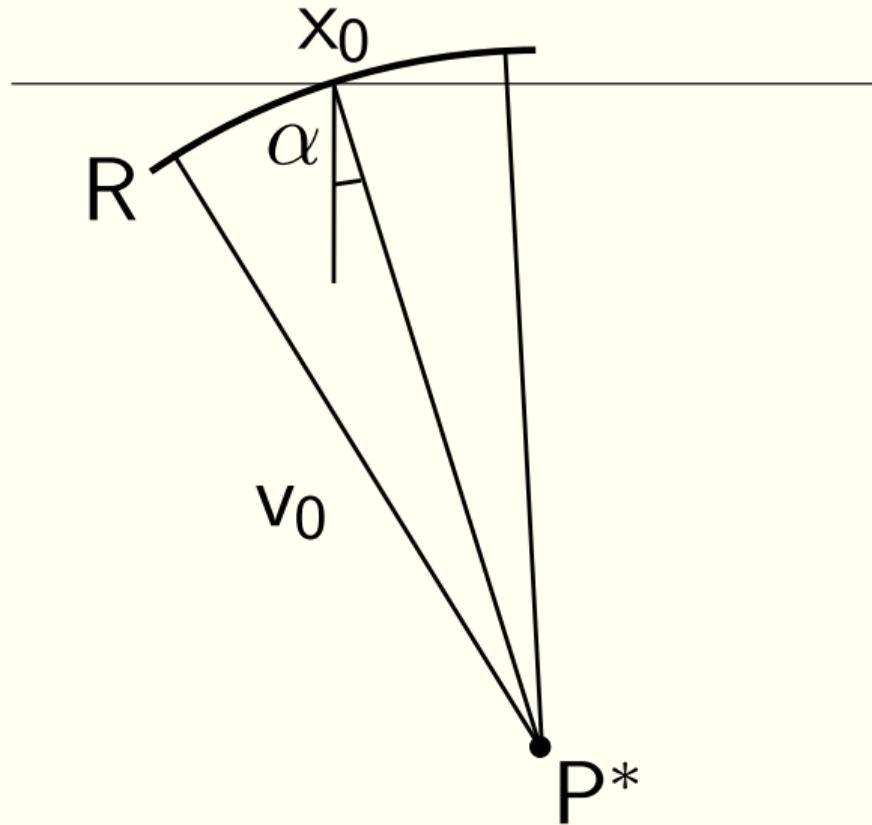
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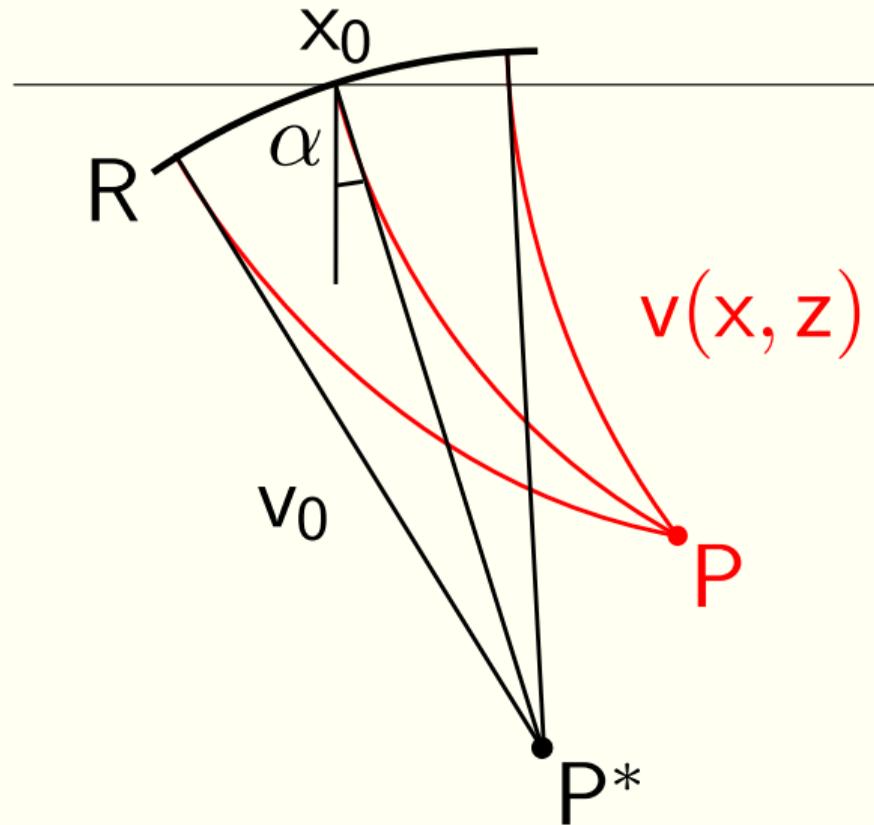
- Passive seismics: One additional attribute ( $t_s$ )

$$t = t_s + t_g(t_0, \alpha, R)$$

# Wavefront tomography: Image space



# Wavefront tomography: Model space



# Wavefront tomography: Inverse problem



- Input:  $n$  picked data points  $(x_0, t_0, \alpha, R)_i$

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$$\Psi(\mathbf{m}) = \frac{1}{2} \|\mathbf{d} - \mathbf{f}(\mathbf{m})\|_D^2 + \Lambda[\partial_{xx}v(x, z), \partial_{zz}v(x, z)]$$

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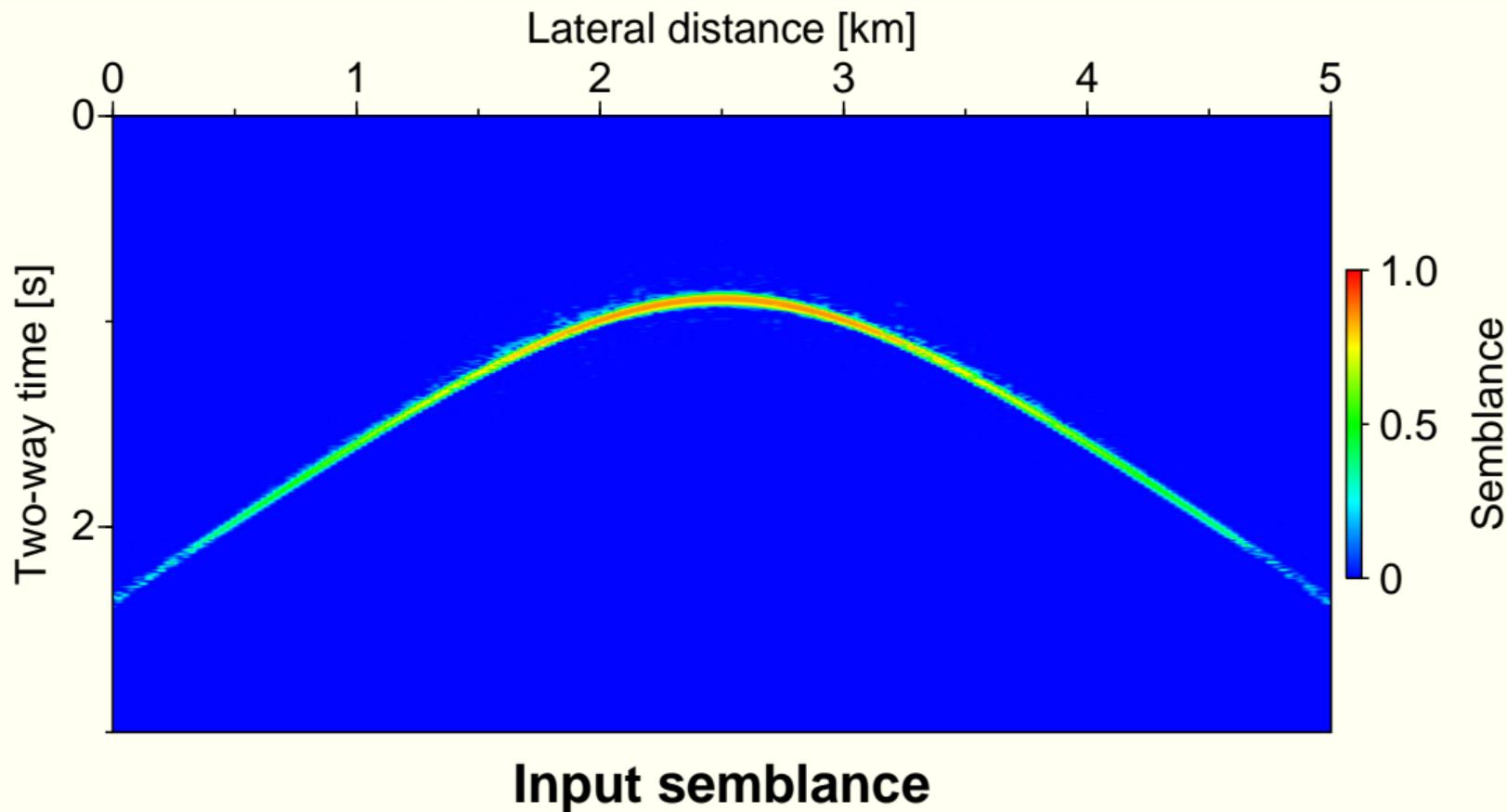


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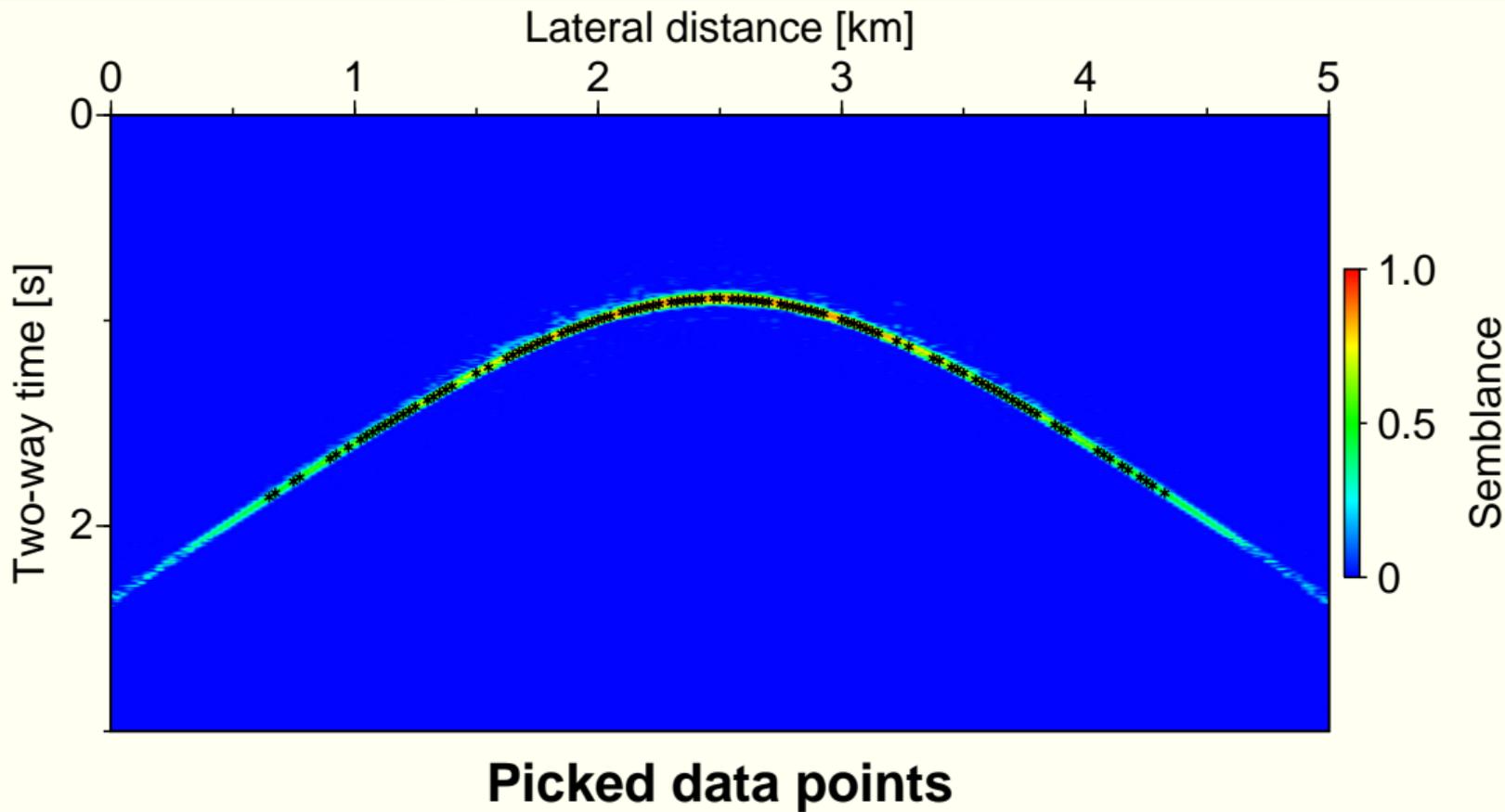
$$\Psi(\mathbf{m}) = \frac{1}{2} \|\mathbf{d} - \mathbf{f}(\mathbf{m})\|_D^2 + \Lambda[\partial_{xx}v(x, z), \partial_{zz}v(x, z)]$$

- Output: smooth velocity model  $v(x, z)$

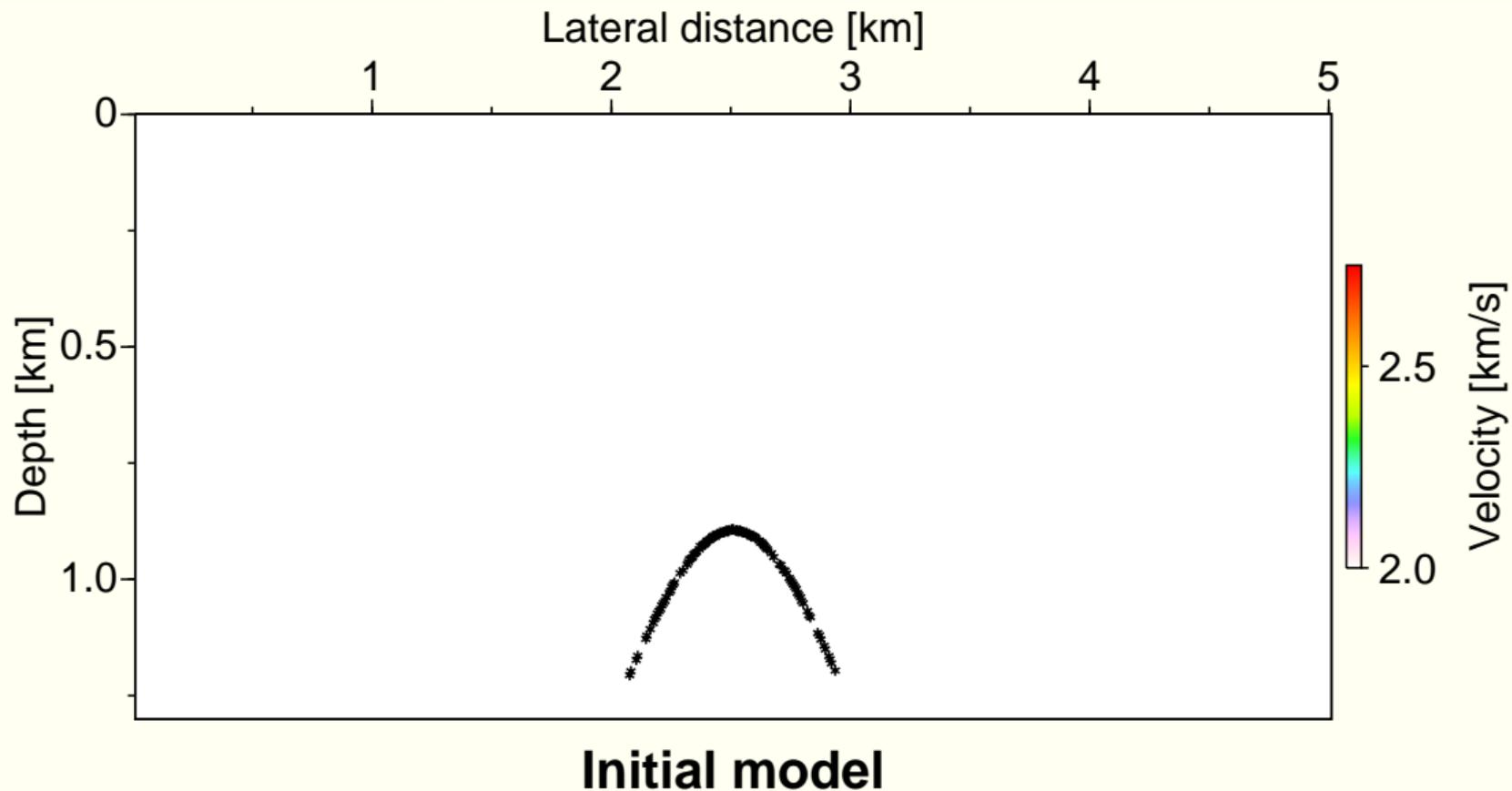
# Diffraction example: Input semblance



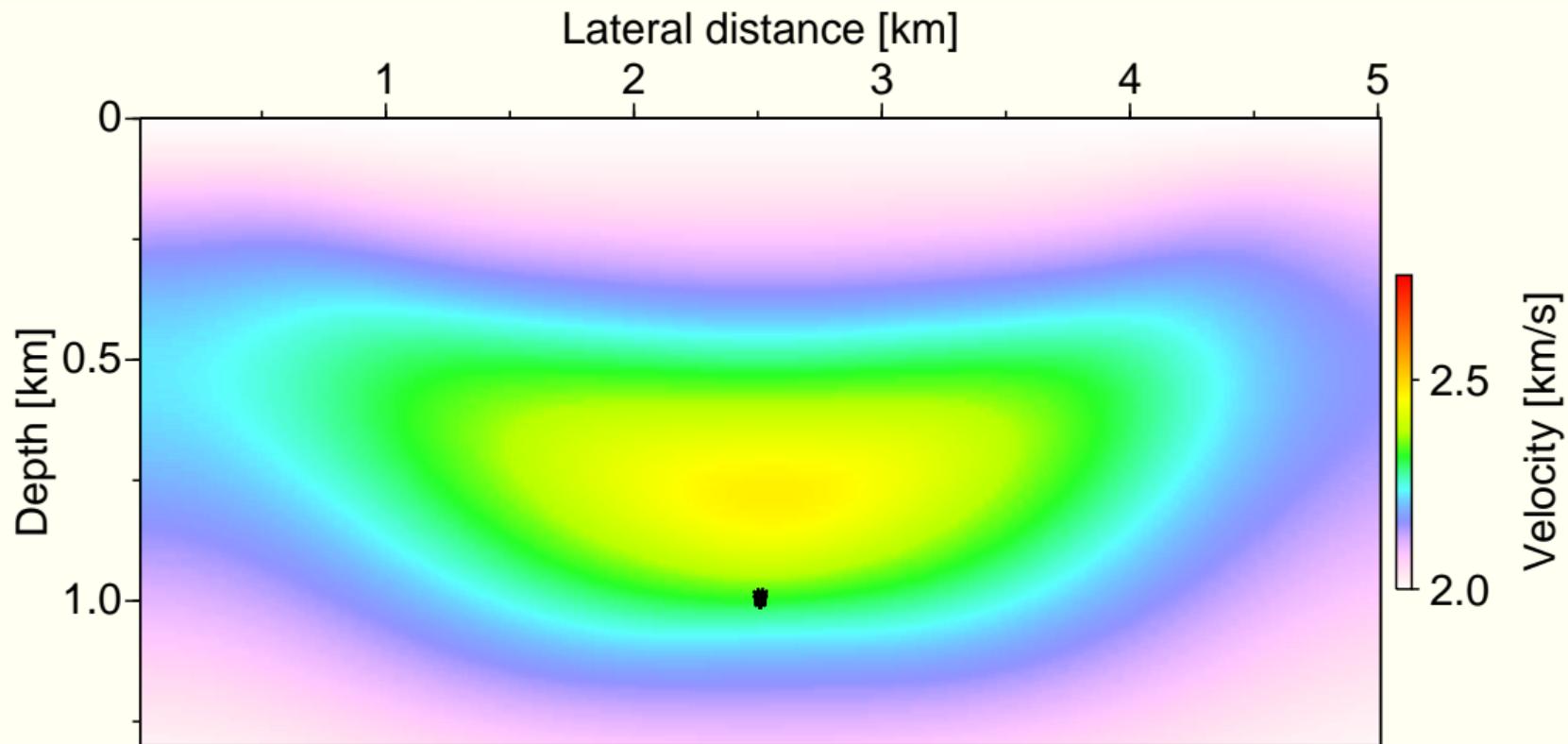
# Diffraction example: Picked data points



# Diffraction example: Initial model

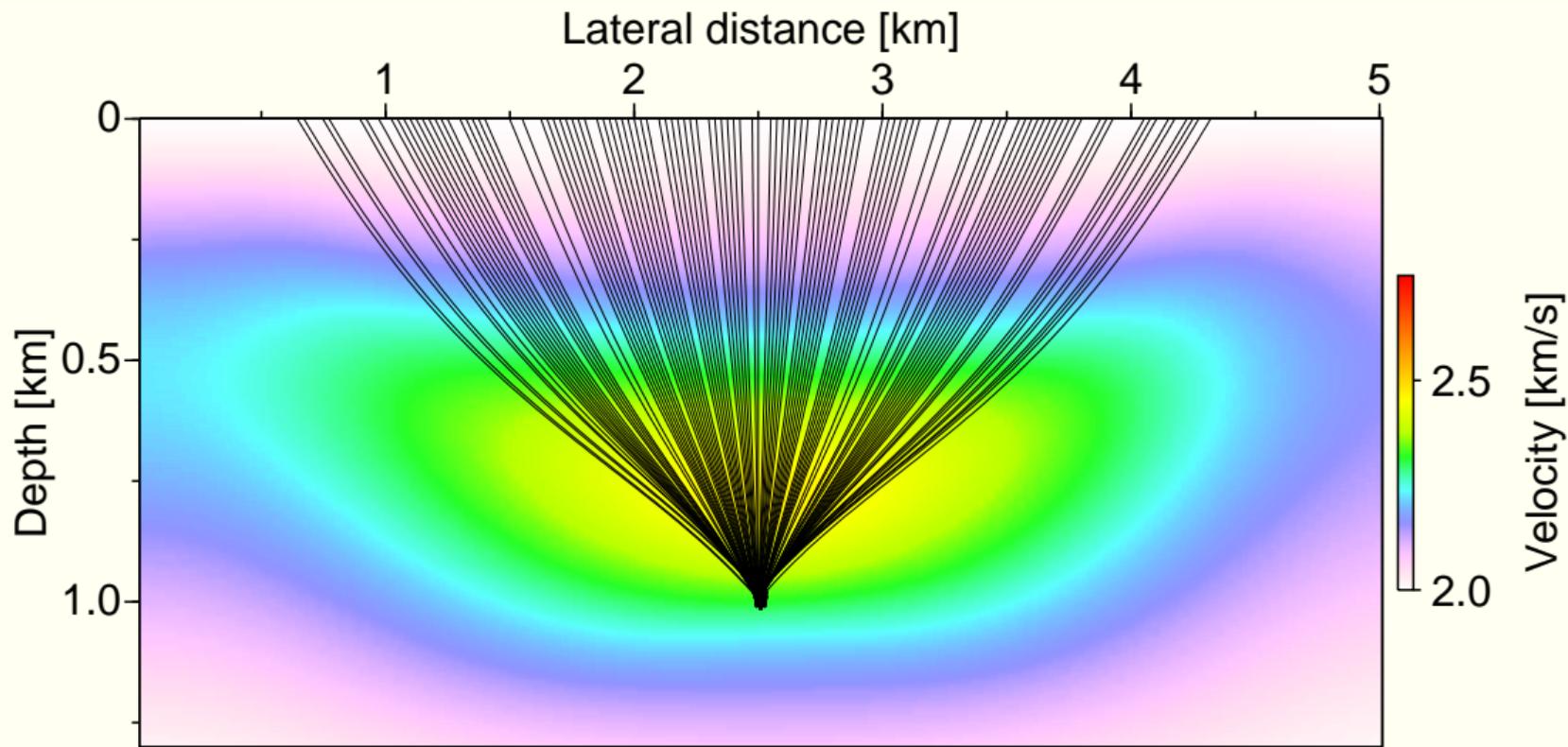


# Diffraction example: Inverted model



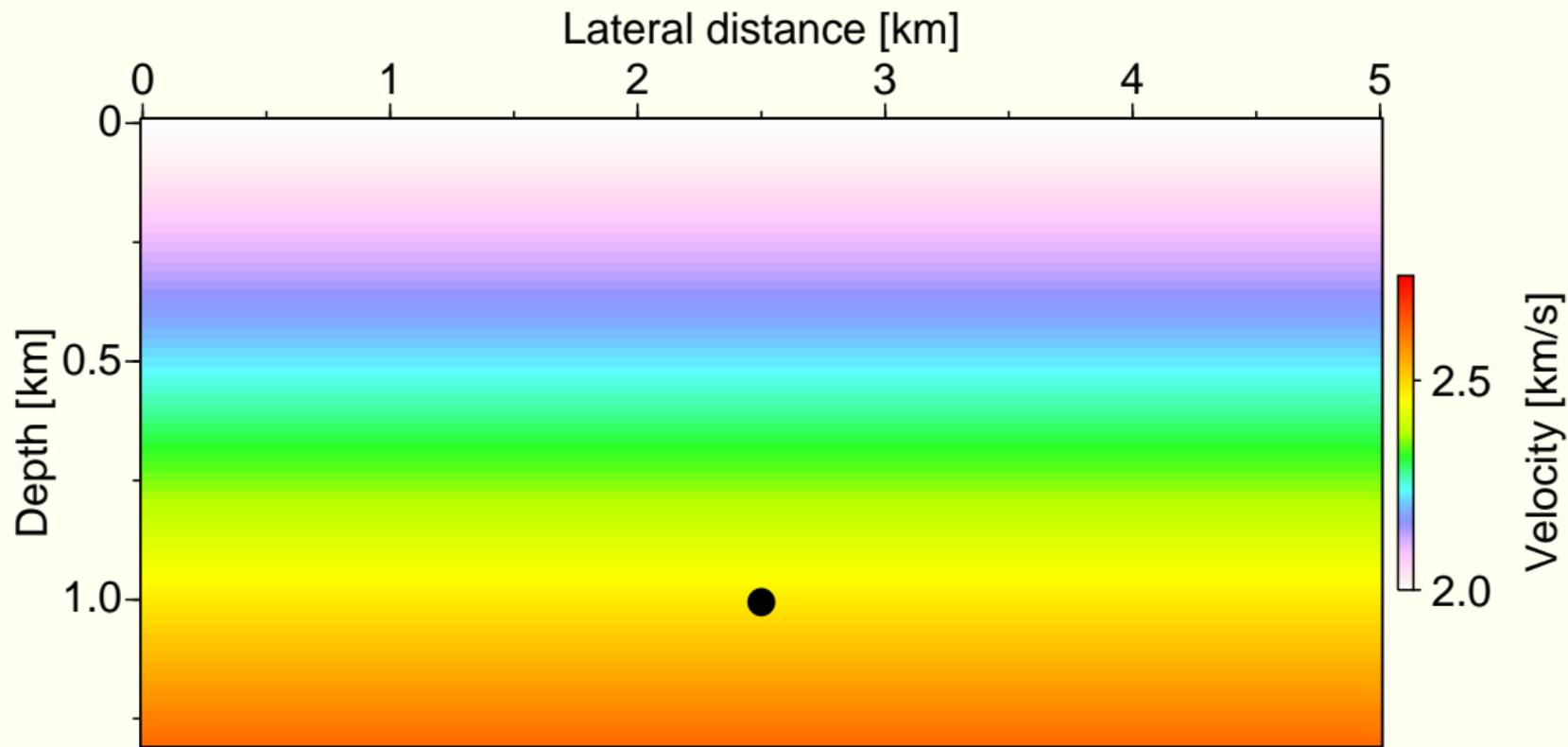
**Inverted model**

# Diffraction example: Inverted model



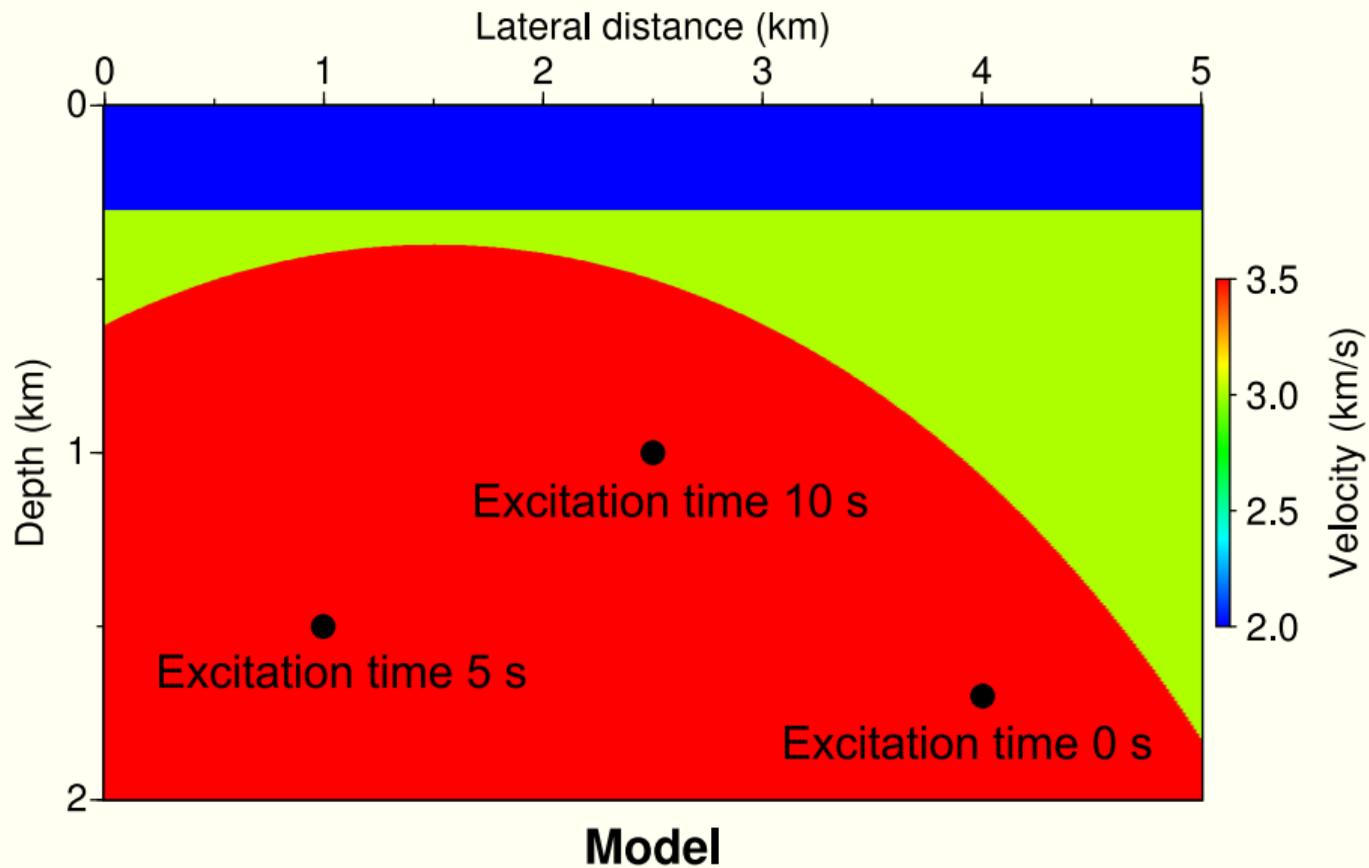
**Inverted model**

# Diffraction example: Correct model

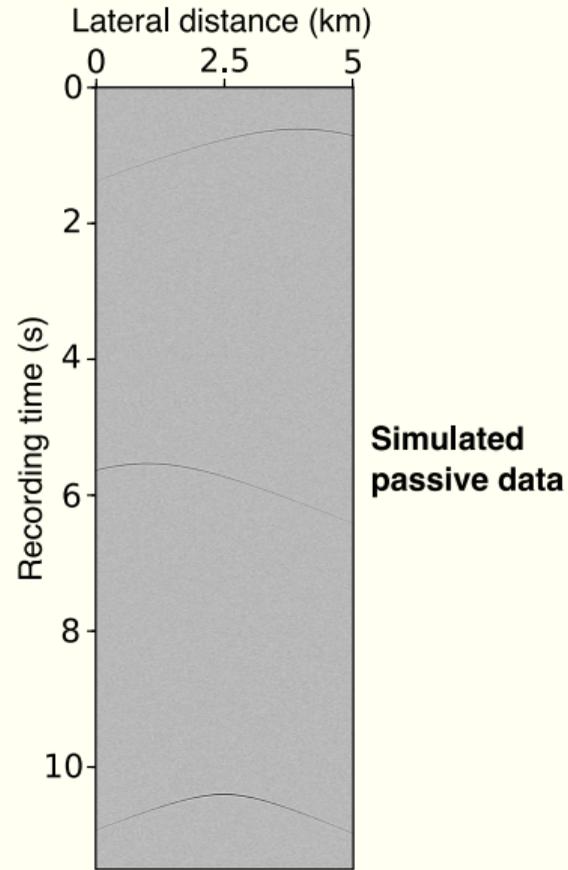
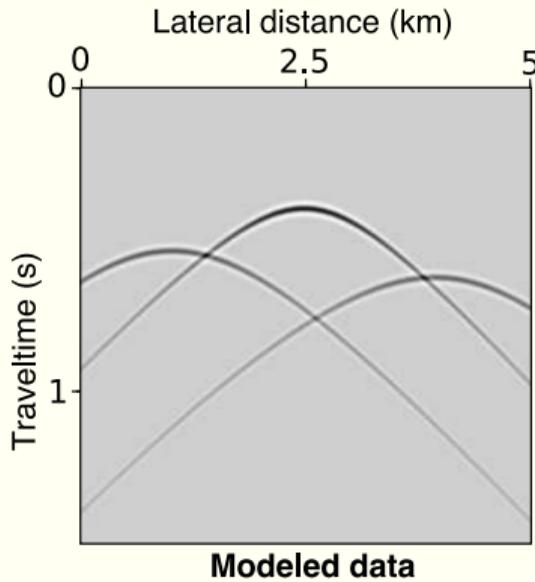


**Correct model**

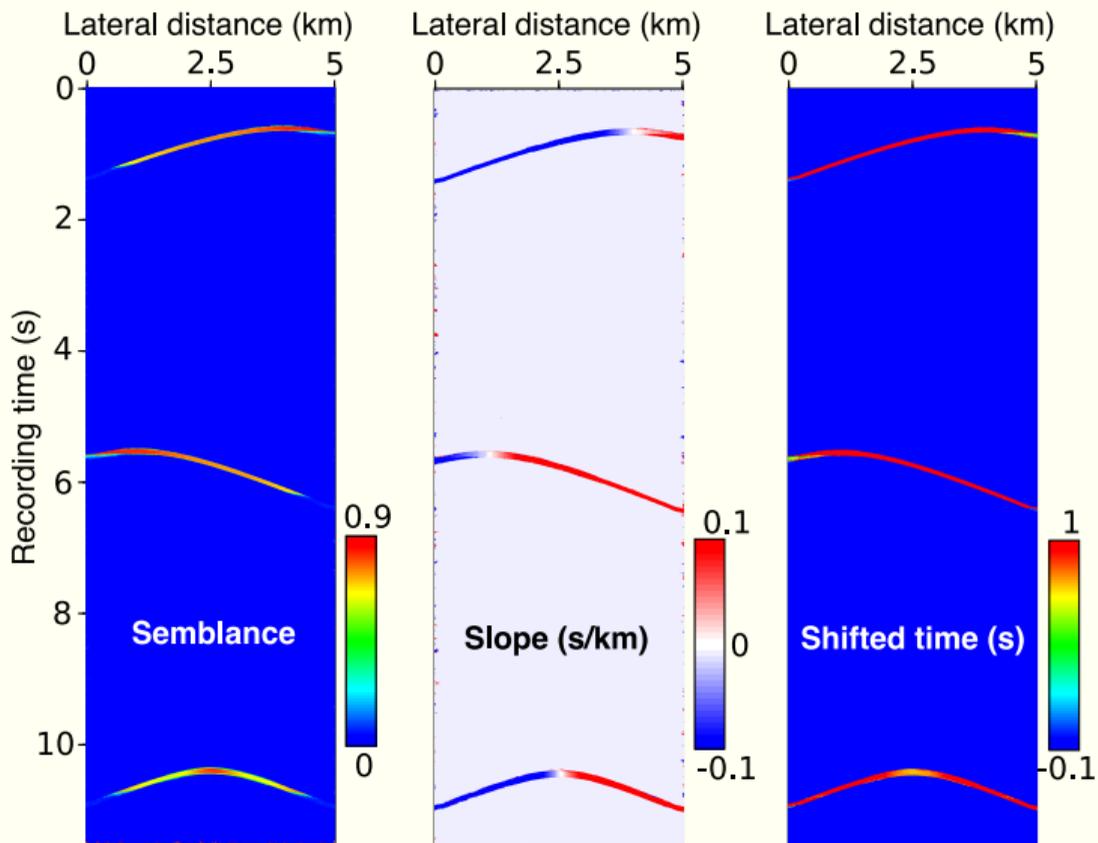
# Passive data example



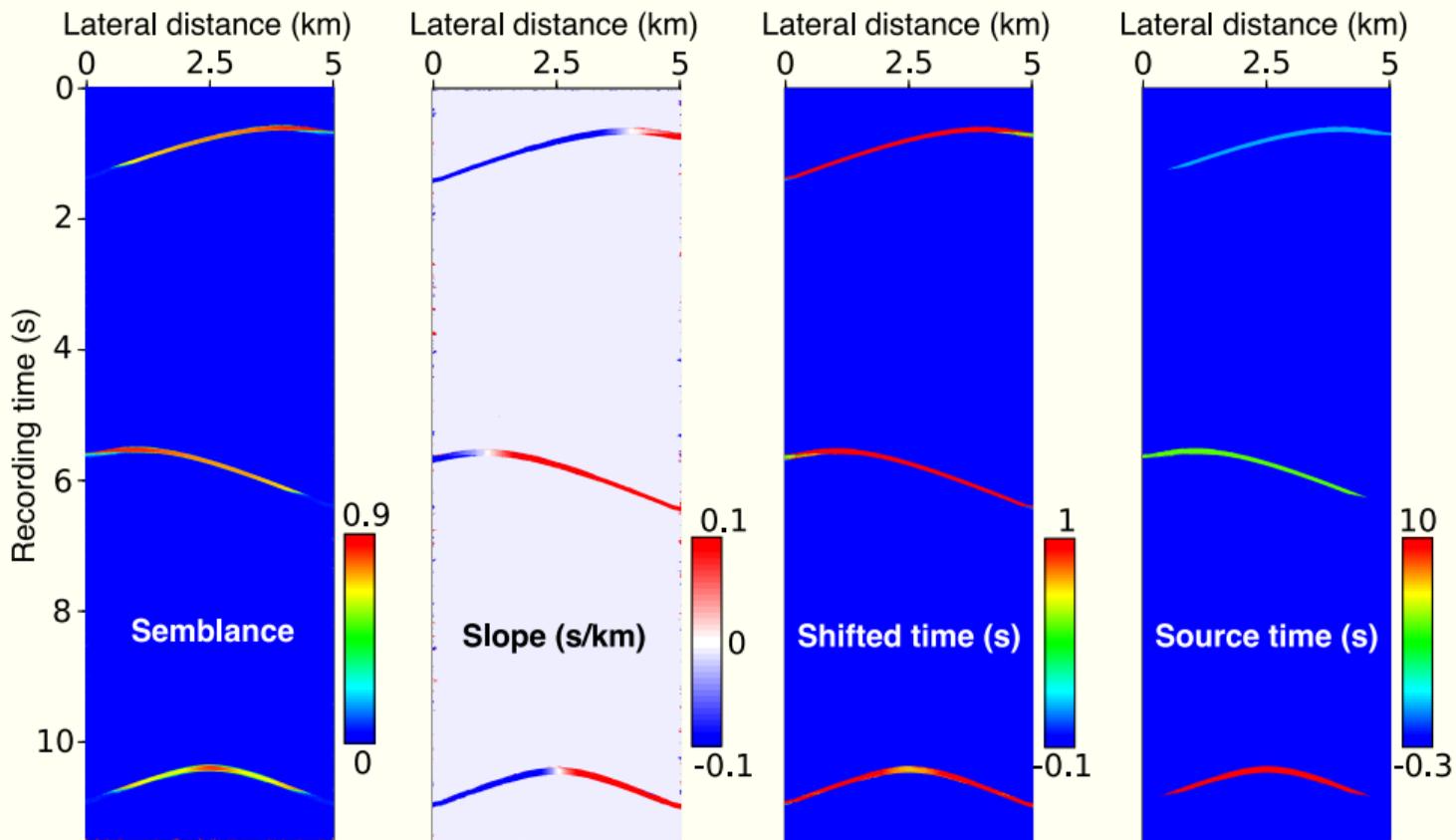
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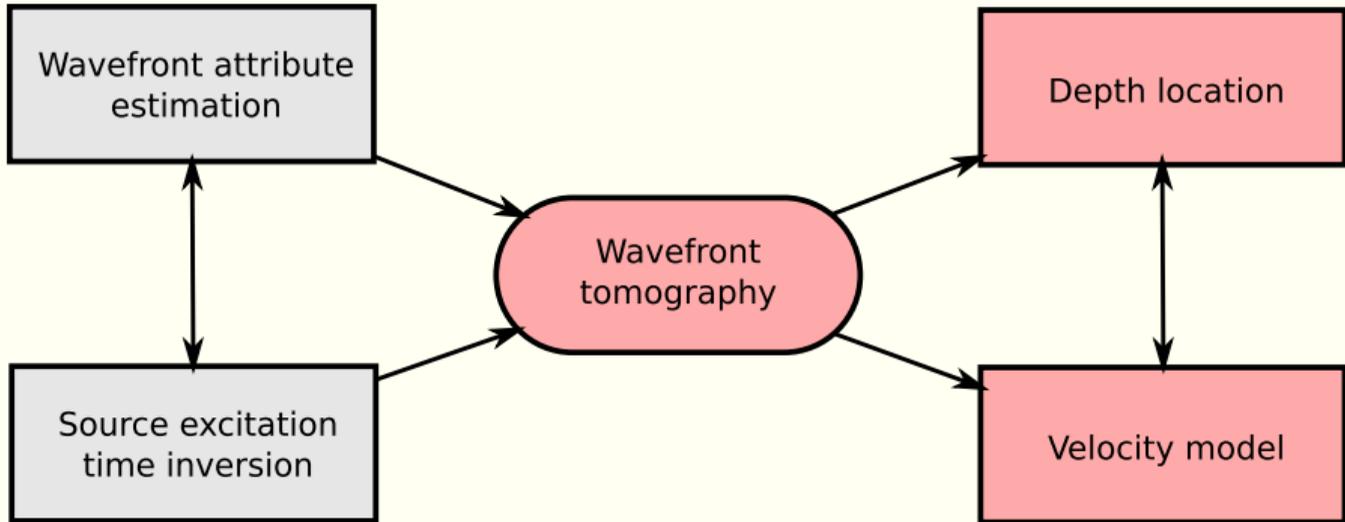
# Passive attribute panels



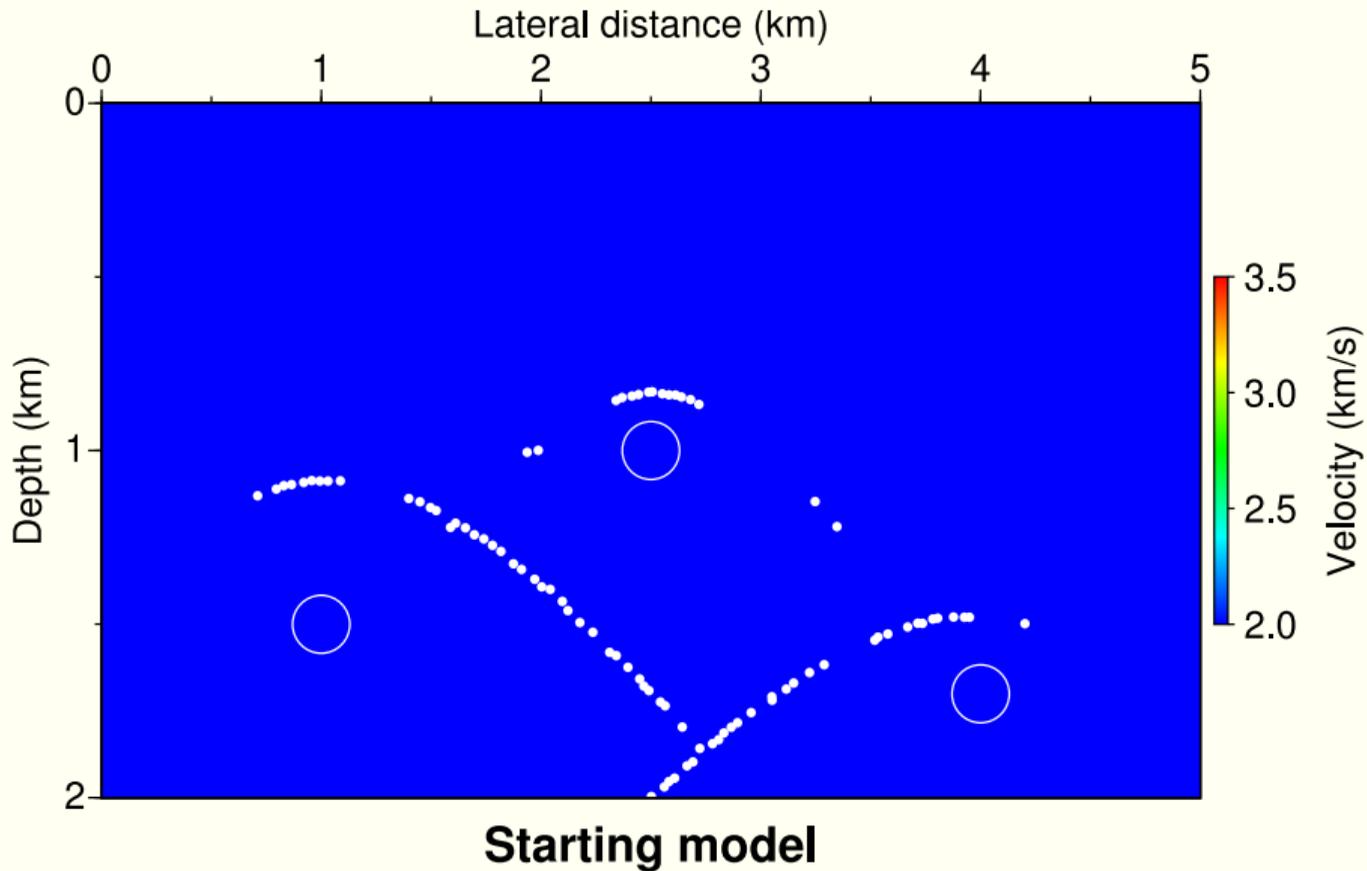
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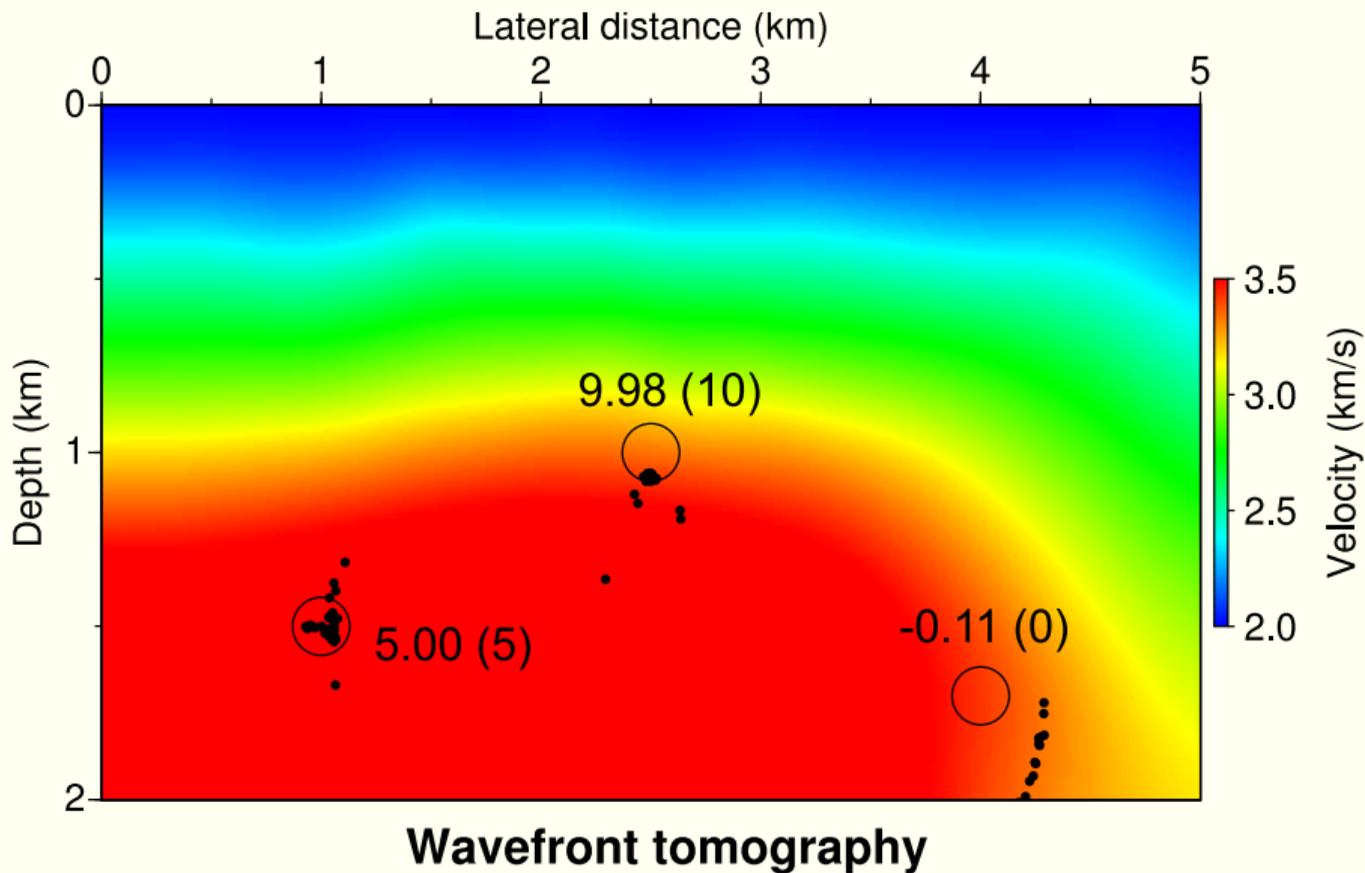
# Joint location and velocity inversion



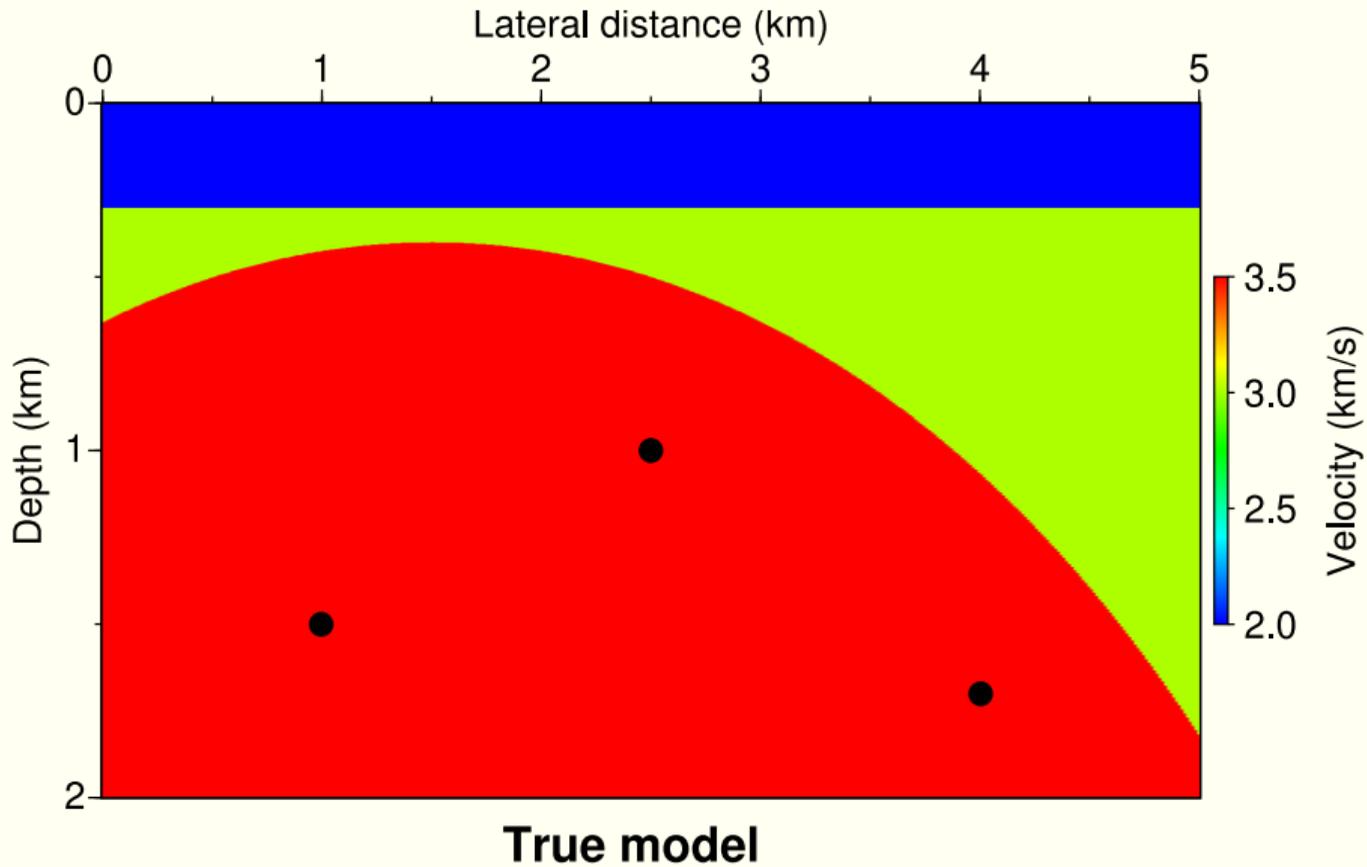
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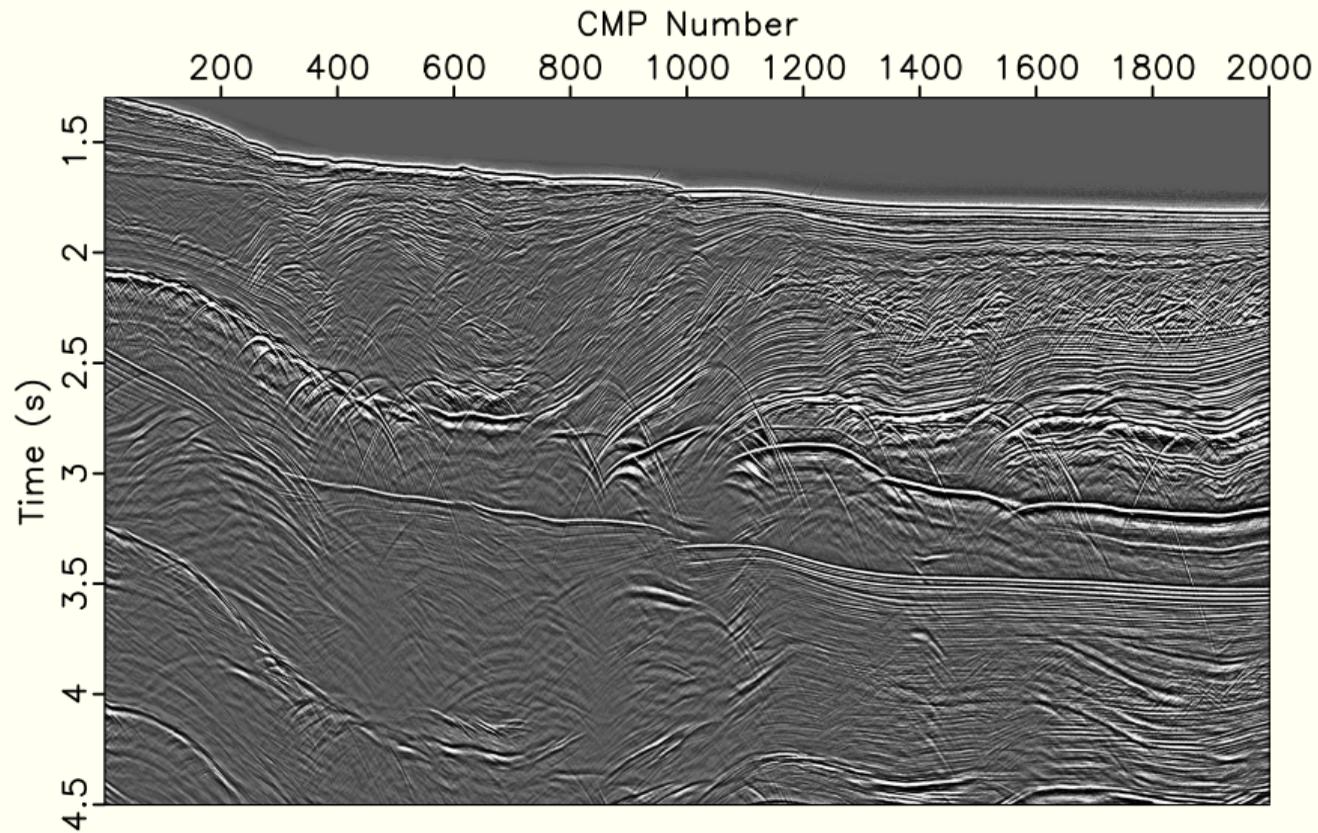
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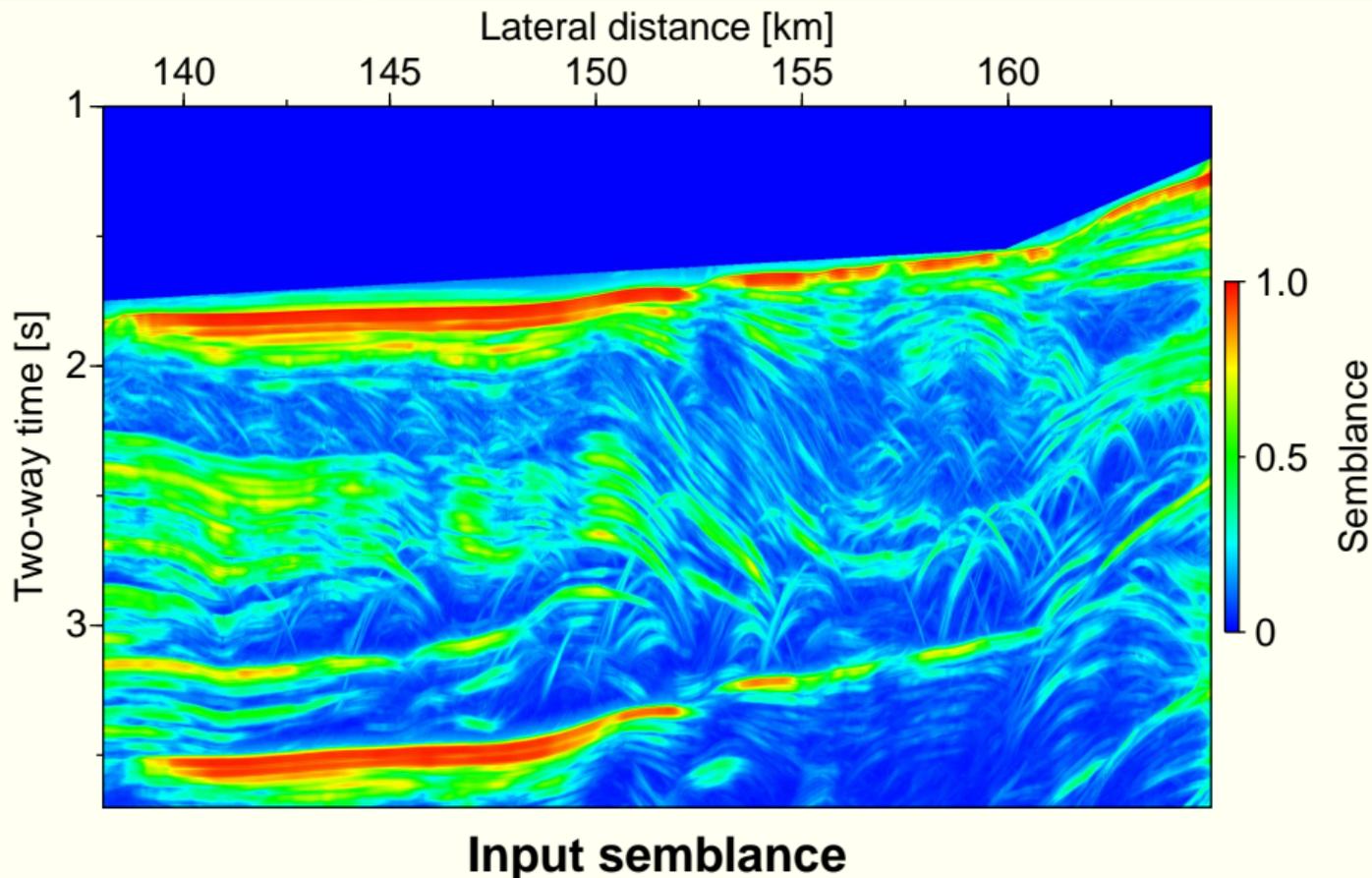
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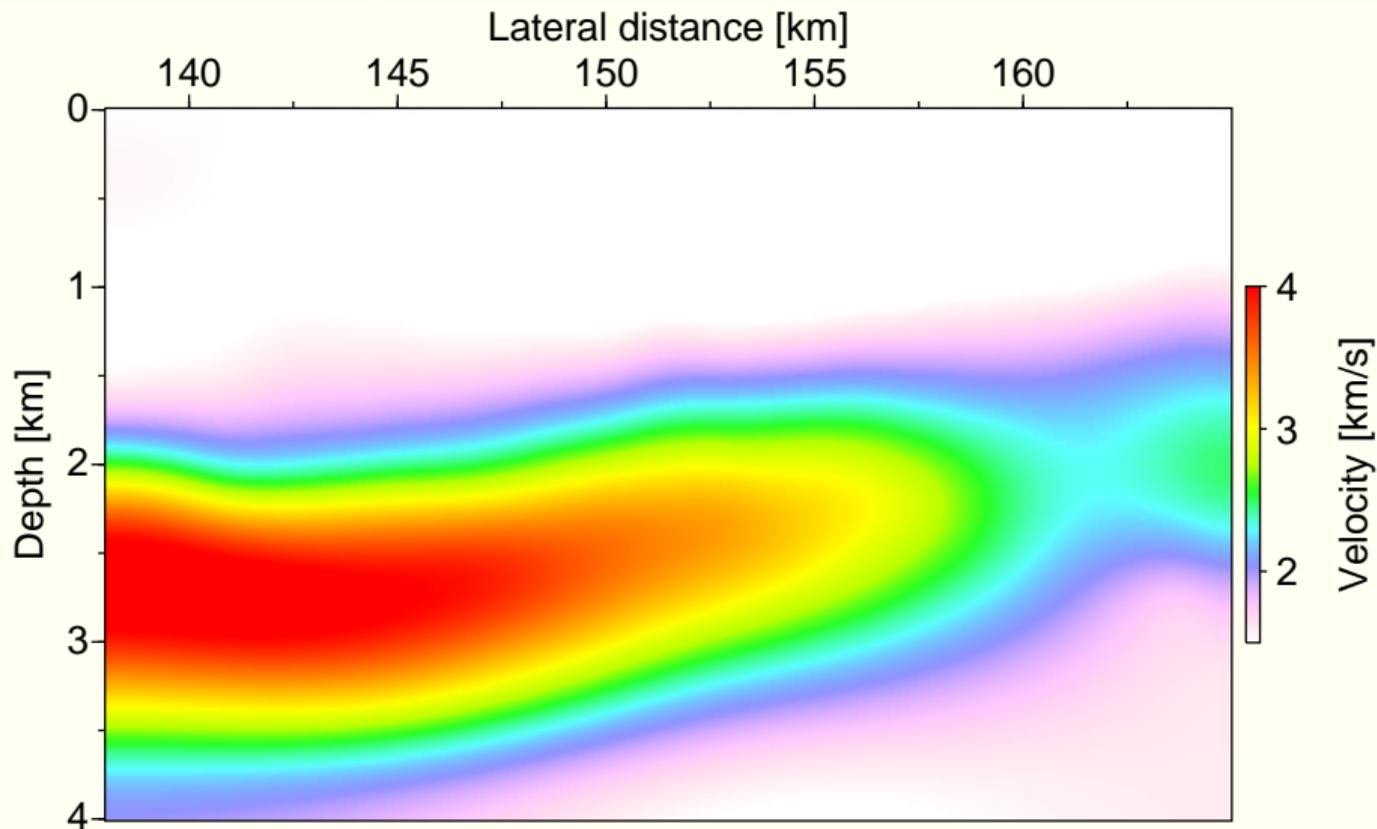
# Field data: Stack



# Field data: Input semblance

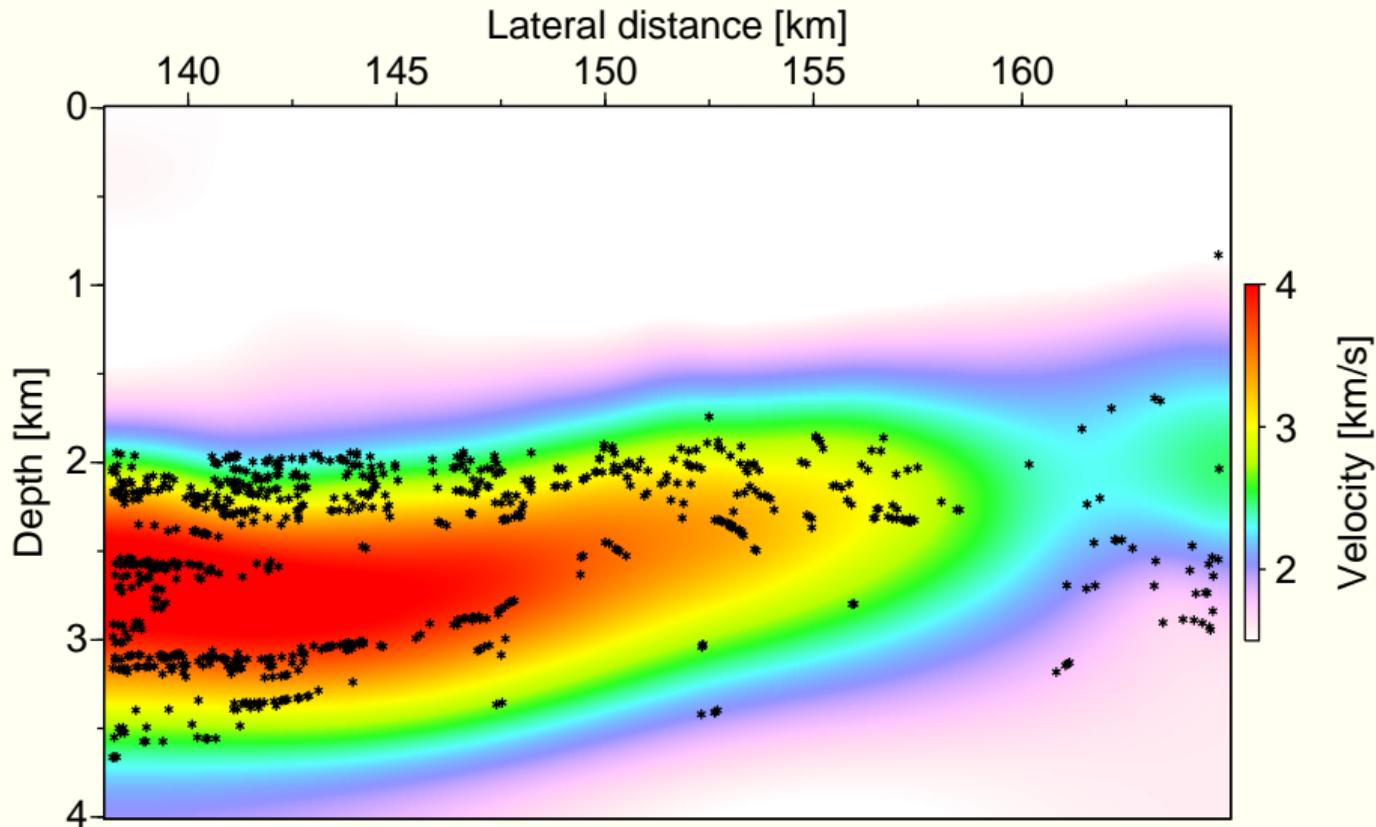


# Field data: Reflection-based inversion



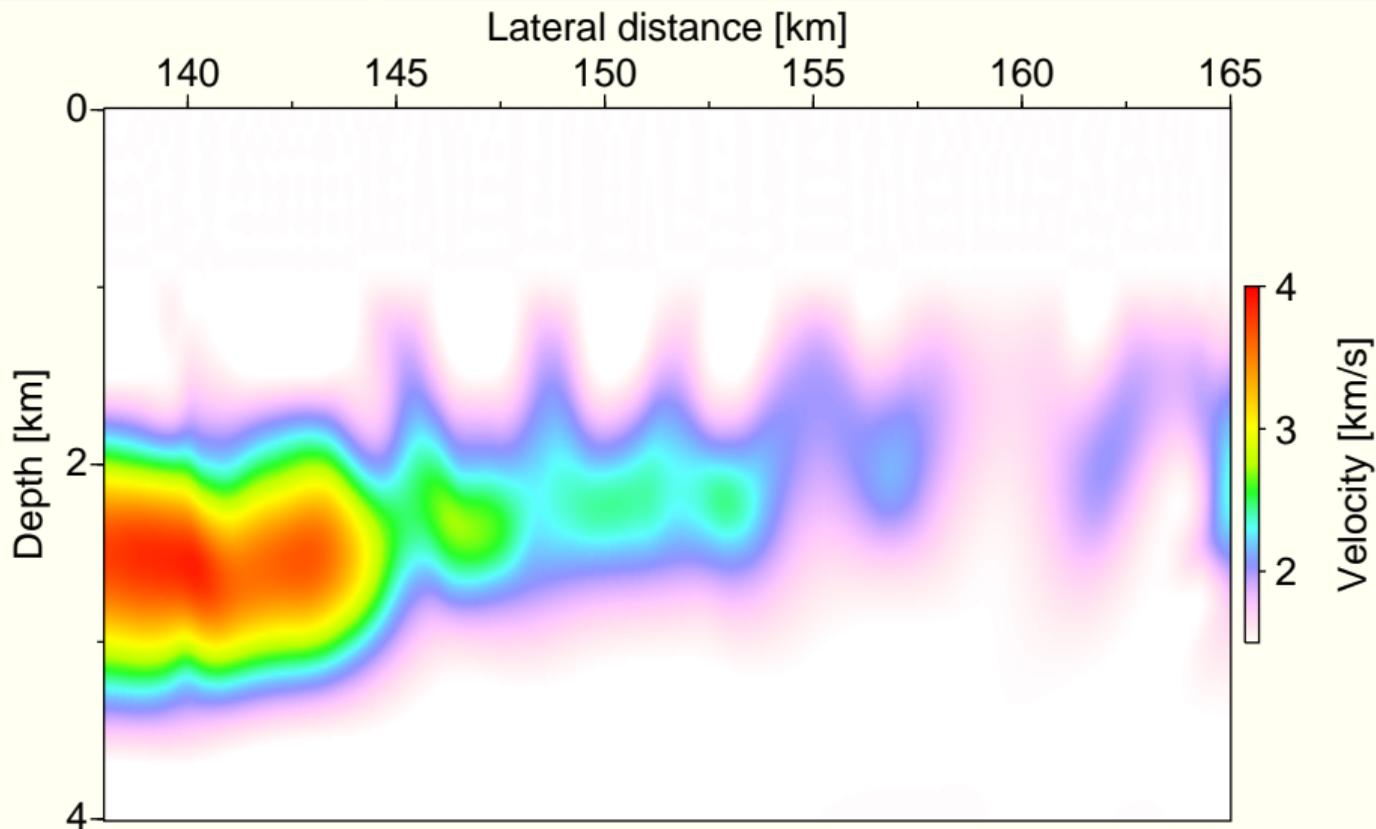
**Reflection-based inverted model**

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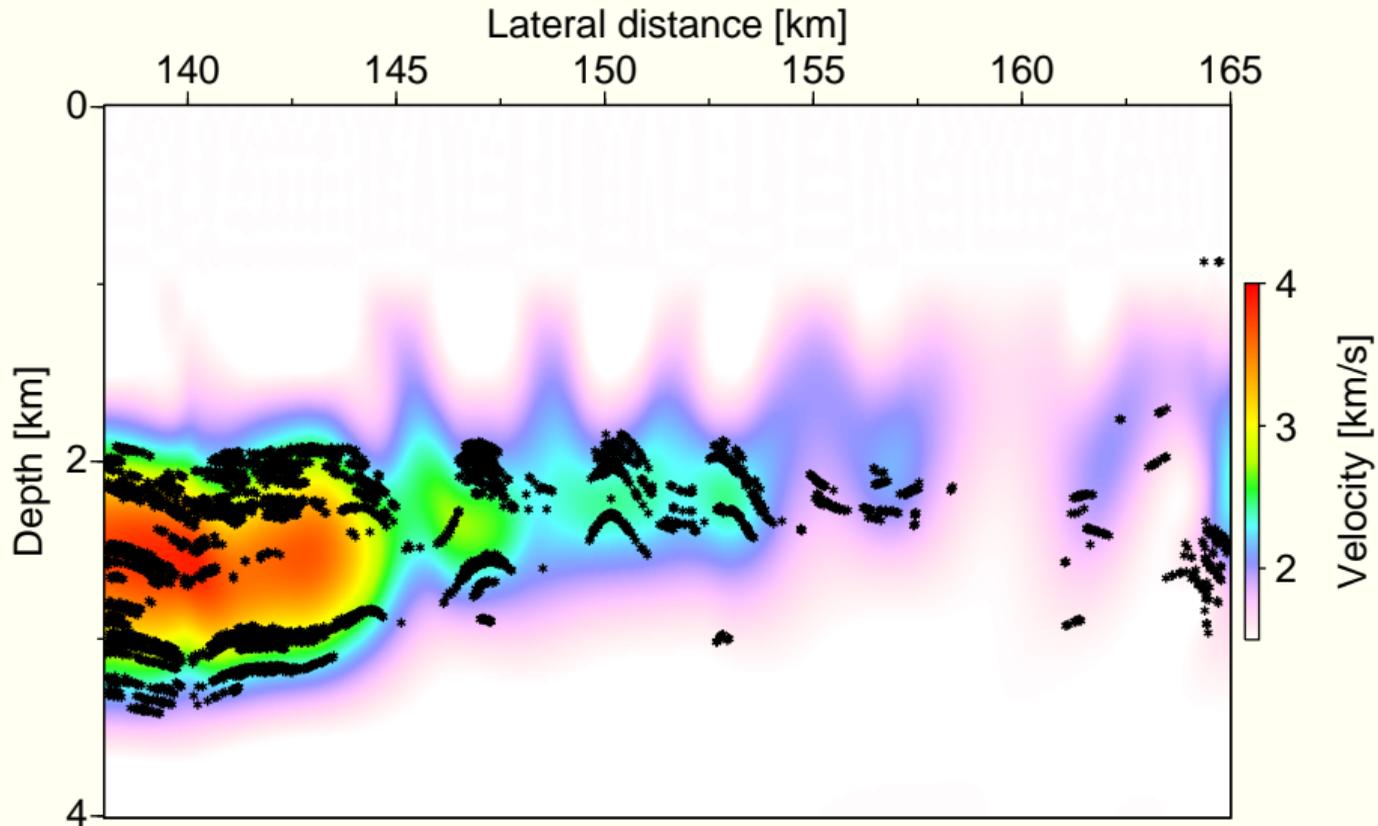
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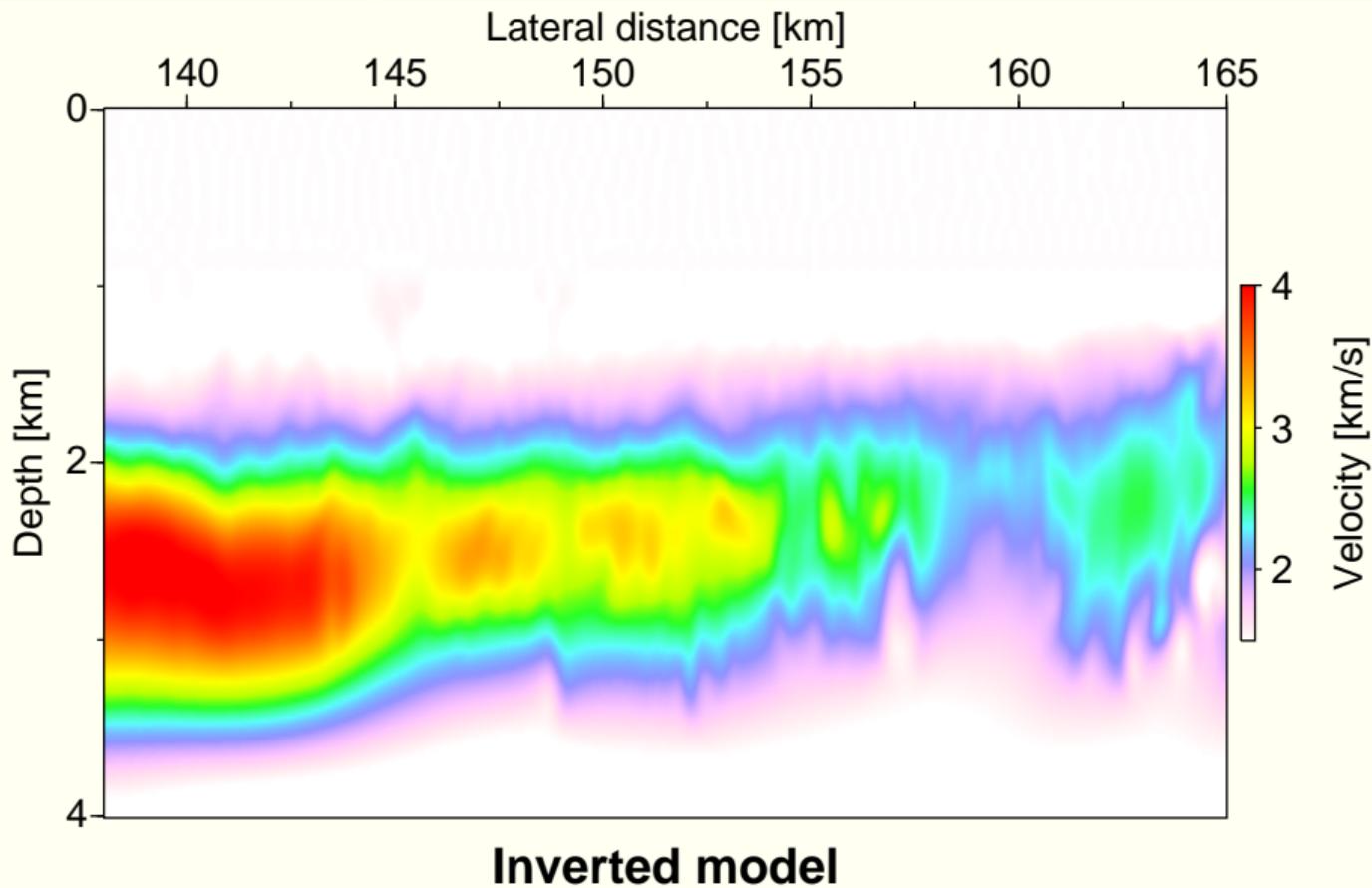
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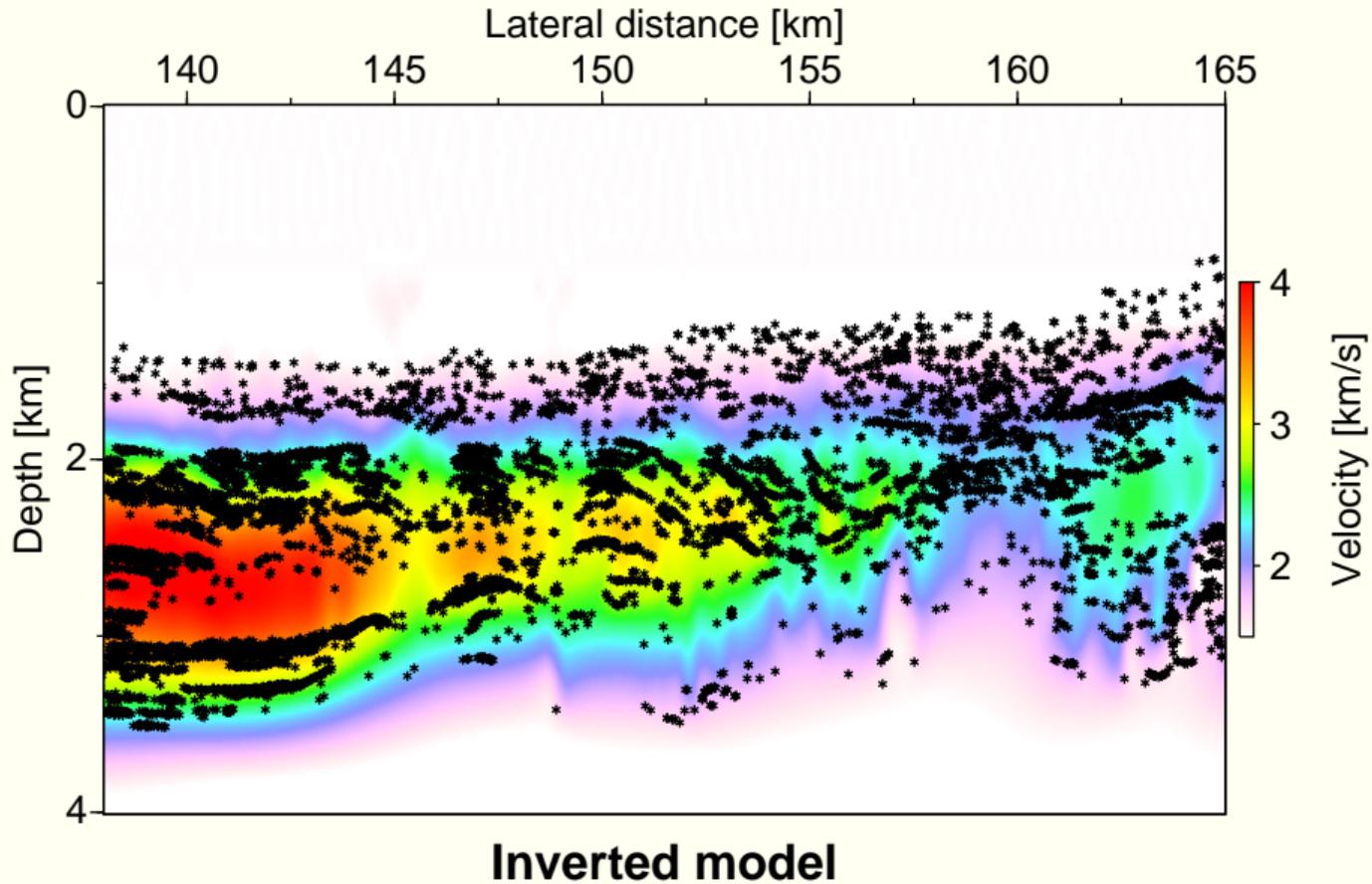


Reflection-based inverted model

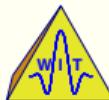
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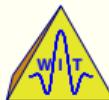


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- Joint passive event location and velocity inversion



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  - Global optimization



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  - Conflicting dip processing



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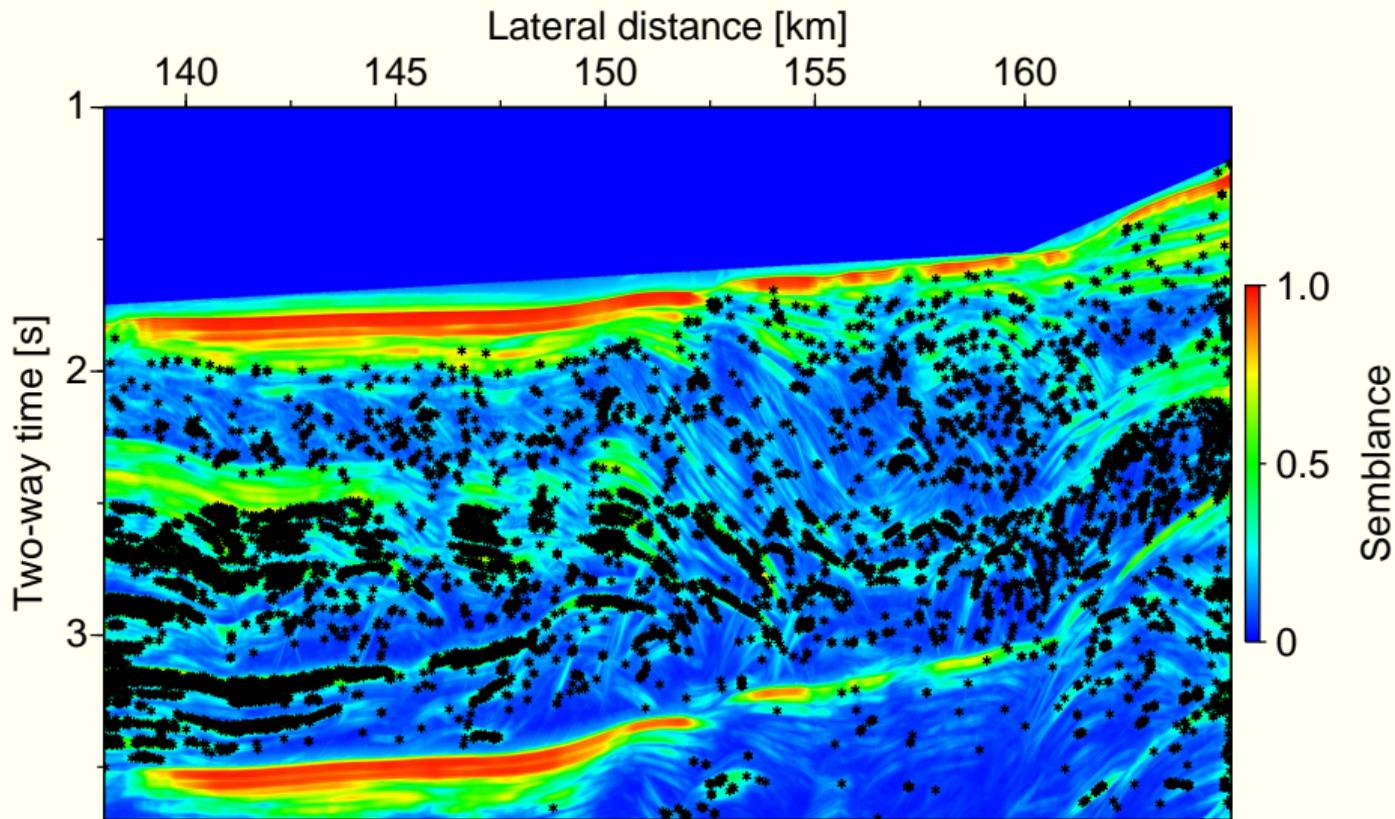
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- Anisotropy

# Acknowledgments



- Applied Seismics Group Hamburg
- Sponsors of the WIT consortium
- TGS
- Seismic Un\*x
- NORSAR

# Field data: Picked data points



Picked data points