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3D inversion of electromagnetic data

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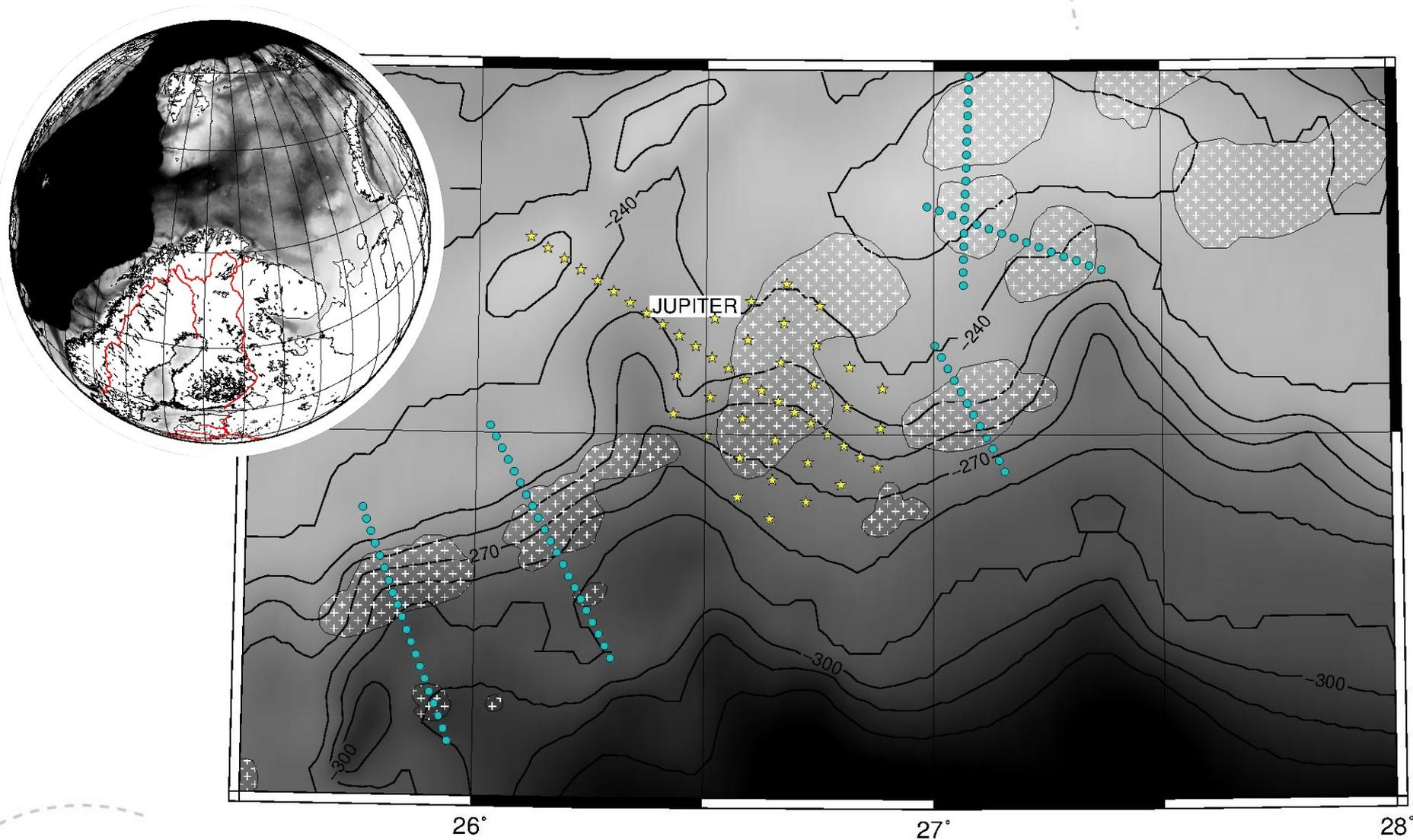
ROSE meeting April 2012 in Trondheim

Content

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 - Survey area
- Receiver orientation analysis
 - new method + example
- Joint CSEM and Magnetotelluric inversion
 - Theory
 - Real data example



Survey Area

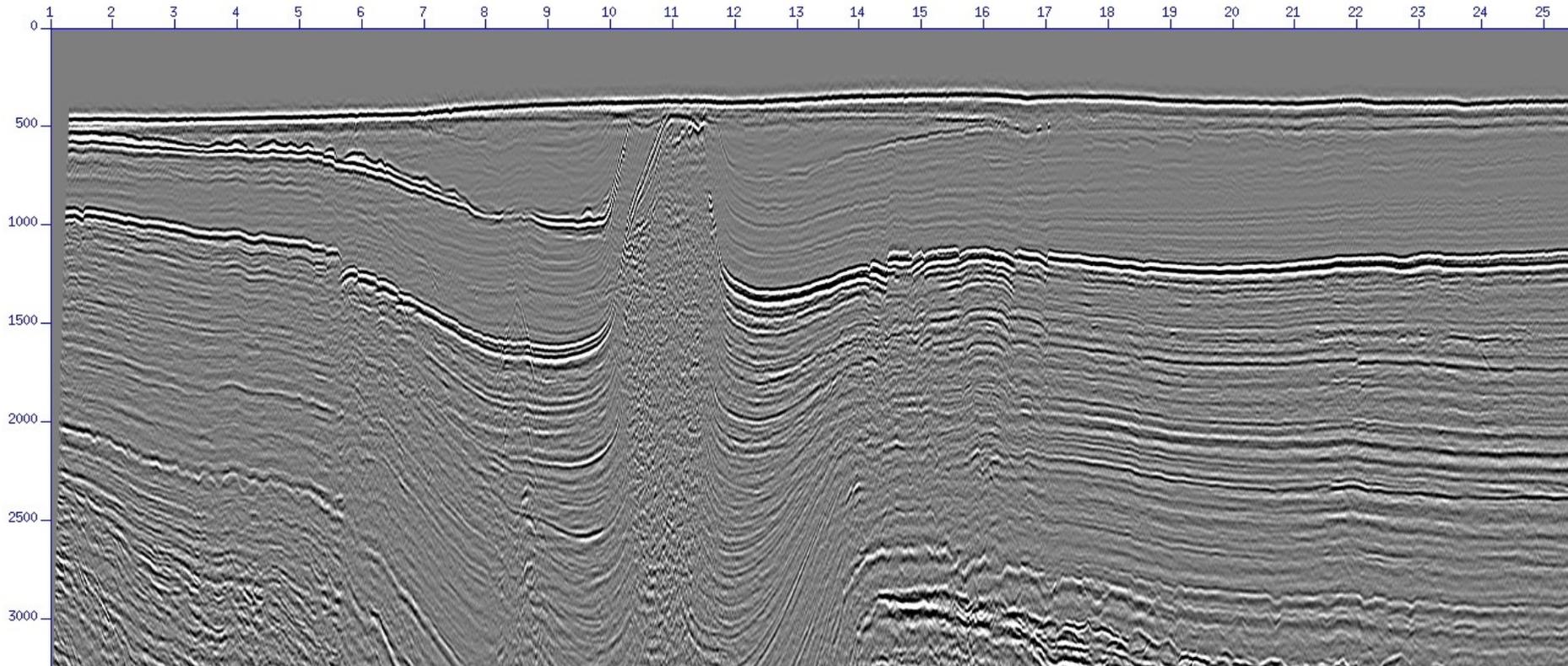


Motivation

- Weak primaries, strong multiples, and diffraction caused by the salt
- Limited seismic imaging quality near the salt structures
- Alternative methods CSEM, MT, gravity, and magnetics

SE

NW



Receiver orientation analysis



Photo by K. Hokstad

Orientation of instruments at the seabed is arbitrary and is defined by three angles:

- Azimuth (z-axis, Θ angle)
- Pitch (y-axis, α angle)
- Tilt (x-axis, β angle)



Receiver orientation analysis

- Assume source of the natural EM field to be a plane wave field and utilize 3 components of the magnetic field to estimate the receiver orientation on seabed

1. Tilt and Pitch angle

$$\min_{\alpha_k, \beta_k} \sum_{t_0}^{t_n} \left| H_z^{ref}(t) - \bar{H}_z^k(t) \right|$$

2. Separate 1D downgoing field

$$H_x^{(D)} = H_x - \left[\frac{1}{2} (H_x + \tilde{c}\tilde{\varepsilon}E_y) \right]$$

$$H_y^{(D)} = H_y - \left[\frac{1}{2} (H_y - \tilde{c}\tilde{\varepsilon}E_x) \right]$$

$$\tilde{c}\tilde{\varepsilon} = \sqrt{\frac{i\sigma}{\mu_0\omega}}$$

(Amundsen et al. 2006)

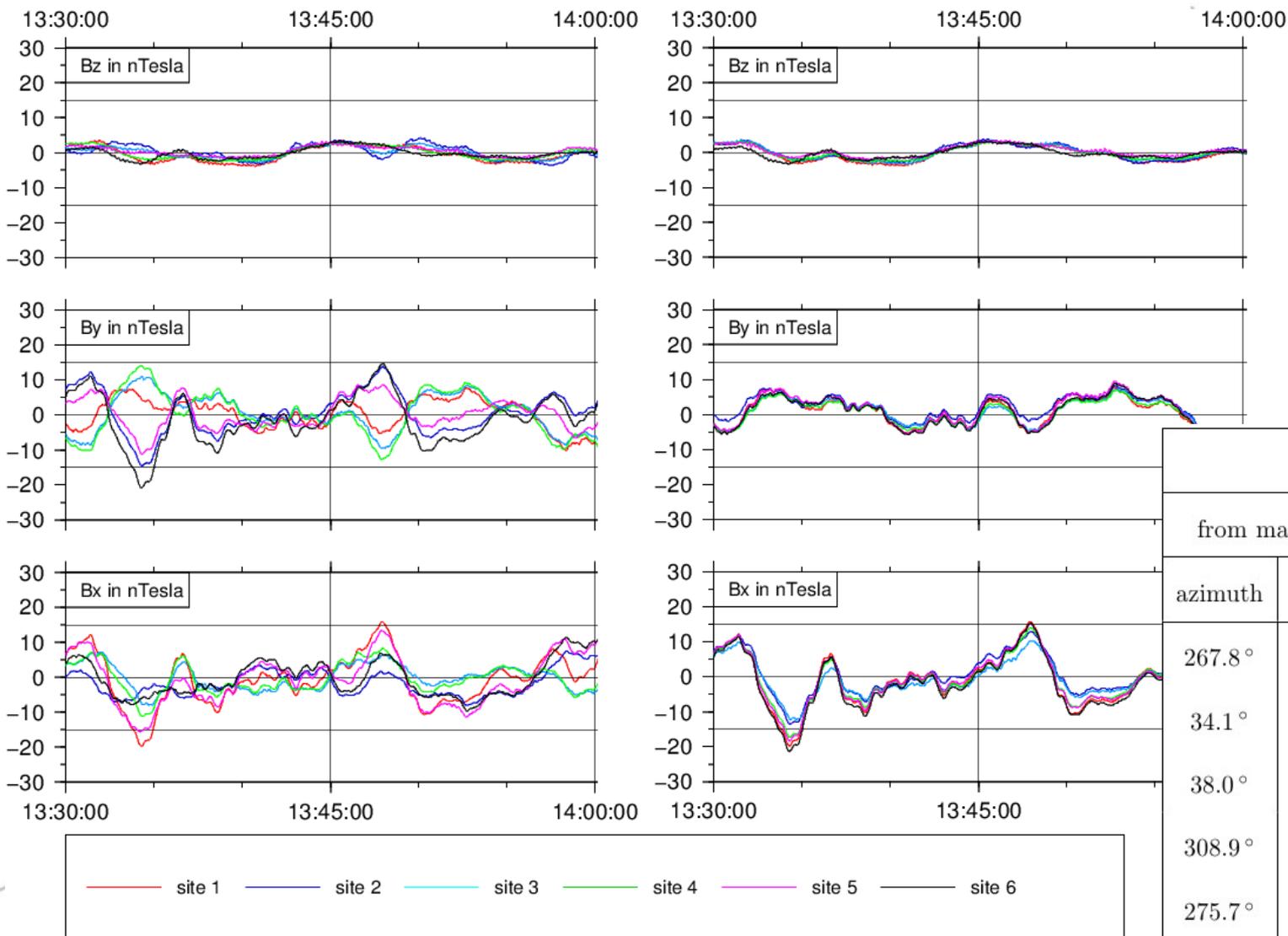
3. Azimuth angle

$$\min_{\theta_x^k, \sigma_{seafloor}} \sum_{t_0}^{t_n} \left| \left\{ |H_x^{D,ref}(t) - \hat{H}_x^{D,k}(t)| - |H_y^{D,ref}(t) - \hat{H}_y^{D,k}(t)| \right\} \right|^2$$

(Mütschard et al., *subm. to Geophysics* 2012)



Receiver orientation analysis



Orientation			
from magnetotellurics			from CSEM
azimuth	pitch	tilt	azimuth
267.8°	10.0°	-13.0°	273.28°
34.1°	10.0°	8.0°	33.01°
38.0°	4.0°	-2.0°	41.07°
308.9°	0.0°	-8.0°	307.52°
275.7°	1.0°	0.0°	276.05°

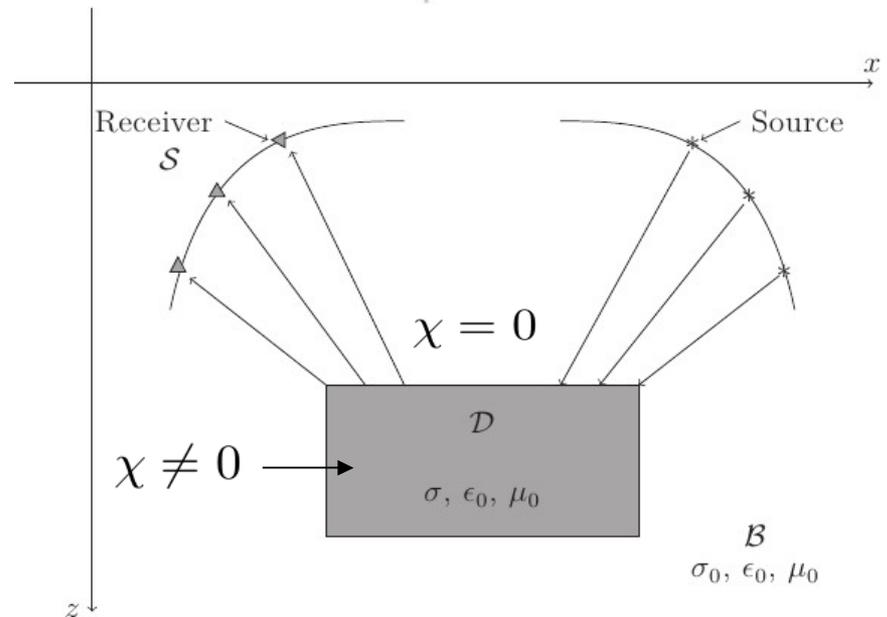
Joint inversion of CSEM and MT data

<u>CSEM</u>	<u>Magnetotellurics</u>
Active method, periodically alternating electric dipole	Passive method, natural occurring plane wave EM source field
0.1Hz - 20Hz	0.001Hz - 10Hz
Skin depth 5km in marine environm.	Skin depth up to 50km
High resolution, number of source positions	Low resolution, receiver spacing
Sensitive to resistors in a conductive background	Sensitive to conductors in a resistive background
Vertical + horizontal resistivity	Horizontal resistivity

Joint inversion of CSEM and MT data

3D Contrast source inversion of the scattered electric field

Model divided into a background B and anomalous D region



$$e_i(\mathbf{x}) = e_i^{\text{inc}}(\mathbf{x}) + \int_{\mathcal{D}} G_{ij}^E(\mathbf{x}, \mathbf{x}') \sigma_{0,v}(\mathbf{x}') \chi_{jj}(\mathbf{x}') e_j(\mathbf{x}') d\mathbf{x}', \quad \mathbf{x} \in \mathcal{D}$$

Total field = background field + scattered field (Lippmann – Schwinger equation)

χ is the contrast $\mathcal{W} = \chi e$ is the contrast source

Joint inversion of CSEM and MT data

Definition of:

1) Contrast sources

$$\mathcal{W}_{\text{CSEM}} = \left\{ \mathbf{w}_{\text{CSEM}}^{j,k} \right\}_{j=1 \dots N_s}^{k=1 \dots N_{f\text{CSEM}}} = \left\{ \chi \mathbf{e}_{\text{CSEM}}^{j,k} \right\}_{j=1 \dots N_s}^{k=1 \dots N_{f\text{CSEM}}}$$

$$\mathcal{W}_{\text{MT}} = \left\{ \mathbf{w}_{\text{MT}}^k \right\}_{k=1 \dots N_{f\text{MT}}} = \left\{ \chi \mathbf{e}_{\text{MT}}^k \right\}_{k=1 \dots N_{f\text{MT}}},$$

2) Data operators

$$\mathbf{e} = \mathbf{e}^{\text{inc}} + G^{E,\mathcal{D}} \mathbf{w}$$

$$\mathbf{f}^E = G^{E,\mathcal{S}} \mathbf{w}$$



Joint inversion of CSEM and MT data

Objective function:

$$\begin{aligned}
 F_1(\mathcal{W}_{\text{CSEM}}, \mathcal{W}_{\text{MT}}, \boldsymbol{\chi}) &= \alpha_{1,\text{CSEM}}^E \sum_{k=1}^{N_{\text{fCSEM}}} \sum_{j=1}^{N_s} \left\| \Xi_{\text{CSEM}}^{E,j,k} \left(\mathbf{f}_{\text{CSEM}}^{E,j,k} - G^{E,S,k} \mathbf{w}_{\text{CSEM}}^{j,k} \right) \right\|_S^2 && \text{CSEM data fidelity} \\
 &+ \alpha_{2,\text{CSEM}} \sum_{k=1}^{N_{\text{fCSEM}}} \sum_{j=1}^{N_s} \left\| \boldsymbol{\chi} \mathbf{e}_{\text{CSEM}}^{\text{inc},j,k} - \mathbf{w}_{\text{CSEM}}^{j,k} + \boldsymbol{\chi} G^{E,D,k} \mathbf{w}_{\text{CSEM}}^{j,k} \right\|_{\mathcal{D}}^2 && \text{Lippmann Schwinger} \\
 &+ \alpha_{1,\text{MT}}^E \sum_{k=1}^{N_{\text{fMT}}} \left\| \Xi_{\text{MT}}^{E,k} \left(\mathbf{f}_{\text{MT}}^{E,k} - G^{E,S,k} \mathbf{w}_{\text{MT}}^k \right) \right\|_S^2 && \text{MT data fidelity} \\
 &+ \alpha_{2,\text{MT}} \sum_{k=1}^{N_{\text{fMT}}} \left\| \boldsymbol{\chi} \mathbf{e}_{\text{MT}}^{\text{inc},k} - \mathbf{w}_{\text{MT}}^k + \boldsymbol{\chi} G^{E,D,k} \mathbf{w}_{\text{MT}}^k \right\|_{\mathcal{D}}^2 && \text{Lippmann - Schwinger} \\
 &+ \text{regularization}
 \end{aligned}$$

(Wiik, to be subm. to Geophys. Prospecting 2012)



Joint inversion of CSEM and MT data

Input: Initial contrast and contrast sources

foreach *iteration* **do**

foreach *CSEM frequency* **do**

foreach *source* **do**

 | Minimize equation F_1 with respect to $\mathbf{w}_{\text{CSEM}}^{j,k}$

end

end

foreach *MT frequency* **do**

 | Minimize equation F_1 with respect to \mathbf{w}_{MT}^k

end

 Minimize equation F_1 with respect to χ

if *stop criterion is true* **then**

 | stop iterations

else

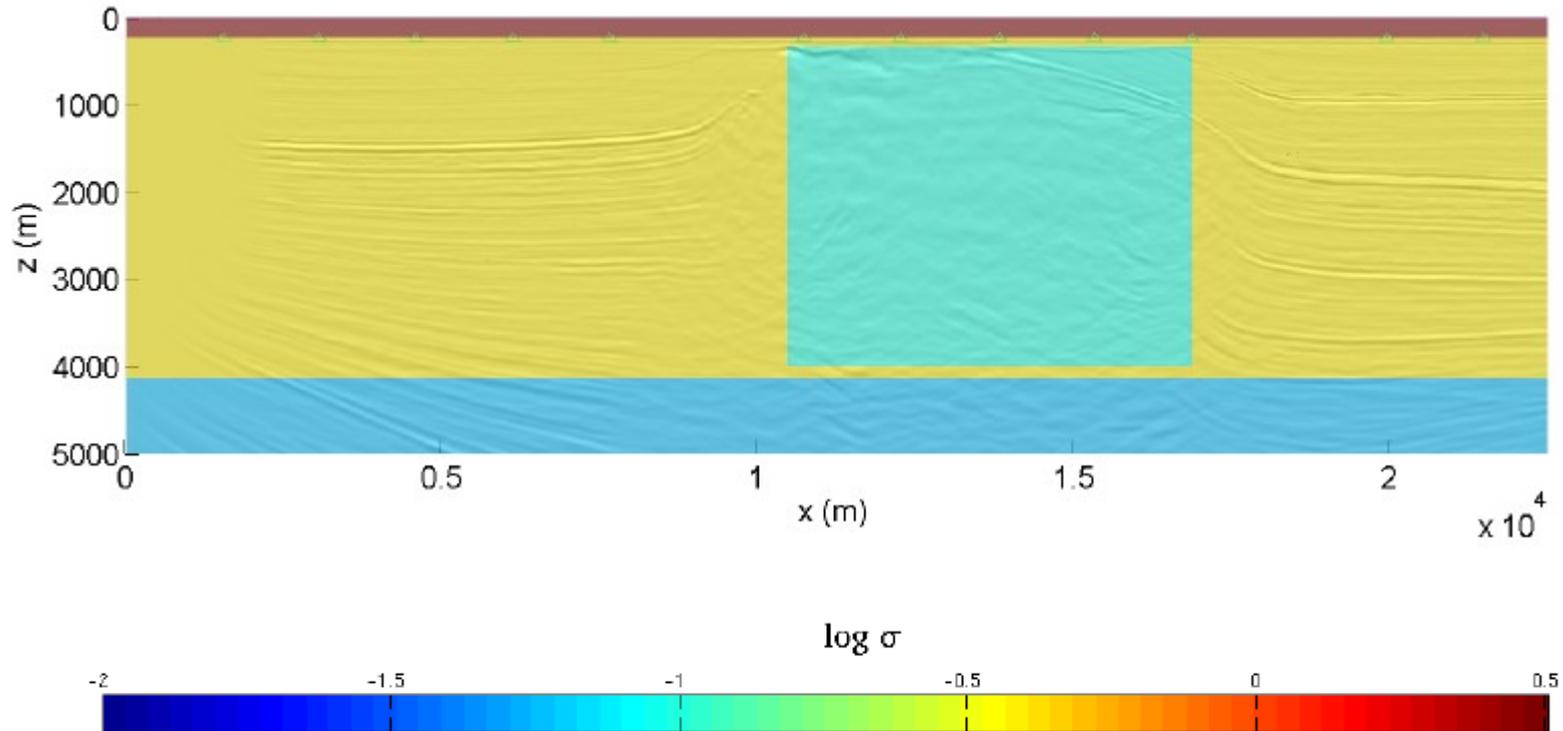
 | proceed to next iteration

end

end

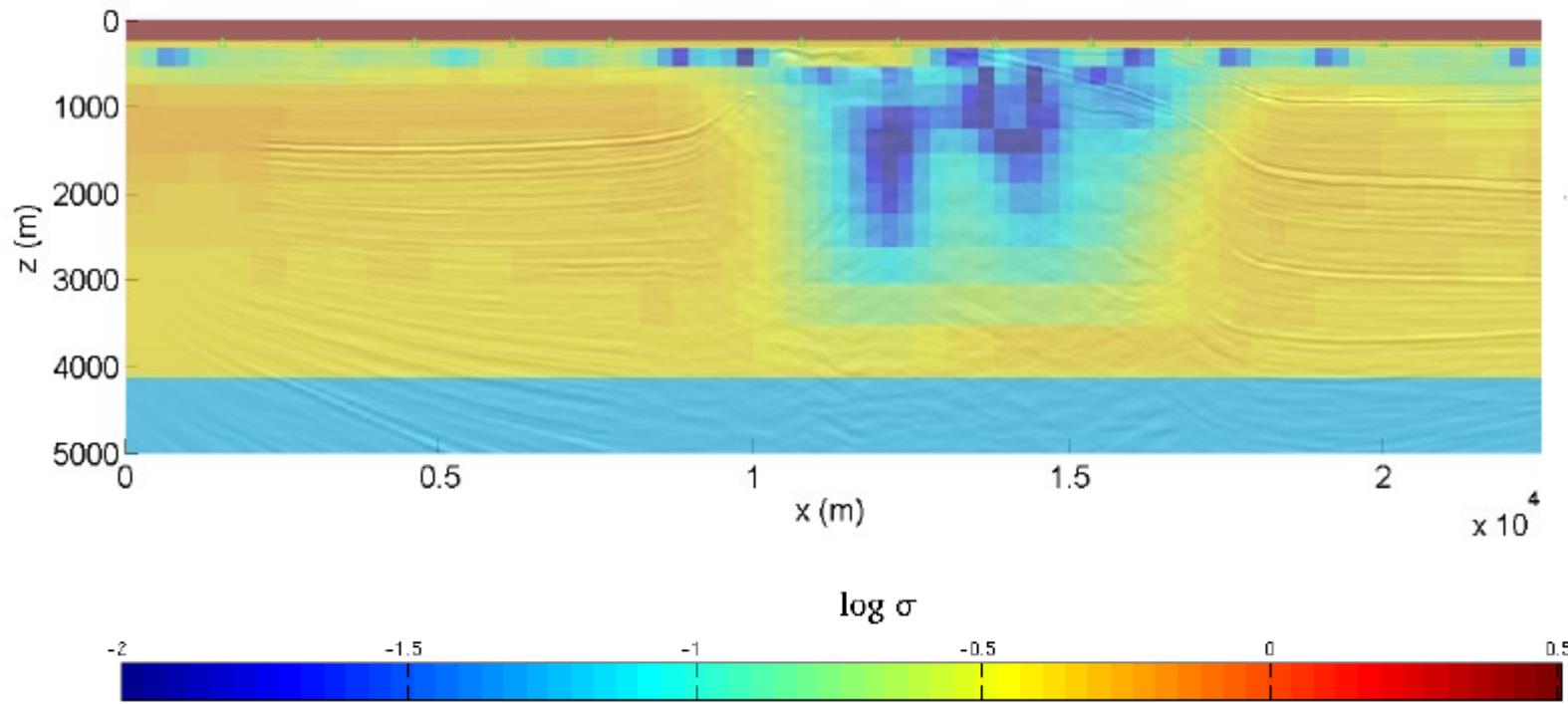


Joint inversion of CSEM and MT data



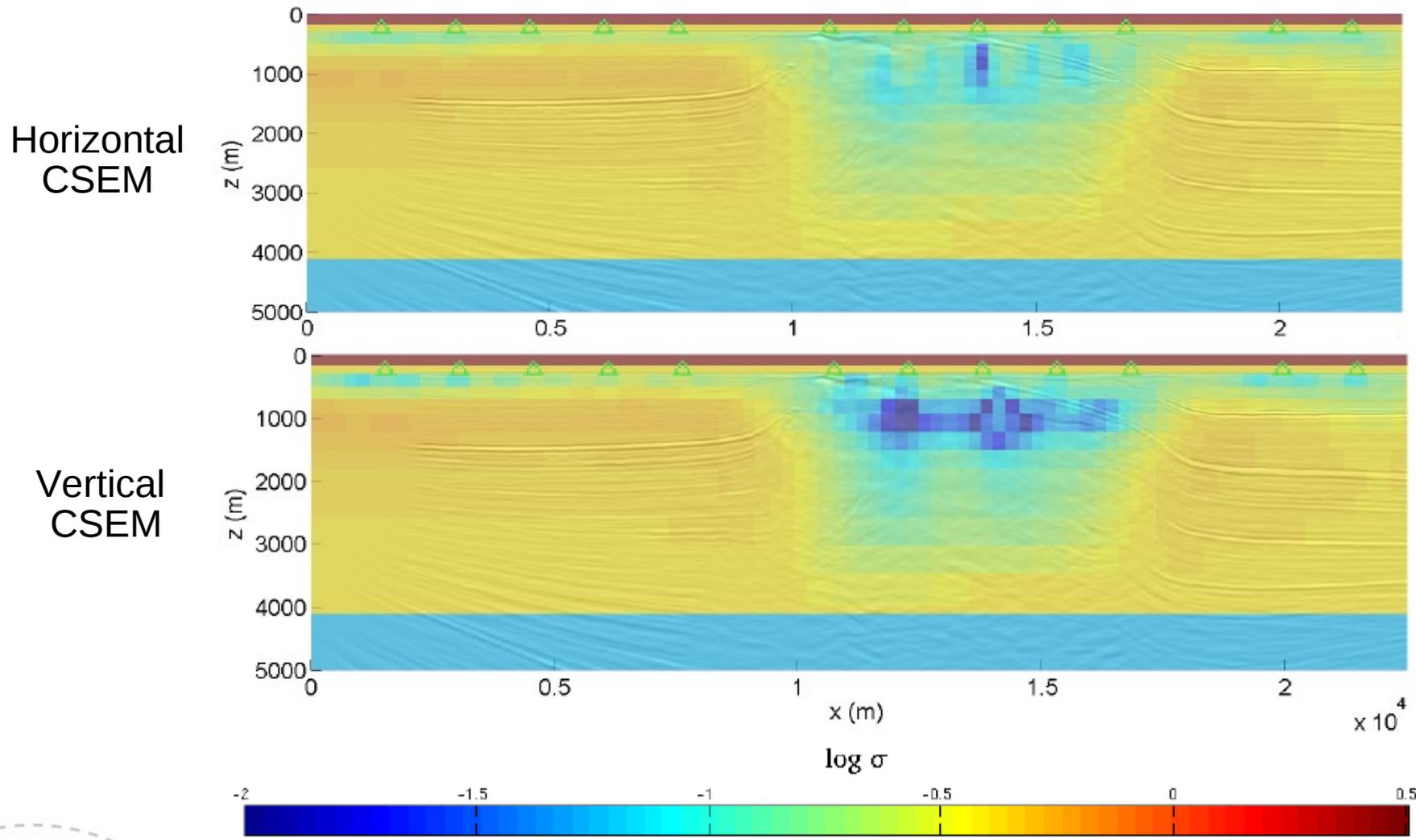
Initial model for MT and CSEM inversion

Joint inversion of CSEM and MT data



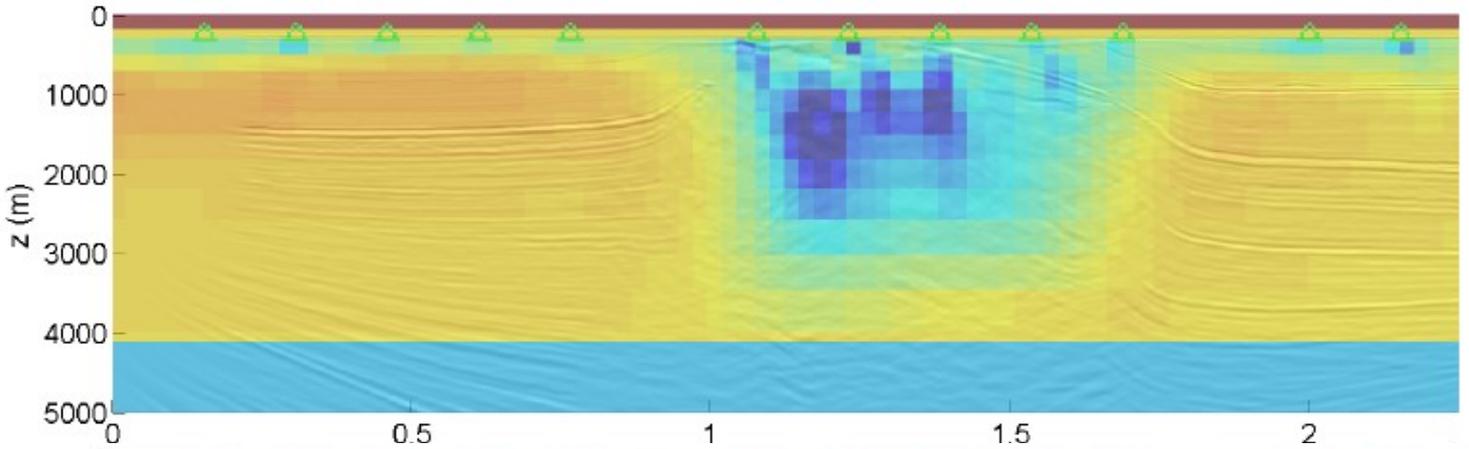
Magnetotelluric data only

Joint inversion of CSEM and MT data

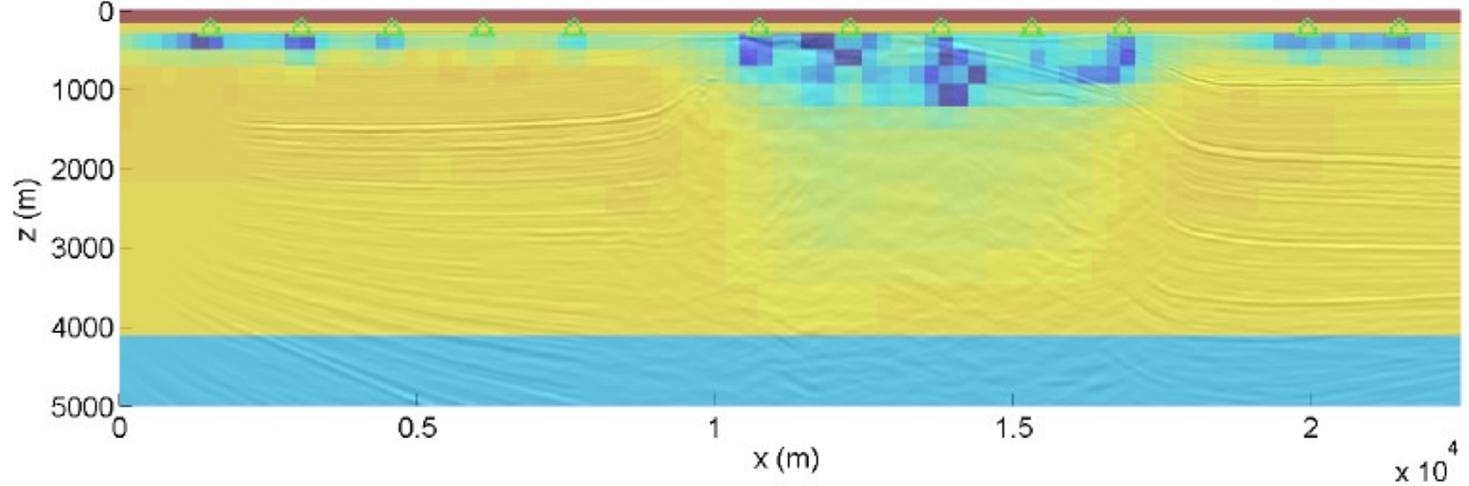


Joint inversion of CSEM and MT data

Joint horizontal

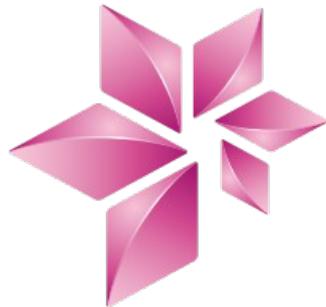


Joint vertical



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Statoil

GDF SUEZ

Literature

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$$\mathbf{R}_z = \begin{pmatrix} \cos(\theta) & -\sin(\theta) & 0 \\ \sin(\theta) & \cos(\theta) & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\mathbf{R}_y = \begin{pmatrix} \cos(\alpha) & 0 & -\sin(\alpha) \\ 0 & 1 & 0 \\ \sin(\alpha) & 0 & \cos(\alpha) \end{pmatrix}$$

$$\mathbf{R}_x = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos(\beta) & -\sin(\beta) \\ 0 & \sin(\beta) & \cos(\beta) \end{pmatrix}$$

$$\begin{pmatrix} H_x \\ H_y \\ H_z \end{pmatrix} = \mathbf{R}_z(\theta)\mathbf{R}_y(\alpha)\mathbf{R}_x(\beta) \begin{pmatrix} H_x \\ H_y \\ H_z \end{pmatrix}$$

