

# Time-lapse full waveform inversion: Synthetic and real data examples

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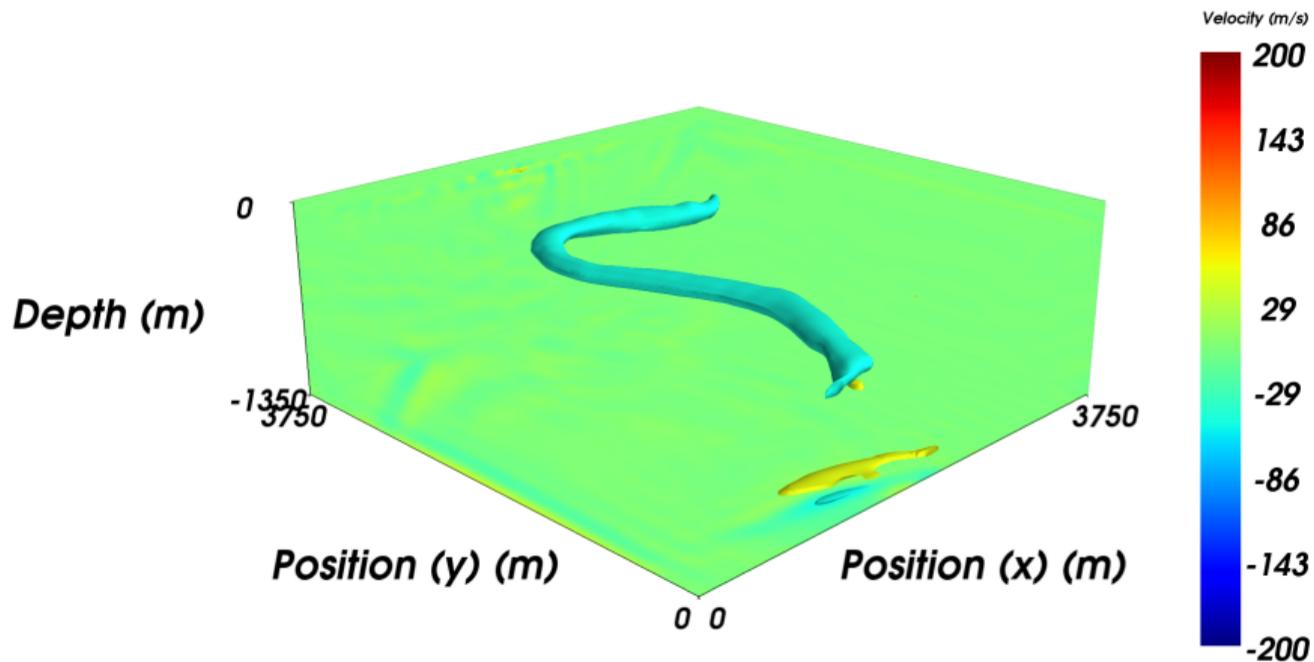
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**NTNU – Trondheim**  
Norwegian University of  
Science and Technology

# Time-lapse Image



## Background

- During the last decade full waveform inversion has proven to be a promising method for parameter model estimation
- Increase in computational power leads to an increase in problem size
- We are now able to do inversion using elastic theory
- In a time-lapse setting, full waveform inversion yields results in the model domain, compared to conventional methods that yield results in the time domain
- Different approaches for performing time-lapse FWI exist in the literature

## Objectives

- Apply elastic full waveform inversion on time-lapse data
- Investigate behavior of full waveform inversion in a time-lapse setting using different streamer geometries
- Investigate different time-lapse approaches using full waveform inversion
- Apply the approaches on both synthetic and real datasets

# Outline

## Methodology

Time-lapse full waveform inversion

## Examples

Synthetic examples

Real example

3D synthetic example

## Conclusions

## Acknowledgments

# A Quick Overview of Full Waveform Inversion

## Overall Goal

*Find an Earth model from which it is possible to create synthetic data that is close to some measured data*

Define  $S(\mathbf{m})$  as the measure between synthetic and measured data. FWI is then the problem

$$\arg \min_{\mathbf{m}} S(\mathbf{m})$$

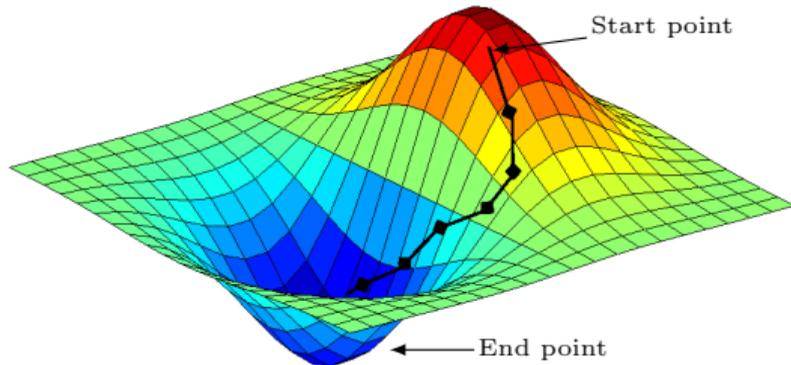
Solved using an iterative method

$$\mathbf{m}_{k+1} = \mathbf{m}_k - \alpha_k \mathbf{g}_k,$$

$\mathbf{m}_k$  model at iteration  $k$

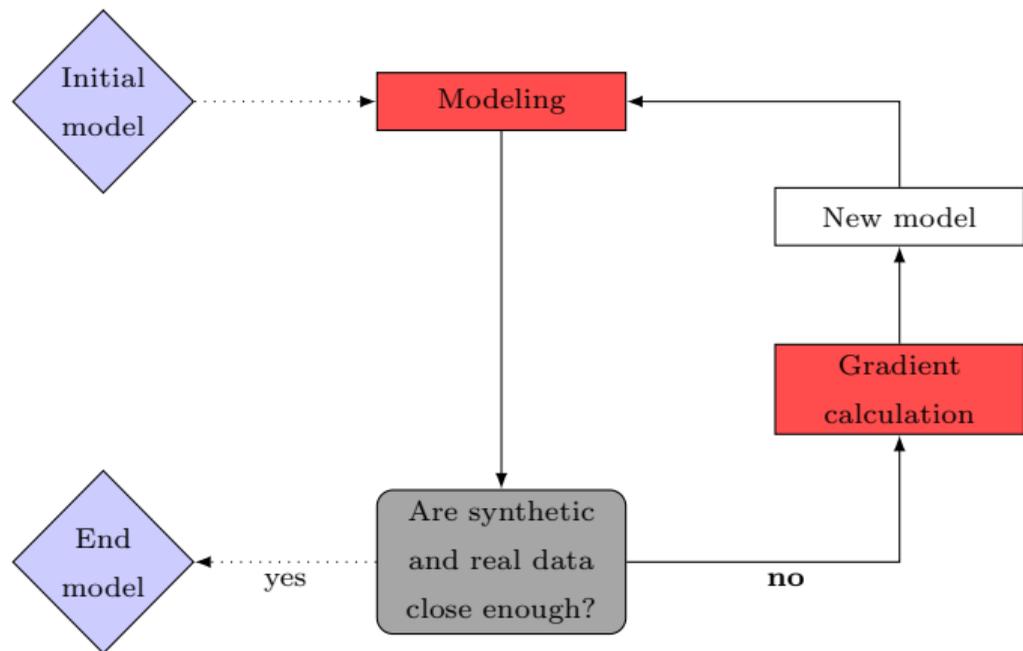
$\mathbf{g}_k$  gradient of  $S(\mathbf{m})$  at iteration  $k$

$\alpha_k$  step length at iteration  $k$



## Schematic View of FWI

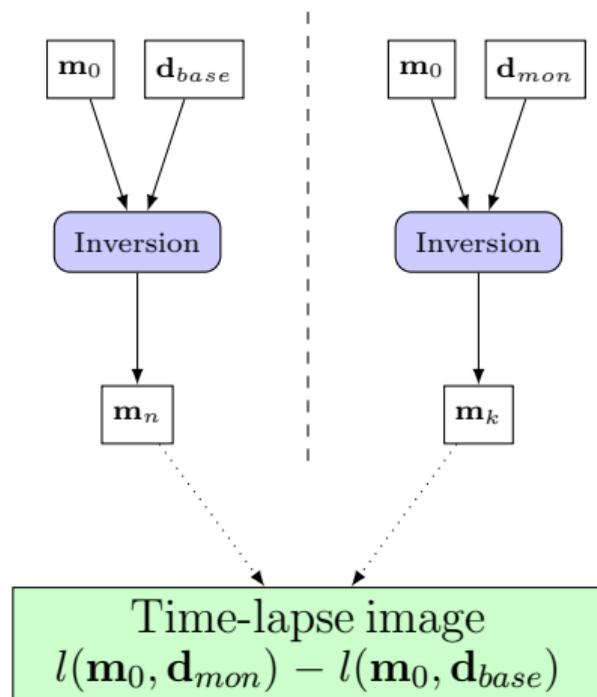
- Modeling using a staggered grid finite difference method
- Parallelized on a shot-by-shot basis
- Minimization algorithm is L-BFGS



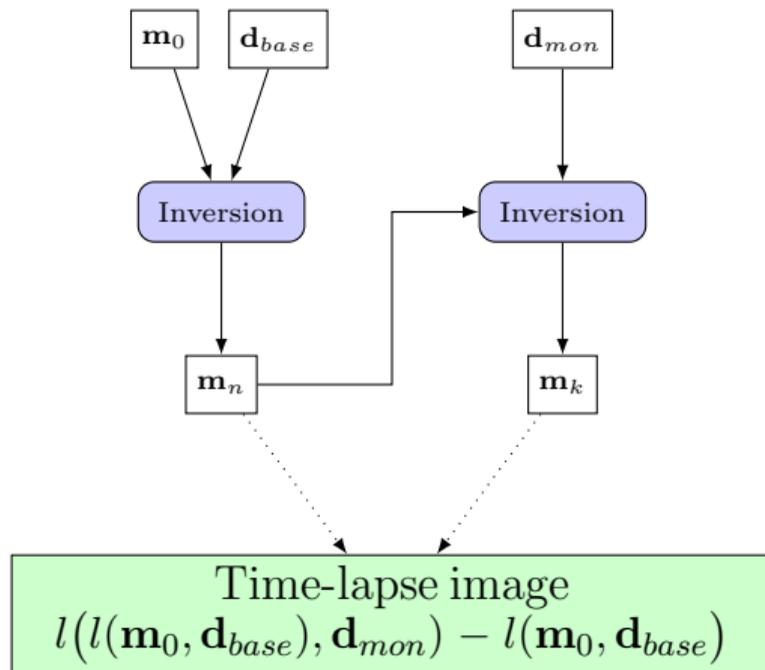
Synchronization

In parallel

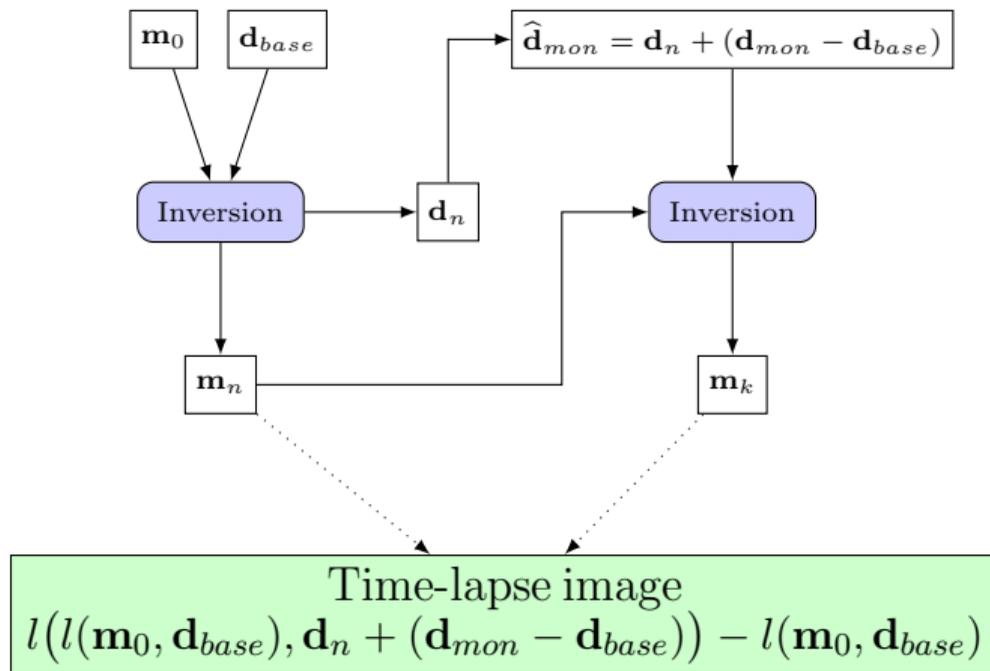
## Time-lapse FWI: Approach 1



## Time-lapse FWI: Approach 2

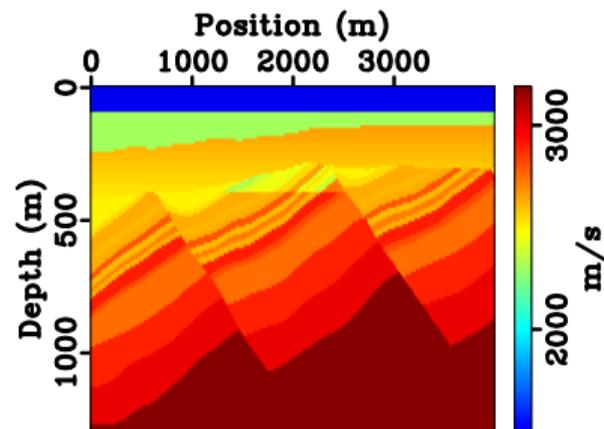
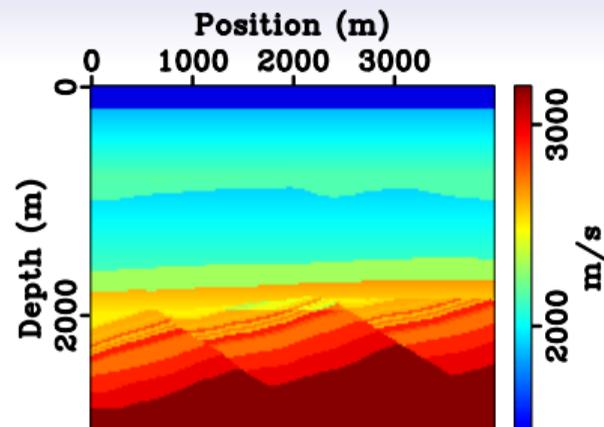


## Time-lapse FWI: Approach 3



## Synthetic examples

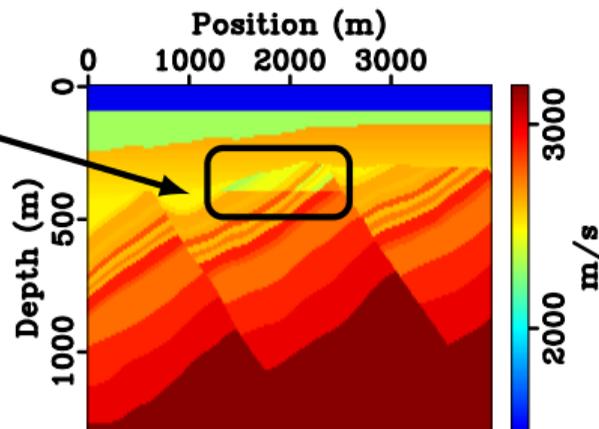
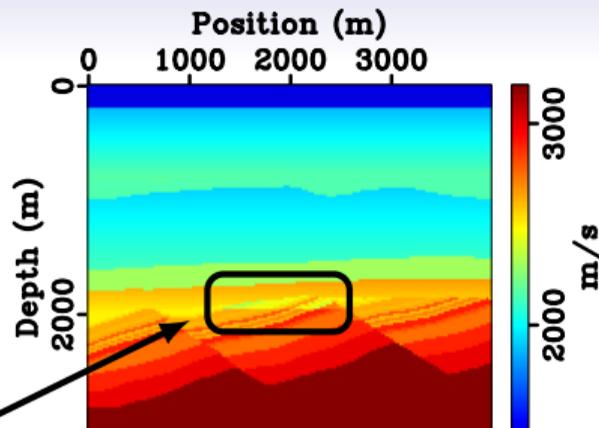
- Two test cases:
  - Deep model with 6 km streamer length
  - Shallow model with 1.2 km streamer length
- Reservoir acts as time-lapse anomaly
- Identical surveys acquired for baseline and monitor models



## Synthetic examples

### Reservoir:

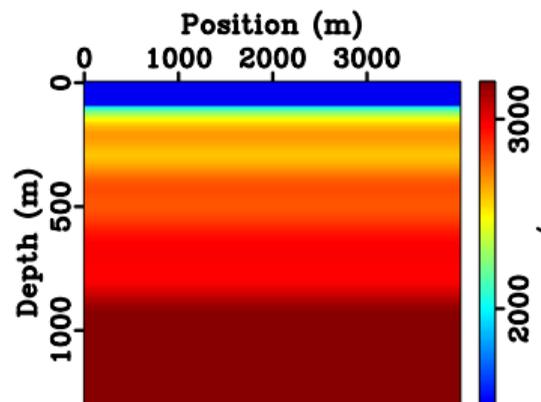
- 1000 m wide, 100 m deep
- Baseline: oil filled
- Monitor: water filled
- P-wave changes:  $-153 - 0$  m/s



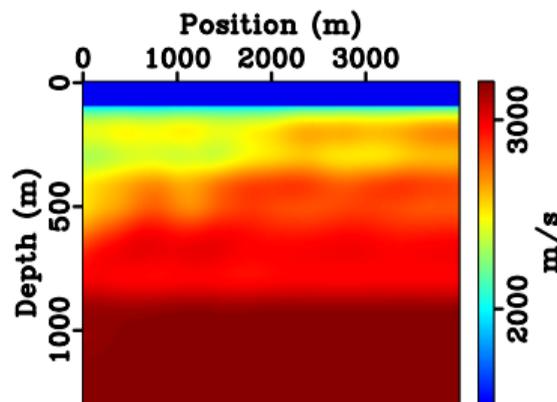
baseline and monitor models

## Workflow for synthetic examples

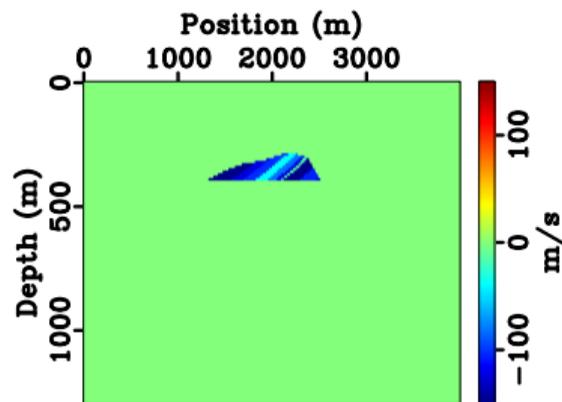
- Using WEMVA for creating initial models for FWI [Weibull et al., 2012]
- Elastic modeling and inversion
- Inverting for P-wave velocities, no updates for S-wave velocities and density



Initial model for WEMVA

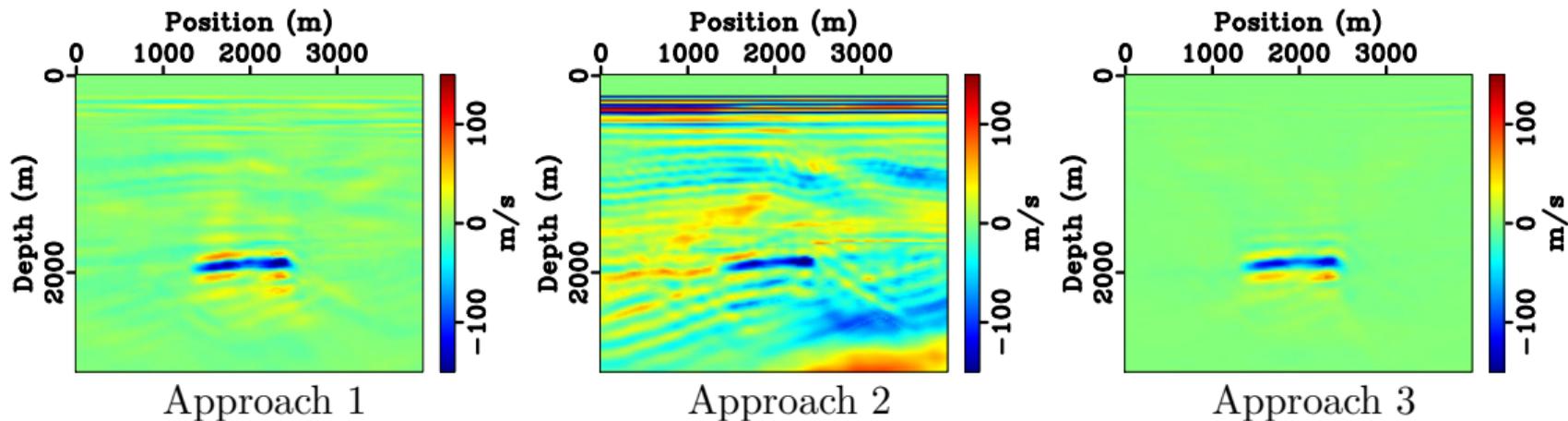


Initial model for FWI

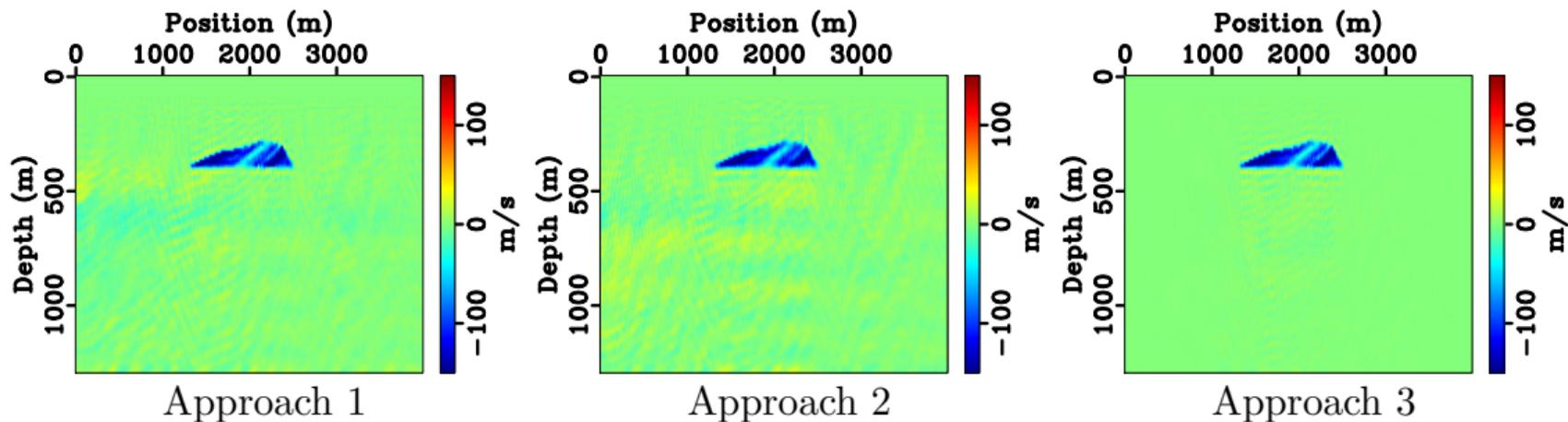


True time-lapse effect  
(shallow model)

## Time-lapse images: long streamer

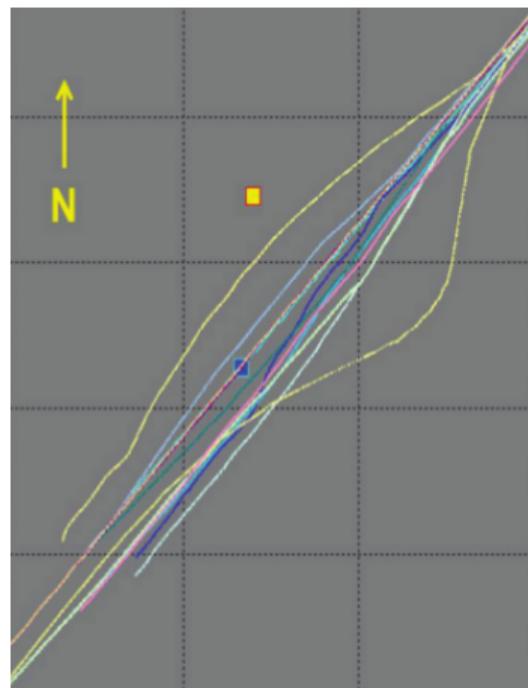


## Time-lapse images: short streamer



## Real example

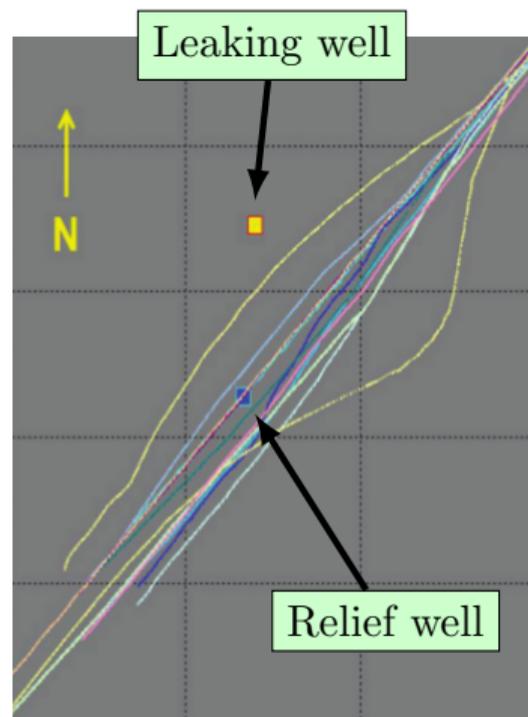
- Time-lapse data from the Norwegian North Sea
- Base dataset acquired in 1988 and monitor dataset in 1990
- Between the dataset the field was exposed to a subsurface gas leakage in one of the producing wells
- Marine streamer survey: 230 shots and 1253 m streamer length
- Streamer: 95 receivers separated by 12.5 m



Ref: [Landrø,2011]

## Real example

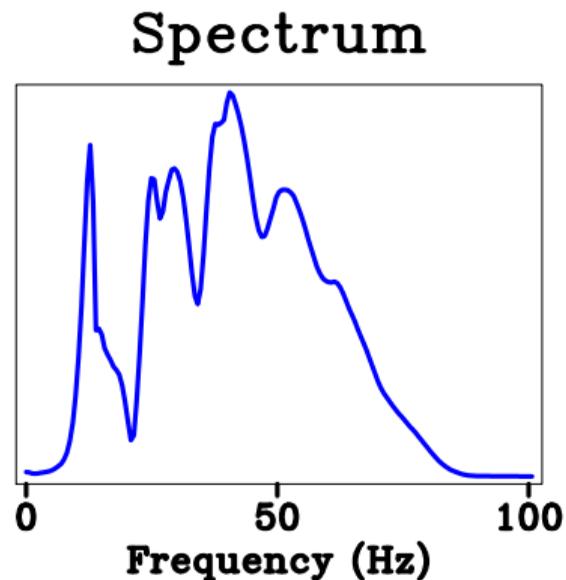
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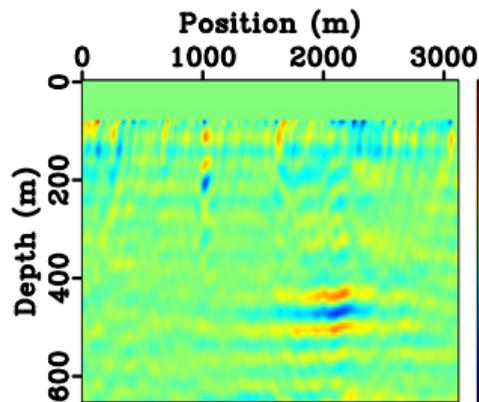
Ref: [Landrø,2011]

## Workflow for real example

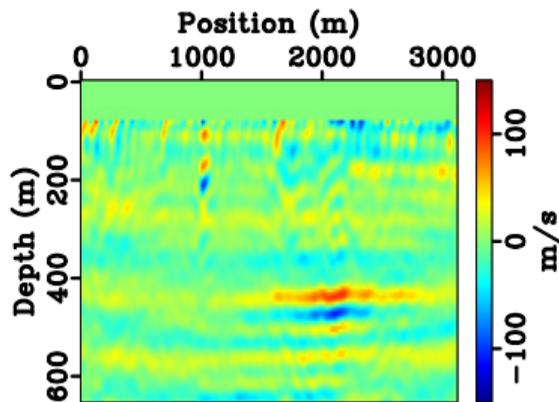
- Data is regularized into a identical grid using linear interpolation
- Bandpass filter (2-20 Hz) is applied
- Grid cells with grid spacing 6.25 m is used
- Initial model estimated using WEMVA
- Source is estimated using FWI keeping parameter models constant
- Inverting for P-wave velocities, linking S-wave velocities and densities using empirical relations



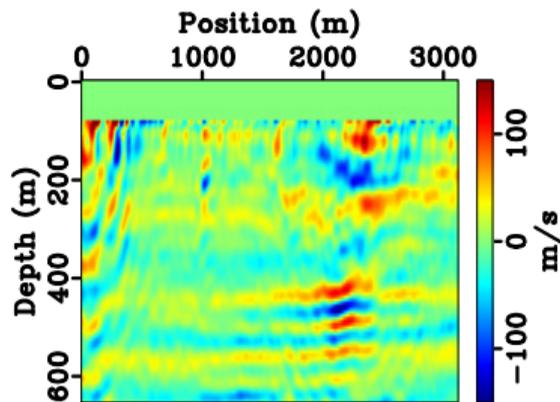
## Time-lapse images: Real example



Approach 1

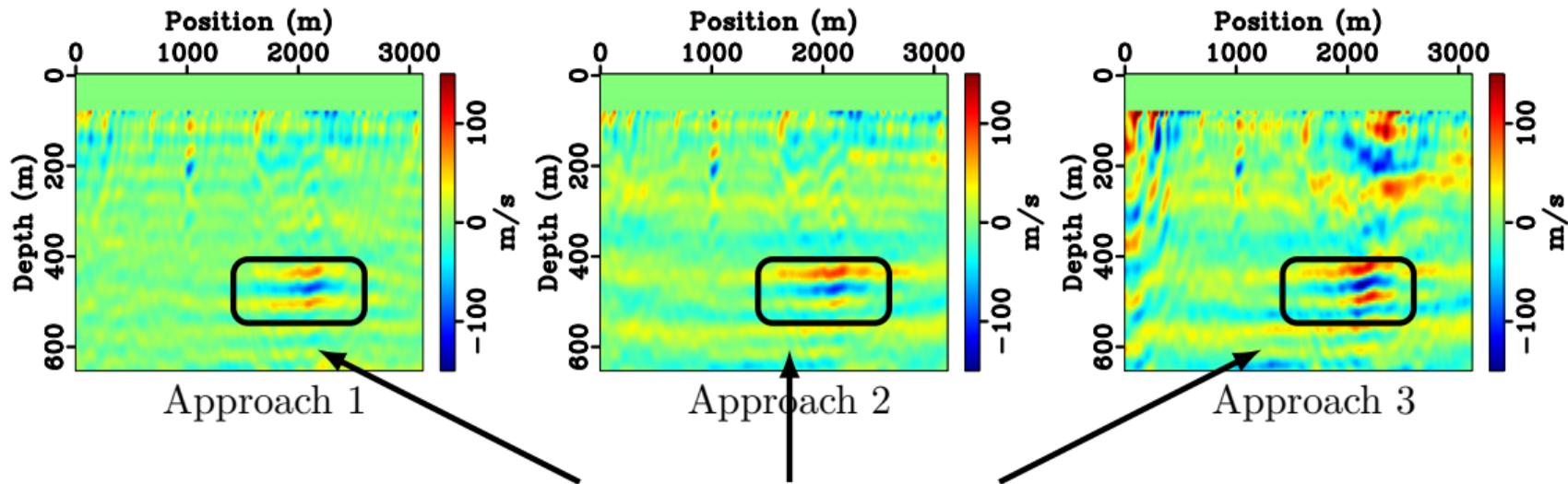


Approach 2



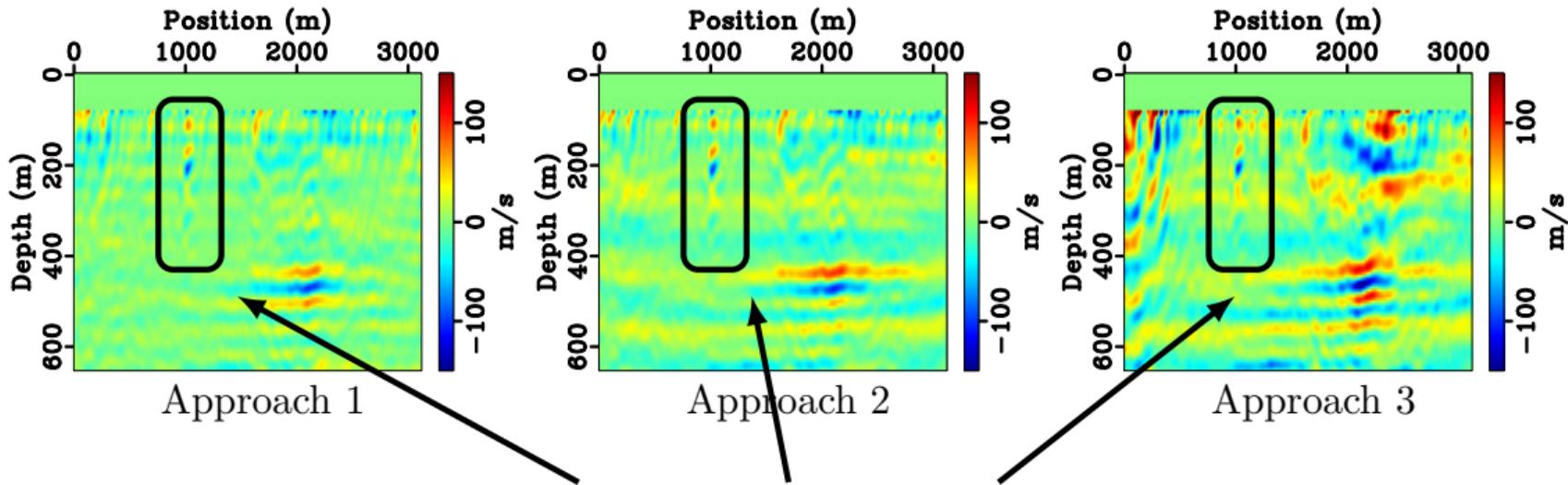
Approach 3

## Time-lapse images: Real example



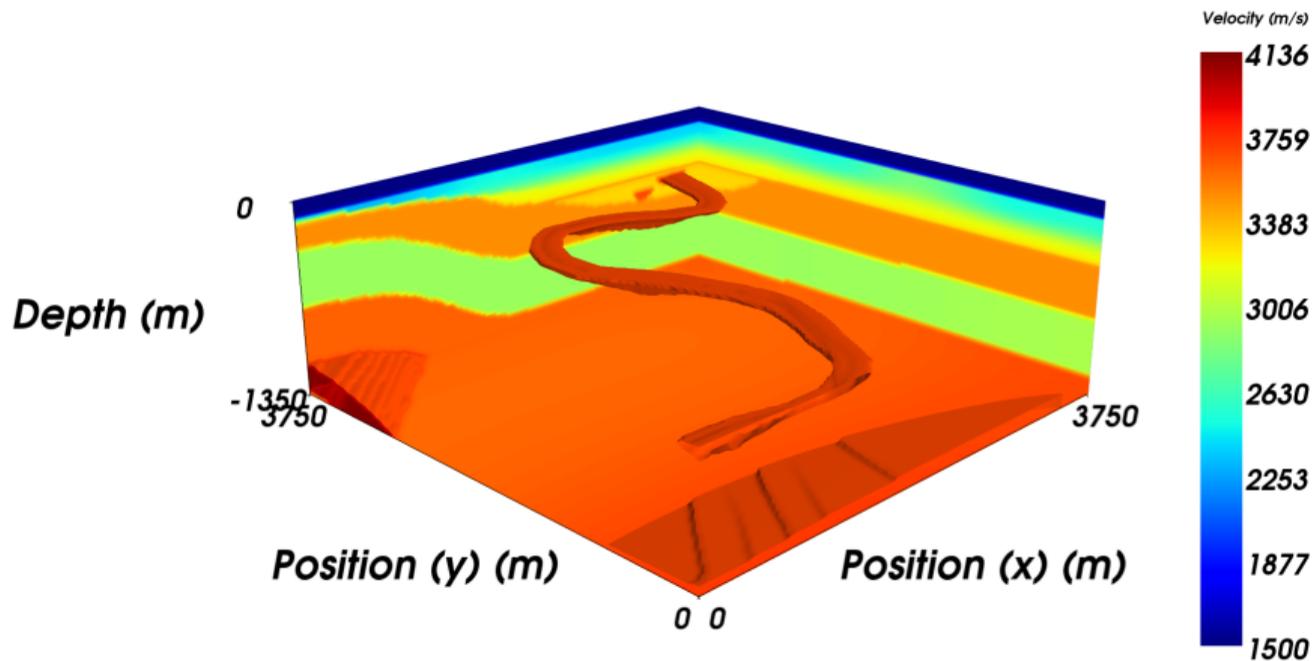
Well-known time-lapse effect:  
Gas leaked into a sand layer at this depth

## Time-lapse images: Real example



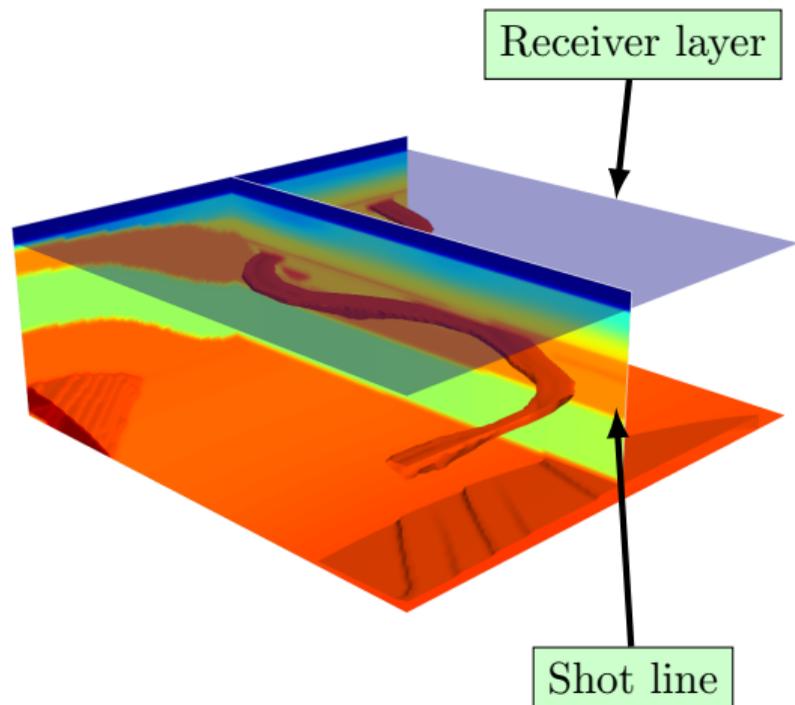
The relief well was drilled at this position:  
Is the well visible?

## 3D synthetic example

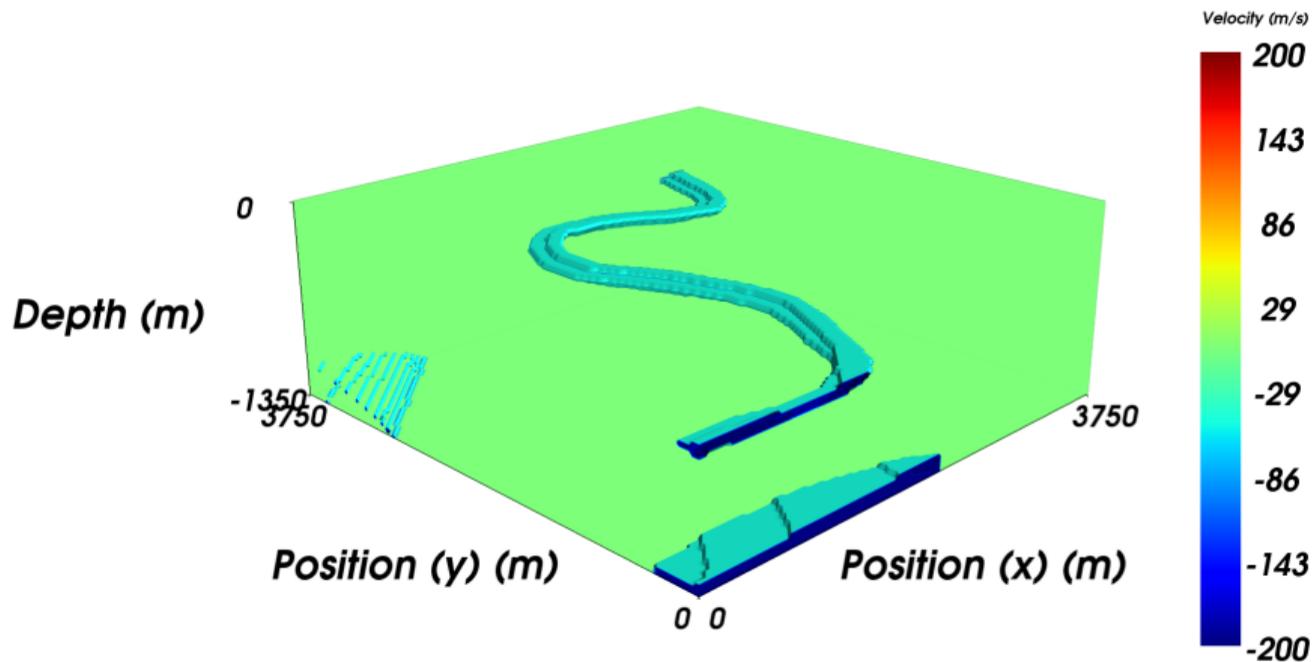


## FWI setup

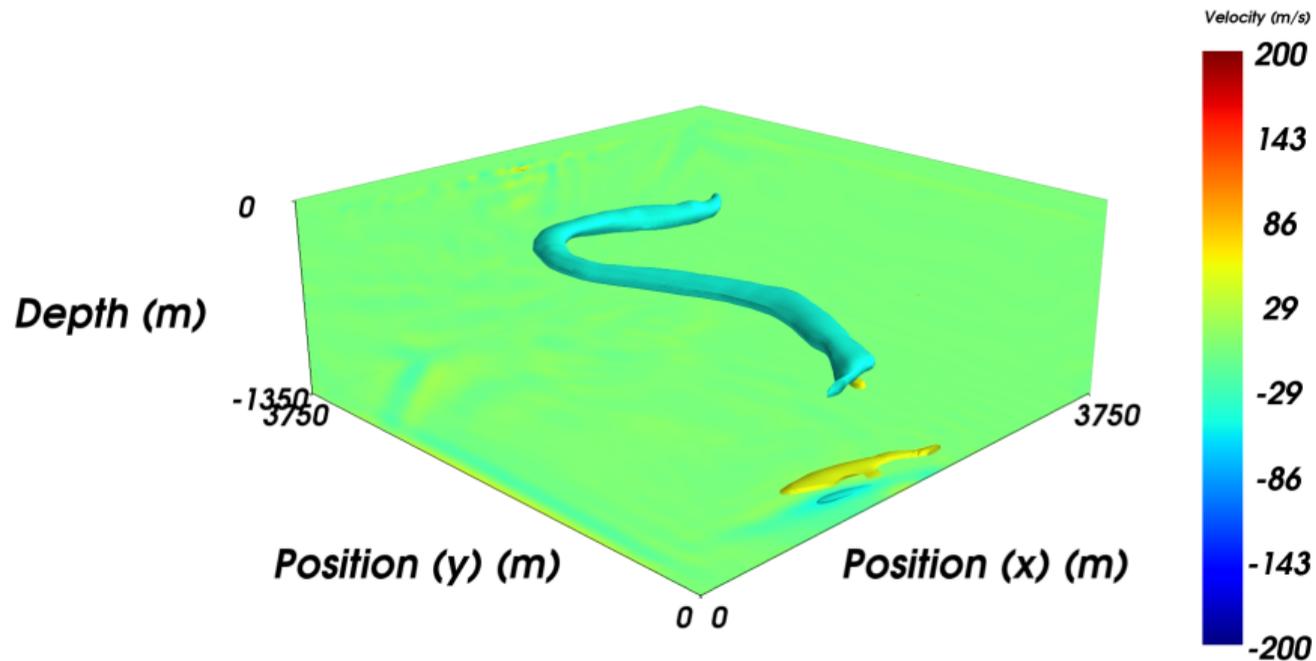
- Grid spacing: 25 m
- Receivers in every grid point in a layer in water column
- 72 shots along a line on y-axis in the middle of the model
- Ricker wavelet with center frequency 5.0 Hz



# True 3D time-lapse effect



## Inverted 3D time-lapse effect



## Conclusions

- Full waveform inversion are able to reveal time-lapse effects
- Time-lapse artifacts are dependent on receiver and source geometries, and depth
- Difficult to make a conclusion on which of the approaches that is the best
- We are able to detect already known time-lapse effects on the real dataset
- Promising synthetic time-lapse result in three dimensions

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