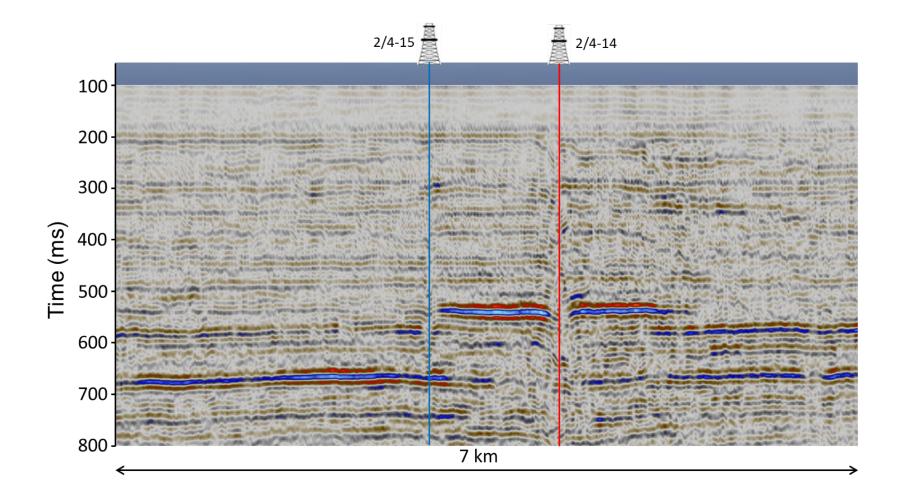
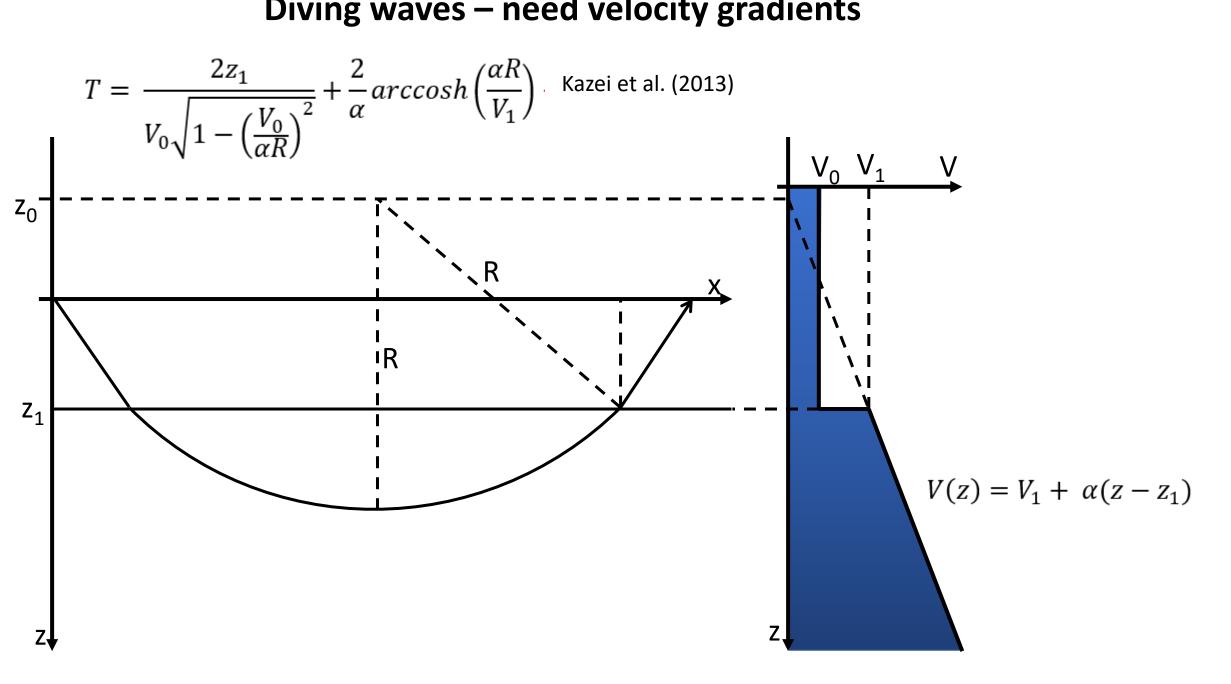
Using diving waves for time-lapse seismic studies and overburden characterization

Bjarte Foseide, NTNU Izzie Yi Liu, NTNU Martin Landrø, NTNU

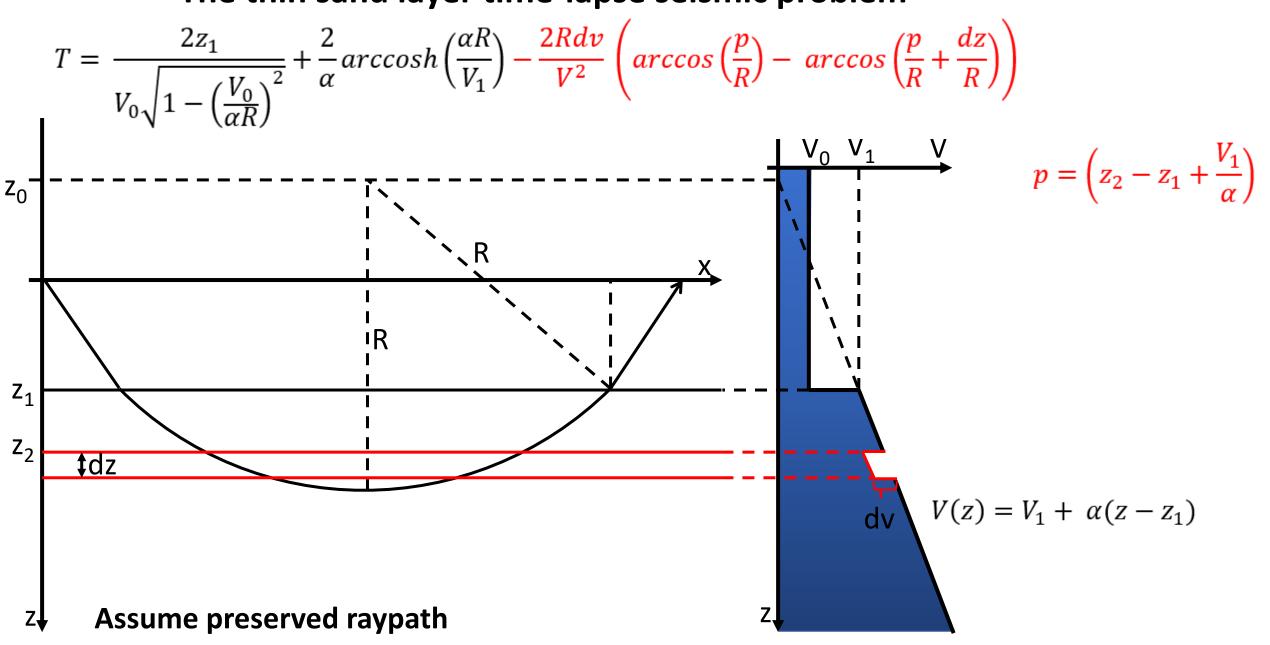
Underground blowout -2/4-14



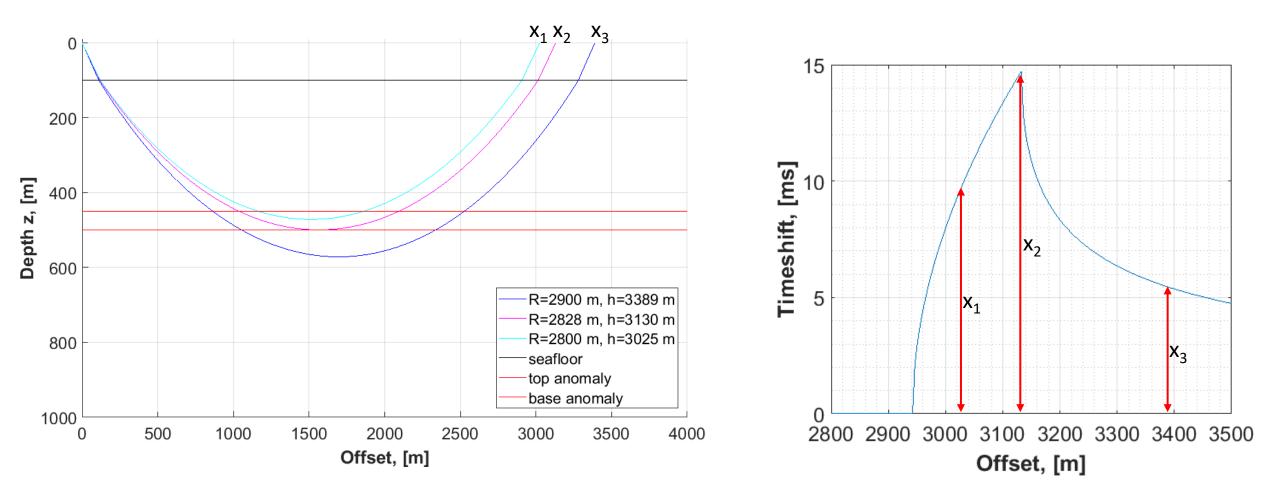
Diving waves – need velocity gradients



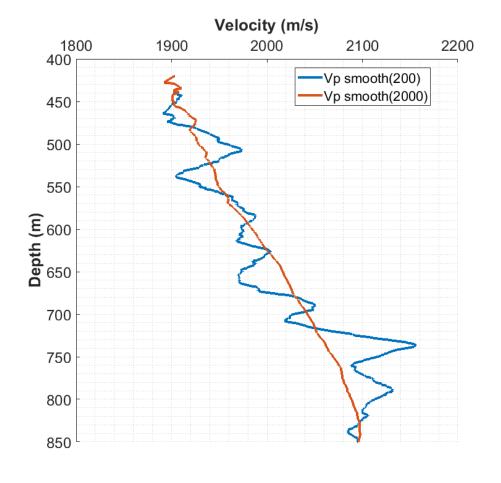
The thin sand layer time-lapse seismic problem



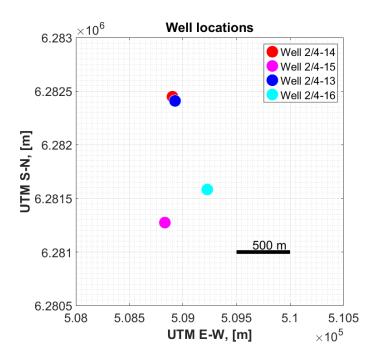
Raypath of diving wave at different offsets and the corresponding timeshift



Velocity log from well 2/4-16

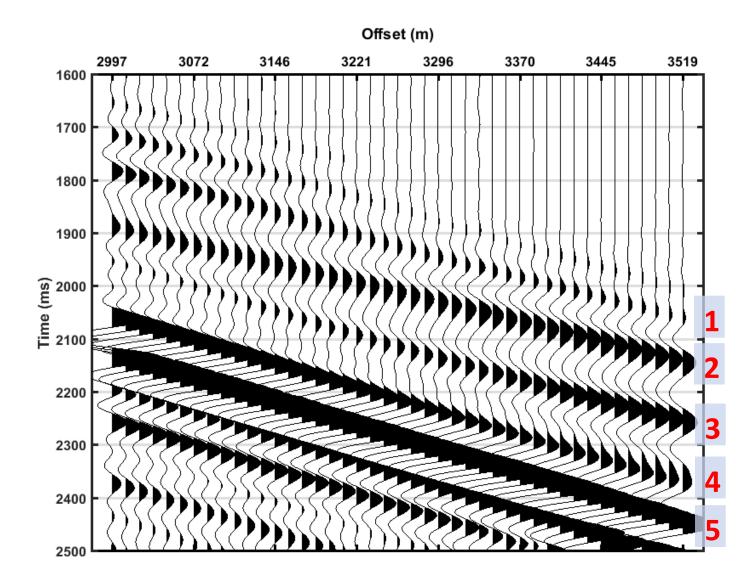


- Velocity log smoothed with a moving average.
- General gradient of 0.6 s⁻¹

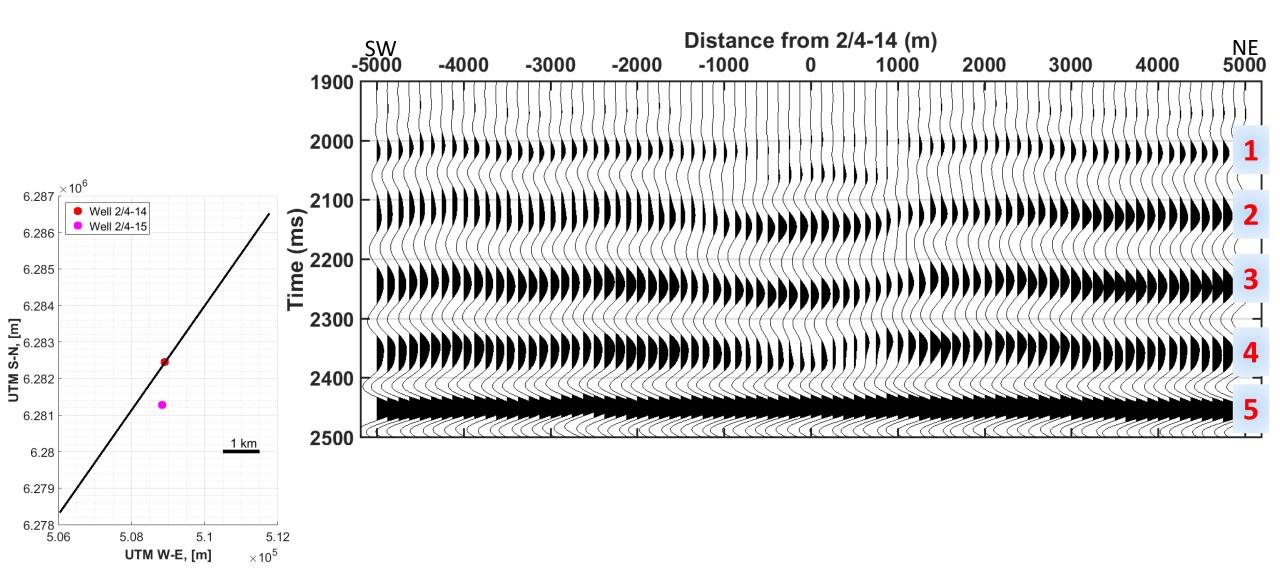


Low-passed shot gather, 2/4-14 field data

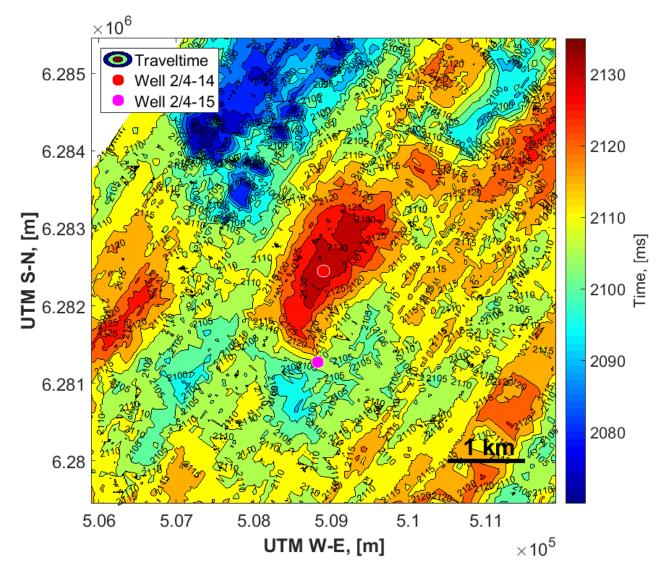
Superpositioning of headwave and diving waves + diving wave multiples gives amplitudes increasing with offset (*Kazei et al. 2013*)



Seismic trace at 3500 m offset

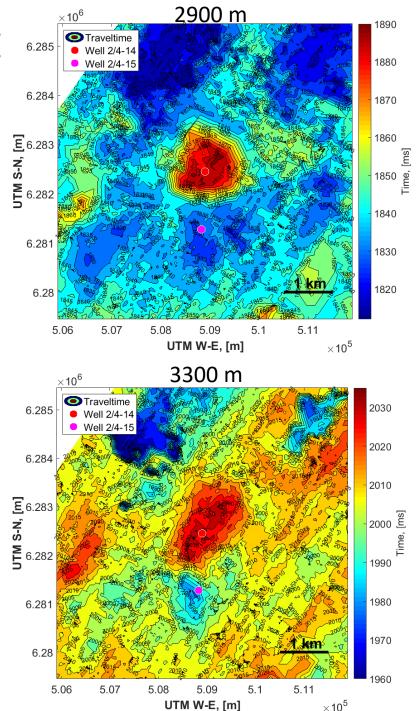


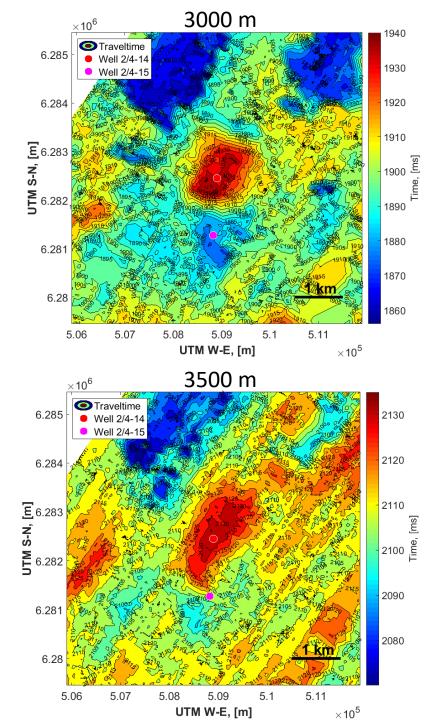
Second event at 3500 meter offset.



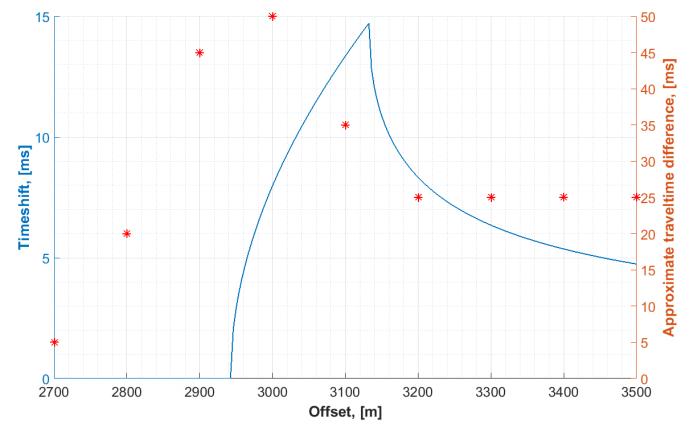
Second event at different offsets

- Start as round shape then get more elongated with higher offset.
- General traveltime difference
 bewteen anomaly
 centre and
 surroundings vary.



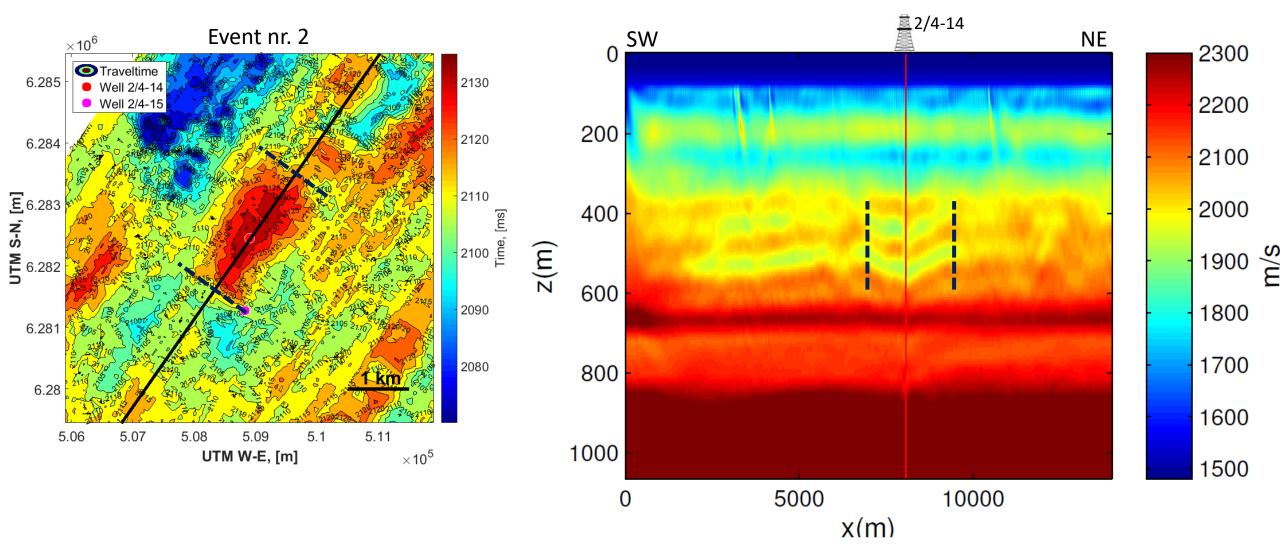


Traveltime differences and timeshifts

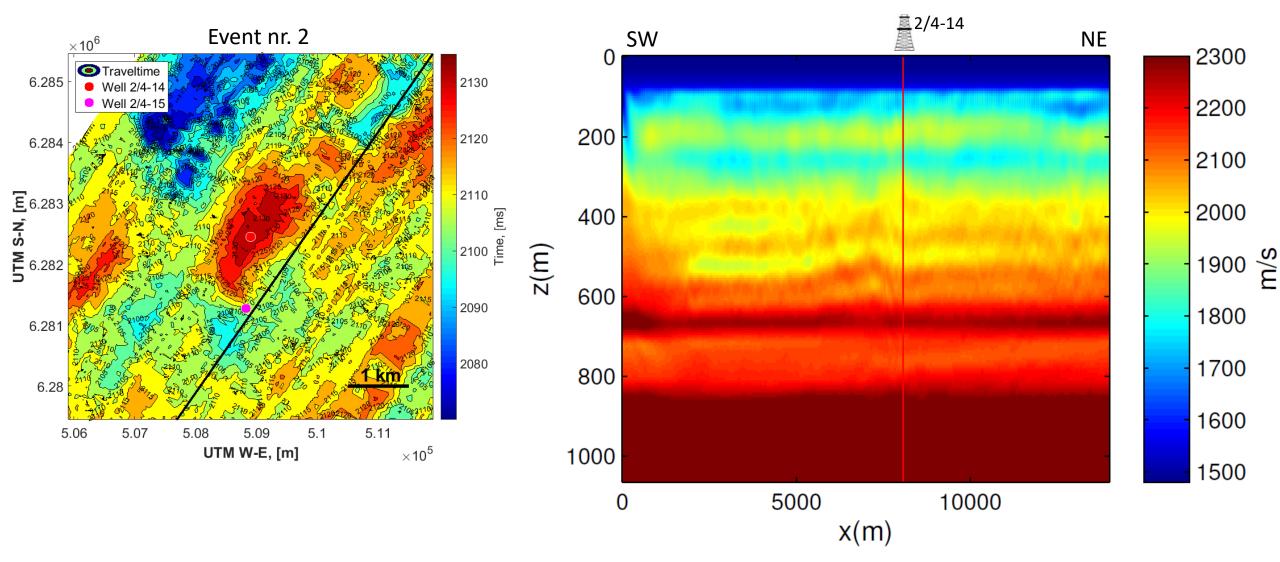


- Traveltime differences for second event.
- Similar behaviour with offset.
- Unrealistically high traveltime differences given the assumptions?

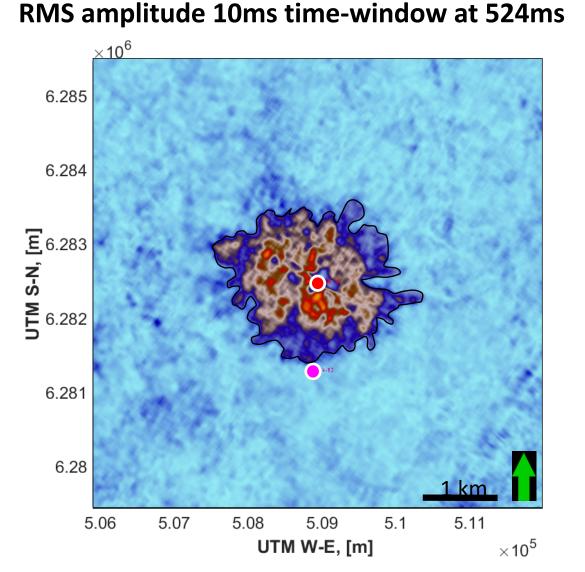
Full Waveform Inversion (preliminary results)

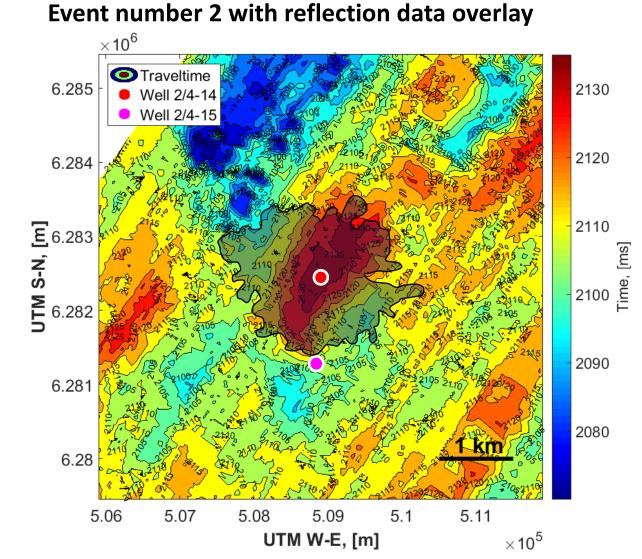


Full Waveform Inversion (perlimenary results)



Comparison with reflection data





Summary and further work

- High offset events, i.e. refractions and diving waves, have information that can be used for monitoring shallow velocity anomalies.
- Diving waves has the potential to be used for time-lapse analysis.
- A simple method of mapping traveltimes of high offset events can give indications of velocity anomalies.
- FWI gives depth estimates. Still under progress.
- Finite difference modeling to better understand 3D and 4D behaviour.

Acknowledgements

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