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Viscoacoustic sensitivity analysis using partial Hessian matrix.

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2 Methodology

3 Results



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- Sensitivity analysis to determine the trade-off between parameters.
 - Two or more variables have similar effects on the data during the inversion.
 - The result depends on the acquisition configuration for each model. [2]

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- For this work a viscoacoustic model has been used.



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$$e(\mathbf{m}) = \frac{1}{2} \int d\mathbf{x}_r \int d\mathbf{x}_s \int dt \left[d^{obs}(\mathbf{x}_r, \mathbf{x}_s, t) - d(\mathbf{x}_r, \mathbf{x}_s, t) \right]^2 \quad (1)$$

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$$\mathbf{m} = [\alpha(\mathbf{x}), Q(\mathbf{x})] \rightarrow \text{model parameter.}$$

 $\mathbf{m}_0 \rightarrow \text{initial model.}$

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 The estimate Δm̂ is related to the true parameter estimate perturbation Δm via [1]

$$\Delta \hat{m}(x) = \alpha \int d\mathbf{x}' \mathbf{H}(\mathbf{x}, \mathbf{x}') \Delta \mathbf{m}(\mathbf{x}'),$$
 (2)

 The approximate Hessian can be expressed in terms of the Modeling operator J [4]

$$\mathbf{H}(\mathbf{x}, \mathbf{x}') = \int dt \int dS(\mathbf{x}_s) \int dS(\mathbf{x}_r) \mathbf{J}(\mathbf{x}_r, \mathbf{x}, t) \mathbf{J}(\mathbf{x}_r, \mathbf{x}', t), \quad (3)$$

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 The modeling operator provides a linear relation between Δm and Δd [3, 5]

$$\Delta d(\mathbf{x}_r \mathbf{x}_s, t) = \int d\mathbf{x}' \mathbf{J}(\mathbf{x}_r, \mathbf{x}', t) \Delta \mathbf{m}(\mathbf{x}'), \tag{4}$$

 \mathbf{J} is defined as $\mathbf{J} = [J_{\alpha}, J_Q]$.

Re-expressing the Hessian

$$H^{ij}(x,x') = \int d\omega \int ds(x_s) \int ds(x_r) J^i(x_r,x,\omega) J^j(x_r,x',\omega)$$
 (5)

Introduction Methodology Results Conclusions References

Re-expressing the Hessian

$$H^{ij}(x,x') = \int d\omega \int ds(x_s) \int ds(x_r) J^i(x_r,x,\omega) J^j(x_r,x',\omega)$$
 (5)

For this case of study

$$\mathbf{H} = \begin{bmatrix} H^{\alpha\alpha} & H^{\alpha Q} \\ H^{Q\alpha} & H^{QQ} \end{bmatrix}$$
(6)

The parameter estimates are:

$$\widehat{\Delta \alpha} = H^{\alpha \alpha} \Delta \alpha + H^{\alpha Q} \Delta Q \tag{7}$$

$$\widehat{\Delta Q} = H^{Q\alpha} \Delta \alpha + H^{QQ} \Delta Q. \tag{8}$$

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$$\alpha = \sqrt{\frac{M}{\rho}} \qquad M = M_0 \left| \frac{\omega}{\omega_0} \right|^{2\gamma} e^{i\pi\gamma \text{sgn}(\omega)}$$
$$\gamma = \frac{1}{\pi} \arctan\left(\frac{1}{Q}\right) \qquad c = \sqrt{\frac{M_0}{\rho}}$$
$$M_0 = \rho c_0^2 \cos^2\left(\frac{\pi\gamma}{2}\right)$$

The specific model parameters can be obtained by using

$$\begin{split} \mathbf{J}^{c} &= \mathbf{J}^{\alpha}(\mathbf{x}_{r}, \mathbf{x}, \omega) \left(\frac{\partial \alpha}{\partial c}\right), \\ \mathbf{J}^{Q} &= \mathbf{J}^{\alpha}(\mathbf{x}_{r}, \mathbf{x}, \omega) \left(\frac{\partial \alpha}{\partial Q}\right). \end{split}$$

The specific model parameters can be obtained by using

$$\mathbf{J}^{c} = \mathbf{J}^{\alpha}(\mathbf{x}_{r}, \mathbf{x}, \omega) \left(\frac{\partial \alpha}{\partial c}\right),$$
$$\mathbf{J}^{Q} = \mathbf{J}^{\alpha}(\mathbf{x}_{r}, \mathbf{x}, \omega) \left(\frac{\partial \alpha}{\partial Q}\right).$$

Where

$$J^{\alpha} = \frac{\eta \exp\left[\frac{\omega r 1}{c_0 \epsilon} \left(-\tan(\xi/2) + i\left(1 + \frac{\xi c_o \epsilon}{2\omega r_1}\right)\right)\right]}{c_0 \cos\left(\frac{\xi \epsilon}{2}\right)}.$$
 (9)

Where,
$$r_1 = r + r_s$$
, $\epsilon = \left|\frac{\omega}{\omega_0}\right|^{\xi/\pi}$, $\xi = \arctan\left(\frac{1}{Q}\right)$, $\eta = -\frac{2\omega^2}{rr_s}$



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The expressions of the Hessian are

$$H^{cc} = \int d\omega \int ds(x_s) \int ds(x_r) \frac{\eta \eta' s(\omega) s^*(\omega)}{c_0^2} \Lambda$$
(10)

$$H^{cQ} = \int \int \int \frac{\kappa}{c_0} \left[\frac{1}{2} \tan\left(\frac{\xi}{2}\right) - \frac{1}{\pi} \ln\left|\frac{\omega}{\omega_0}\right| + \frac{i}{2} \right] \Lambda$$
(11)

$$H^{Qc} = \int \int \int \frac{\kappa}{c_0} \left[\frac{1}{2} \tan\left(\frac{\xi}{2}\right) - \frac{1}{\pi} \ln\left|\frac{\omega}{\omega_0}\right| - \frac{i}{2} \right] \Lambda$$
(12)

$$H^{QQ} = \int \int \int \frac{\kappa}{Q^2 + 1} \left[\frac{1}{4} \tan^2 \left(\frac{\xi}{2} \right) - \frac{1}{\pi} \tan \left(\frac{\xi}{2} \right) \ln \left| \frac{\omega}{\omega_0} \right| + \frac{1}{4} \right] \Lambda,$$
(13)

where,
$$R = r' + r'_s - r - r_s$$
, $\xi = \arctan\left(\frac{1}{Q}\right)$, $\kappa = \frac{\eta \eta' s(\omega) s^*(\omega)}{Q^2 + 1}$,
 $\eta = -\frac{2\omega^2}{rr_s}$, $\eta' = -\frac{2\omega^2}{r'r'_s}$, $\Lambda = \exp\left[\frac{i\omega R}{c_0 \left|\frac{\omega}{\omega_0}\right|^{\xi/\pi}}\right] \exp\left[\frac{-\omega R \tan\left(\frac{1}{2}\xi\right)}{c_0 \left|\frac{\omega}{\omega_0}\right|^{\xi/\pi}}\right]$.

Acquisition model



Homogeneous model with a perturbation at the center.

Reflection experiment



No trade-off between parameters. No attenuation Q = 10,000.

Reflection experiment



Hessian with high attenuation, Q = 10.

Reflection experiment



Hessian with low attenuation, Q = 50.

Transmission experiment



No trade-off between parameters. No attenuation, Q = 10,000.

Transmission experiment



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Hessian with low attenuation, Q=50.



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- It is not possible under this model and parametrization to distinguish between the effects of the perturbations of the parameters of the model in the inversion.
- This results can be extrapolated to viscoelasticity.

Acknowledgments



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