

FULL WAVEFORM AMBIENT NOISE INVERSION

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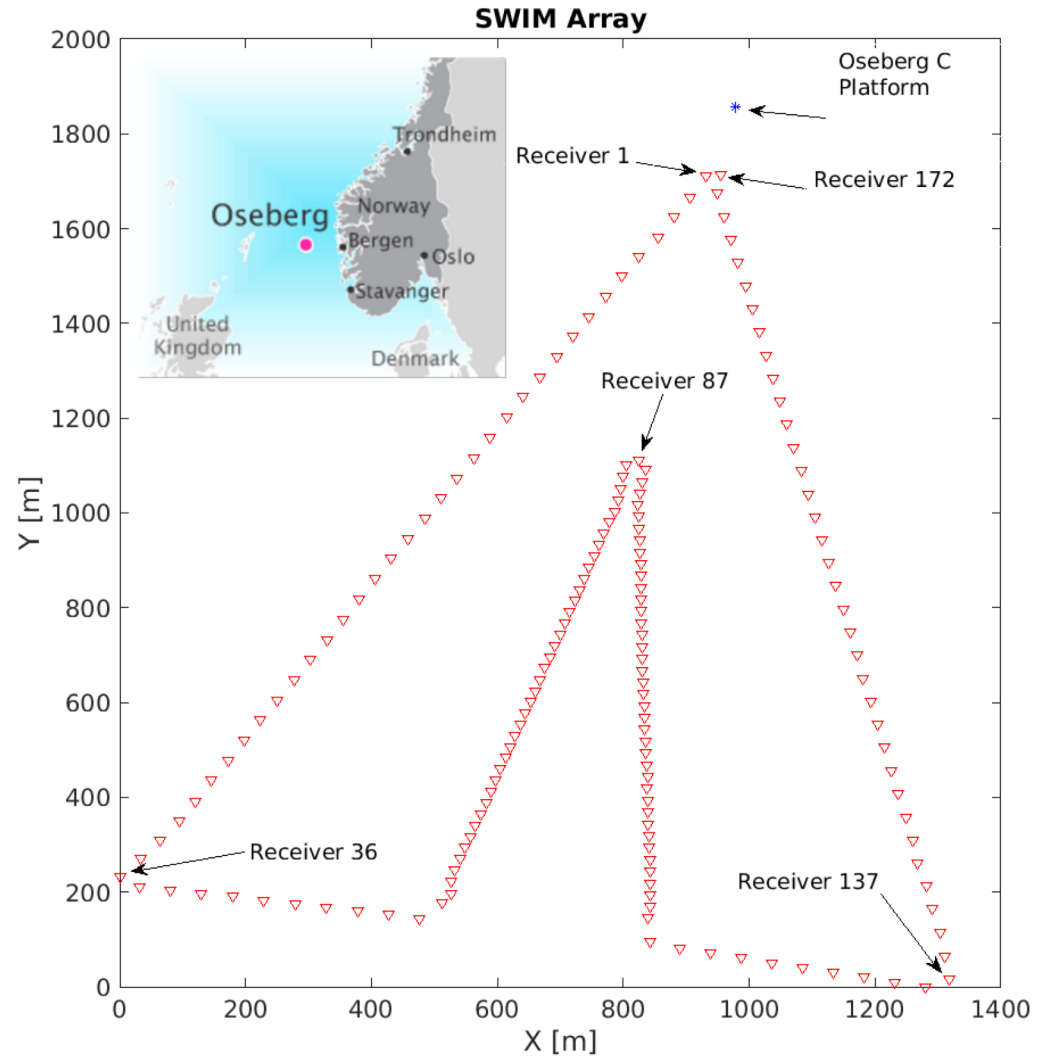
Evan Delaney

Statoil

Andreas Fichtner

ETH Zurich

AMBIENT NOISE AT THE OSEBERG ARRAY

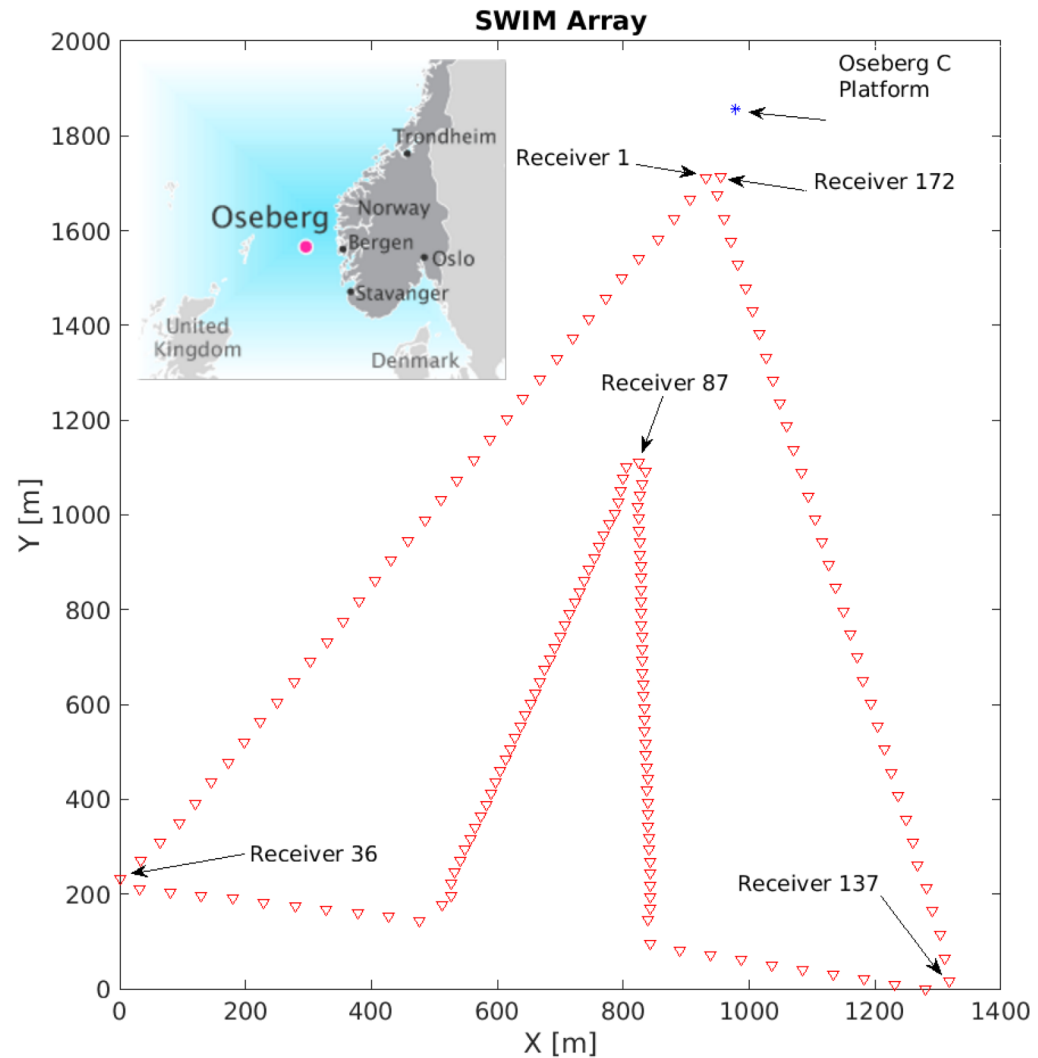


Delaney et al. (2017)

Goal:

- Overburden monitoring
- Using ambient seismic noise
- With high temporal resolution [days, hours]

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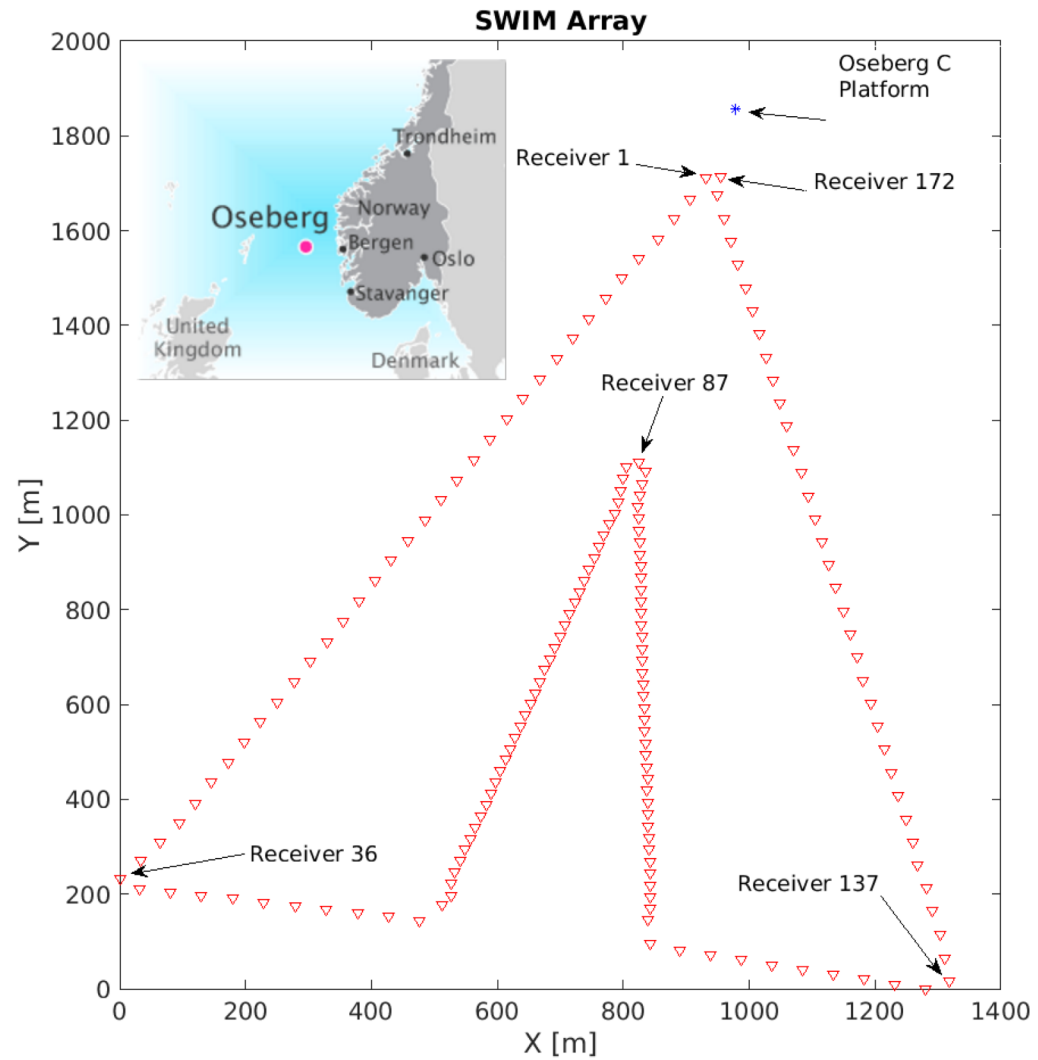
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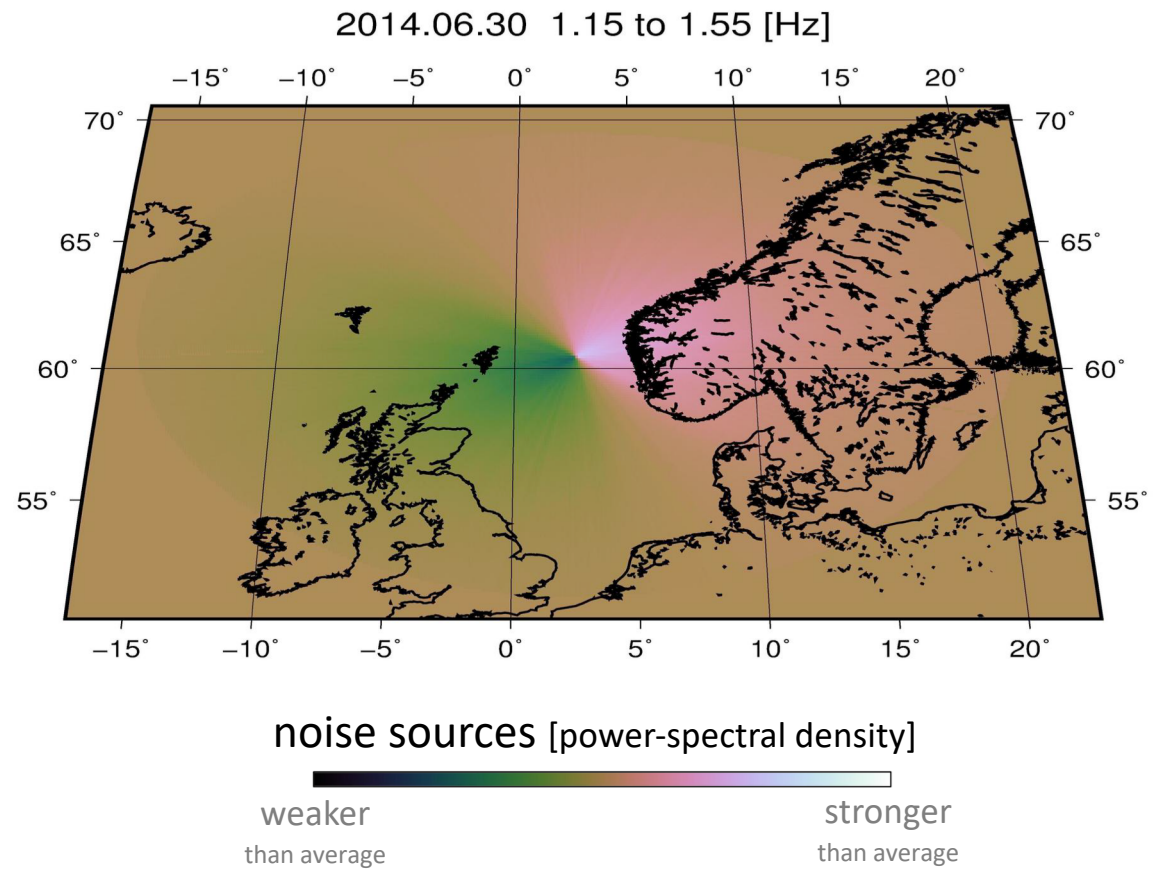
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The challenge is, however, ...

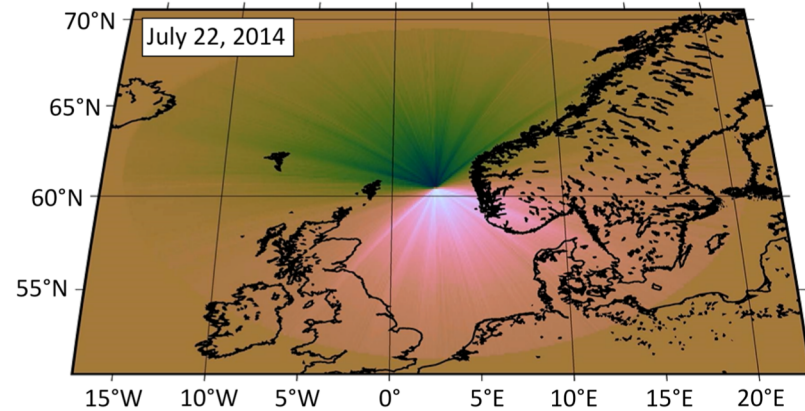
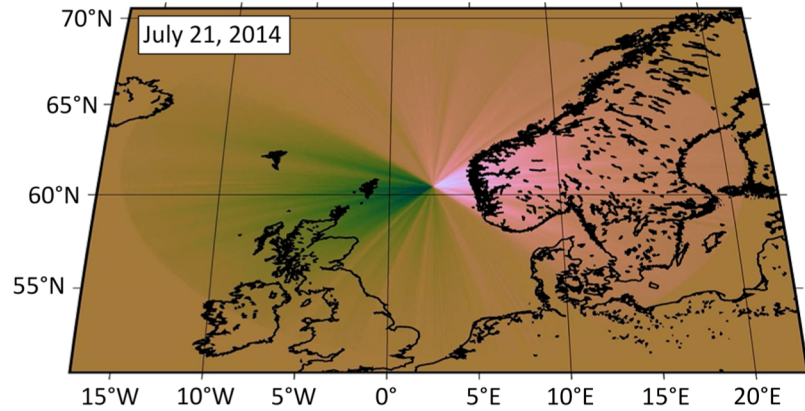
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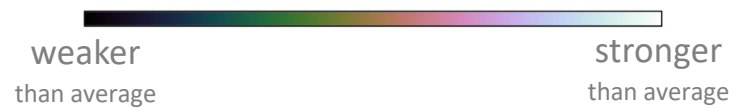
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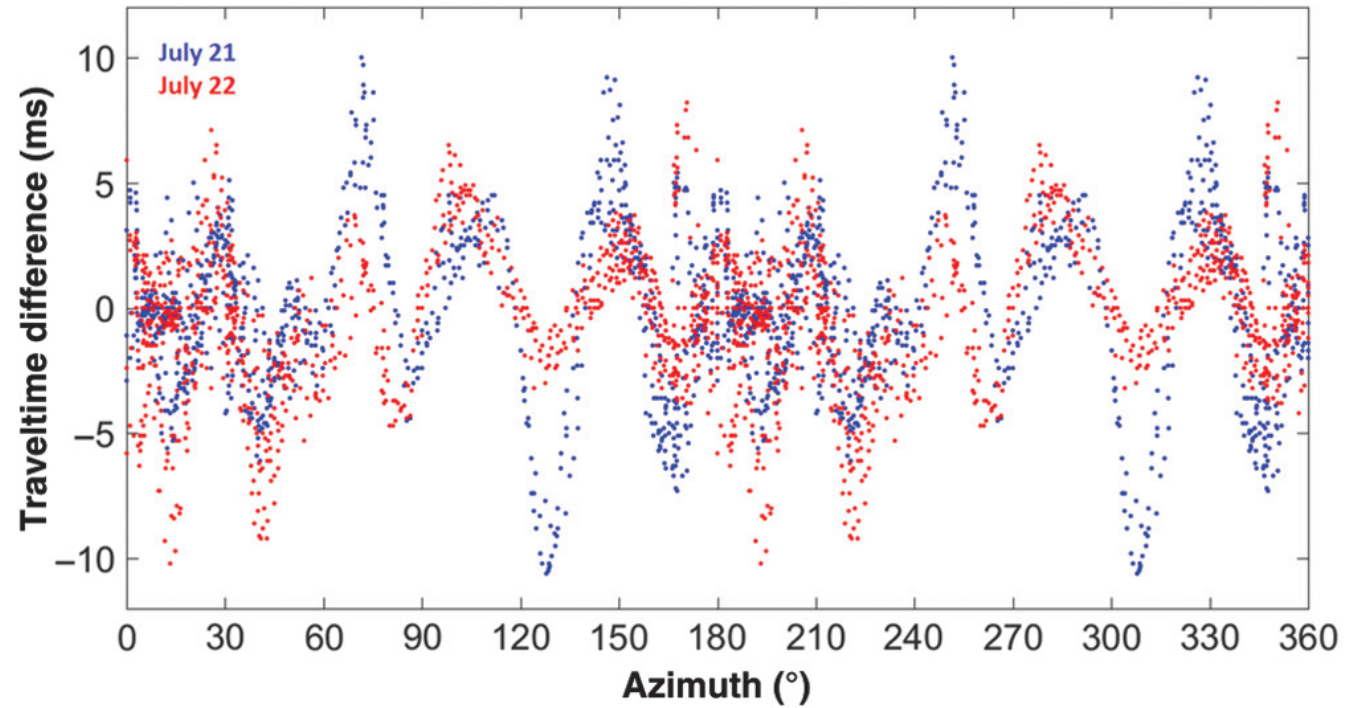
TRAVELTIME BIASES



noise sources [power-spectral density]



Systematic traveltime bias induced by heterogeneous noise source



Delaney et al. (2017)

OBJECTIVES

- **Noise-based monitoring with high temporal resolution**
 - Nearly impossible unless sources are stationary [even when only traveltimes are used]

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- **Improve the resolution of ambient noise tomography**
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 - Mostly restricted to fundamental mode Rayleigh waves
 - Spurious arrivals [e.g. Halliday and Curtis 2008, Kimman and Trampert 2010]
 - Amplitudes are difficult to interpret [e.g. Cupillard and Capdeville 2010, Tsai 2011, Stehly and Boué 2017]
 - Data selection / heavy preprocessing [e.g. Bensen et al. 2007 , Mordret et al. 2015]
 - Tomographic methods exploiting waveforms cannot be applied

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Approach: Full Waveform Ambient Noise Inversion

- Develop & apply joint FWI for noise sources and Earth structure

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- **Improve the resolution of tomographic images**

Approach: Full Waveform Ambient Noise Inversion

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Outline

1. Forward problem: modeling correlations
2. Potential of FWANI: synthetic study in 2D
3. Extension to 3D
4. Conclusions & Outlook

FORWARD PROBLEM

MODELING CORRELATIONS

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Omit the principle of Green function retrieval:

- Incorporate heterogeneous noise source distributions
- Account for 3D heterogeneous Earth structure
- Model the full seismic wave propagation physics

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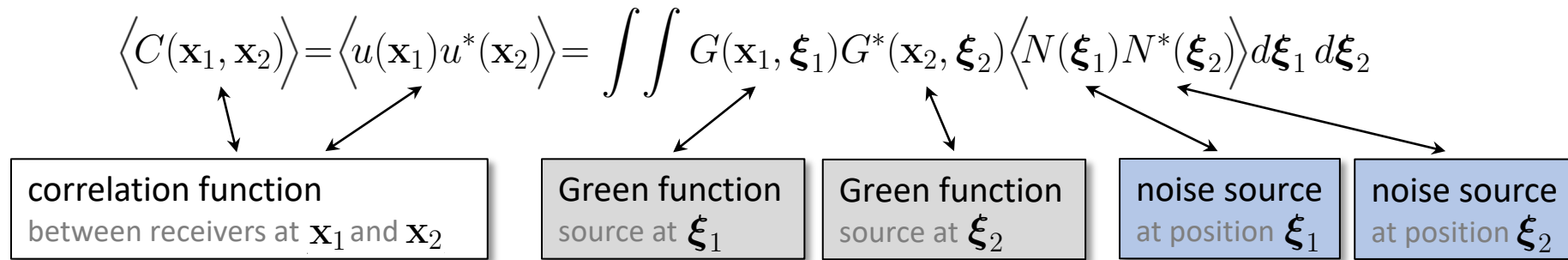
$$\langle C(\mathbf{x}_1, \mathbf{x}_2) \rangle = \langle u(\mathbf{x}_1) u^*(\mathbf{x}_2) \rangle = \iint G(\mathbf{x}_1, \boldsymbol{\xi}_1) G^*(\mathbf{x}_2, \boldsymbol{\xi}_2) \langle N(\boldsymbol{\xi}_1) N^*(\boldsymbol{\xi}_2) \rangle d\boldsymbol{\xi}_1 d\boldsymbol{\xi}_2$$

The diagram illustrates the components of the equation. It features five boxes arranged horizontally below the equation, with arrows pointing from the boxes to the corresponding terms in the equation:

- A white box labeled "correlation function between receivers at \mathbf{x}_1 and \mathbf{x}_2 " has a double-headed arrow pointing to $\langle C(\mathbf{x}_1, \mathbf{x}_2) \rangle$.
- A grey box labeled "Green function source at $\boldsymbol{\xi}_1$ " has an arrow pointing to $G(\mathbf{x}_1, \boldsymbol{\xi}_1)$.
- A grey box labeled "Green function source at $\boldsymbol{\xi}_2$ " has an arrow pointing to $G^*(\mathbf{x}_2, \boldsymbol{\xi}_2)$.
- A blue box labeled "noise source at position $\boldsymbol{\xi}_1$ " has an arrow pointing to $\langle N(\boldsymbol{\xi}_1) N^*(\boldsymbol{\xi}_2) \rangle$.
- A blue box labeled "noise source at position $\boldsymbol{\xi}_2$ " has an arrow pointing to $\langle N(\boldsymbol{\xi}_1) N^*(\boldsymbol{\xi}_2) \rangle$.

similar in Tromp et al. (2010), Hanasoge (2014), Fichtner (2014)

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MODELING CORRELATIONS

$$\langle C(\mathbf{x}_1, \mathbf{x}_2) \rangle = \langle u(\mathbf{x}_1)u^*(\mathbf{x}_2) \rangle = \int \int G(\mathbf{x}_1, \boldsymbol{\xi}_1)G^*(\mathbf{x}_2, \boldsymbol{\xi}_2) \langle N(\boldsymbol{\xi}_1)N^*(\boldsymbol{\xi}_2) \rangle d\boldsymbol{\xi}_1 d\boldsymbol{\xi}_2$$

$$\langle C(\mathbf{x}_1, \mathbf{x}_2) \rangle = \int G(\mathbf{x}_1, \boldsymbol{\xi}_1) \left[\int G^*(\mathbf{x}_2, \boldsymbol{\xi}_2) S(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) d\boldsymbol{\xi}_1 \right] d\boldsymbol{\xi}_2$$



power-spectral density

$$\langle N(\boldsymbol{\xi}_1)N^*(\boldsymbol{\xi}_2) \rangle = S(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2)$$

similar in Tromp et al. (2010), Hanasoge (2014), Fichtner (2014)

MODELING CORRELATIONS

Representation theorem: $u(\mathbf{x}) = \int G(\mathbf{x}, \boldsymbol{\xi}) N(\boldsymbol{\xi}) d\boldsymbol{\xi}$

$$\langle C(\mathbf{x}_1, \mathbf{x}_2) \rangle = \int G(\mathbf{x}_1, \boldsymbol{\xi}_1) \left[\int G^*(\mathbf{x}_2, \boldsymbol{\xi}_2) S(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) d\boldsymbol{\xi}_1 \right] d\boldsymbol{\xi}_2$$

- Step 1:** Using source-receiver reciprocity, compute the Green function $G^*(\mathbf{x}_2, \boldsymbol{\xi}_2)$ with source at \mathbf{x}_2 .
- Step 2:** Combine its complex conjugate with the power-spectral density $S(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2)$.
- Step 3:** Model the correlation wavefield as solution of the wave equation with $\int G^*(\mathbf{x}_2, \boldsymbol{\xi}_2) S(\boldsymbol{\xi}_1, \boldsymbol{\xi}_2) d\boldsymbol{\xi}_1$ as distributed source.

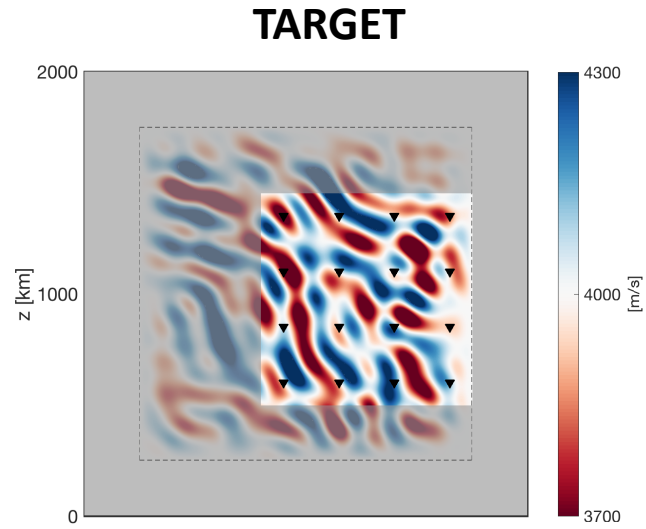
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SYNTHETIC STUDY IN 2D

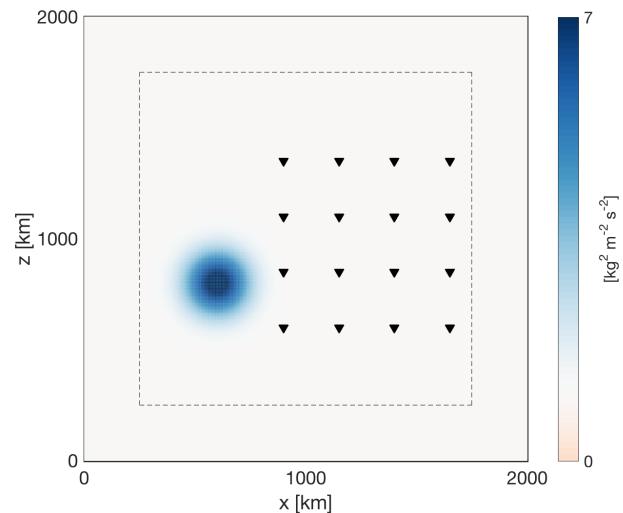
POTENTIAL OF FWANI

POTENTIAL OF FULL WAVEFORM AMBIENT NOISE INVERSION

VELOCITY
MODEL



SOURCE
DISTRIBUTION



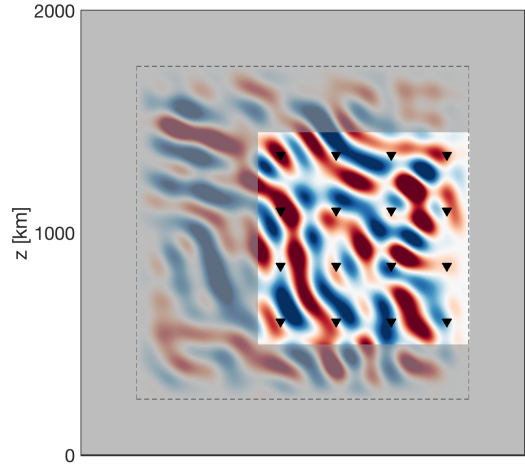
Inversion scheme:

- **2D finite-difference discretization of the membrane wave equation**
[analogous to fundamental-mode surface wave propagation]
- **Iterative inversion scheme**
[based on L-BFGS (Nocedal and Wright 2006)]
- **Stopping criterion:** reduction of the norm of the initial gradient by a factor of 10^{-3}
- **Gaussian smoothing operator as part of the parameterization**
[choose the dominant wavelength as standard deviation]
- **Tikhonov regularization term**
[Tikhonov 1963]

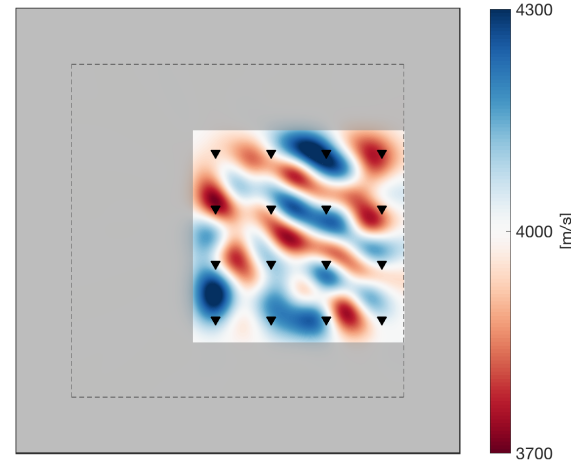
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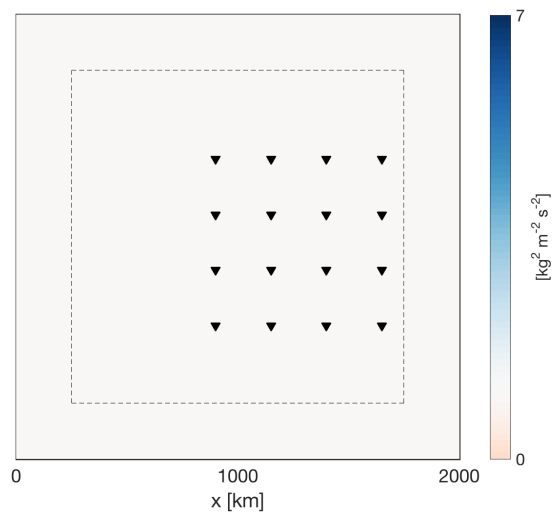
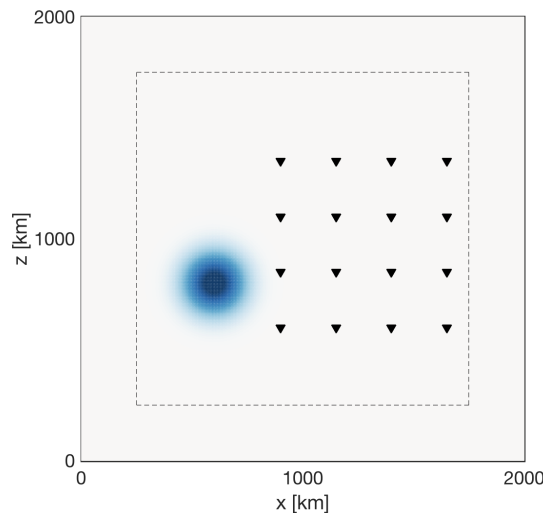
TARGET



TRAVELTIME INVERSION



SOURCE
DISTRIBUTION



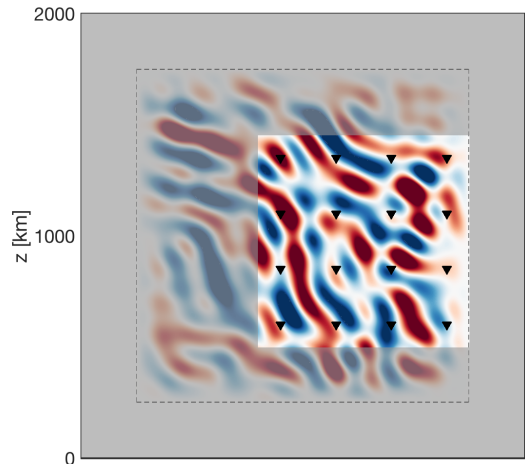
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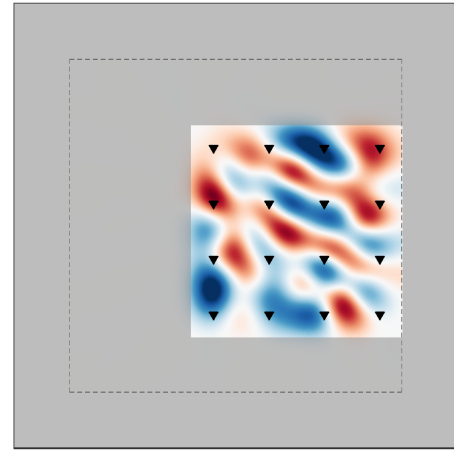
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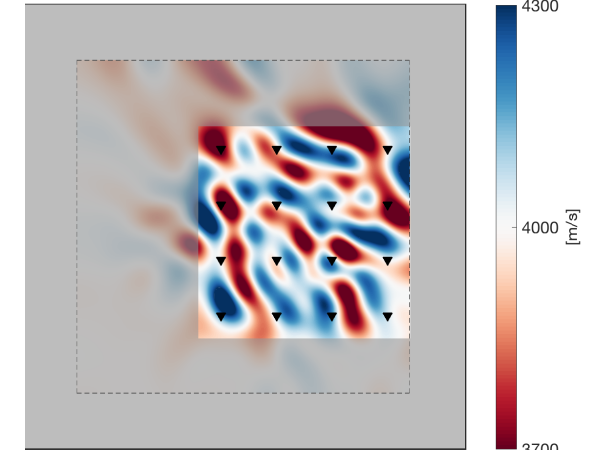
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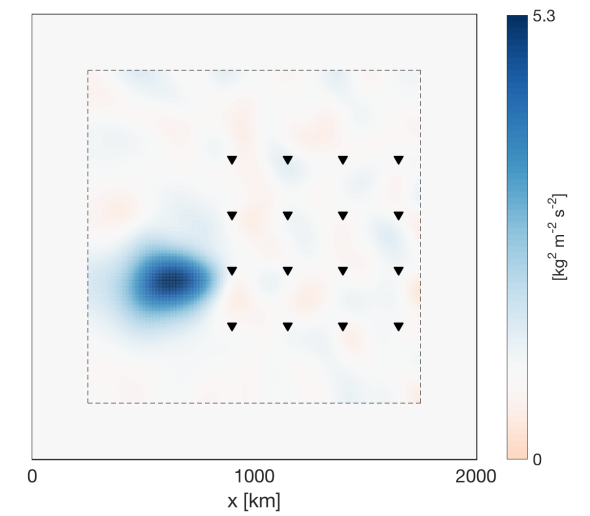
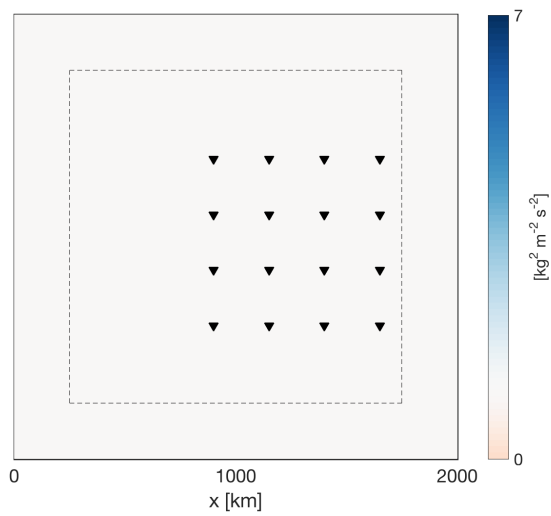
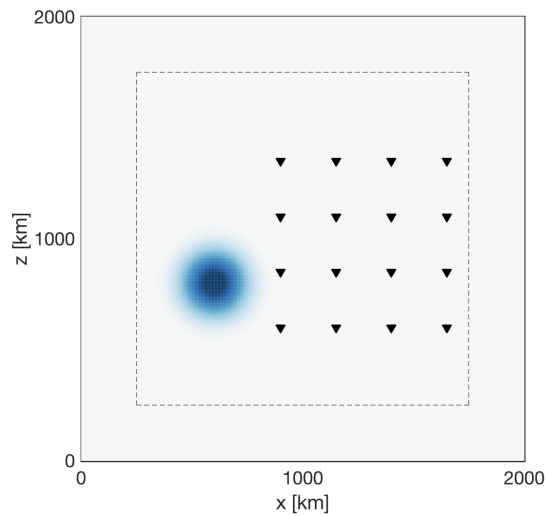
TRAVELTIME INVERSION



FWANI

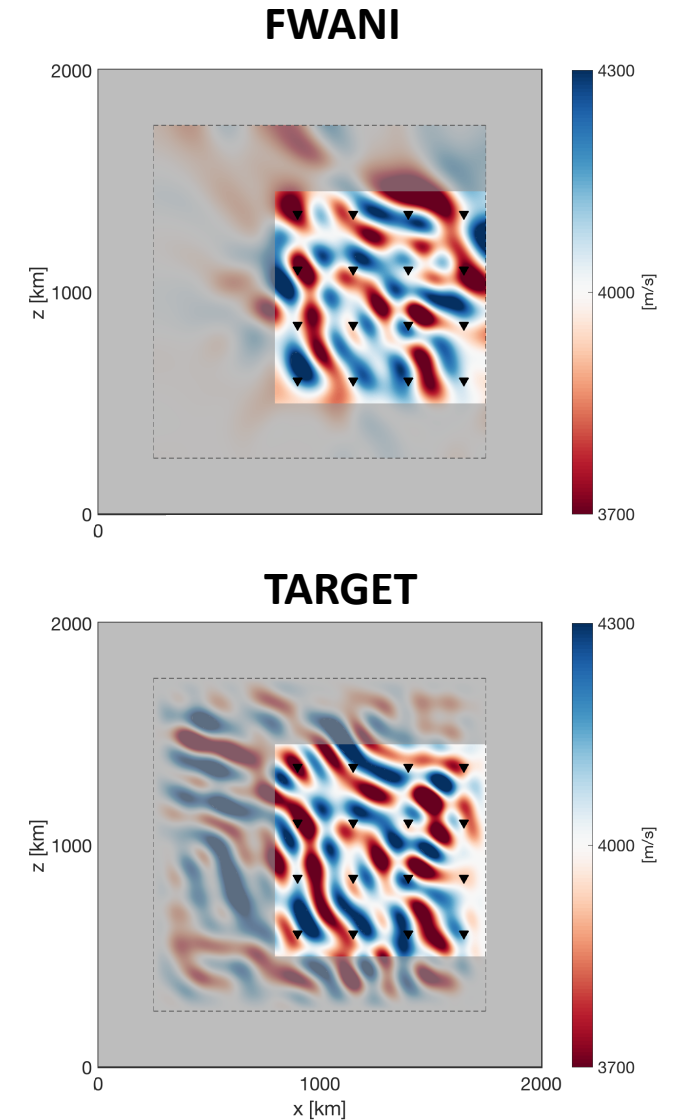


SOURCE
DISTRIBUTION



POTENTIAL OF FULL WAVEFORM AMBIENT NOISE INVERSION (FWANI)

- Possible to go **beyond** traditional ambient noise tomography and to **account** for the **noise source distribution**
- Knowledge of the **noise source distribution** is **essential**
- **Trade-offs** between source and structure can be quantified using **Hessian-vector products**
[Sager et al., GJI, 2018]



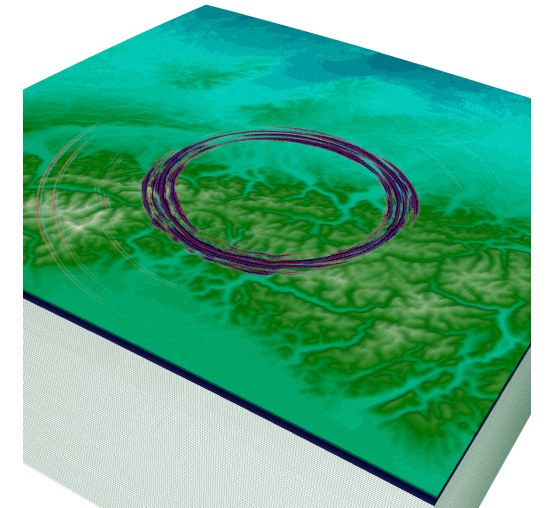
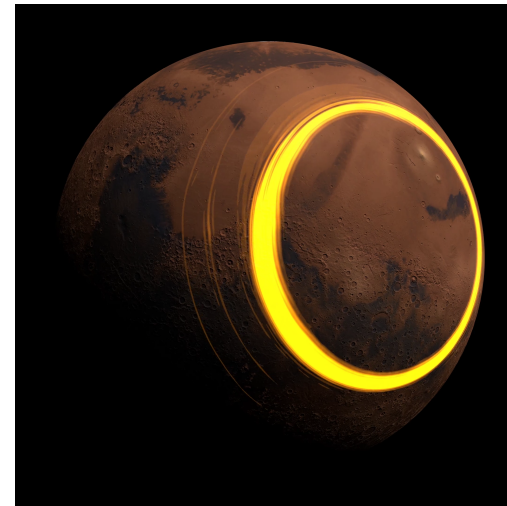
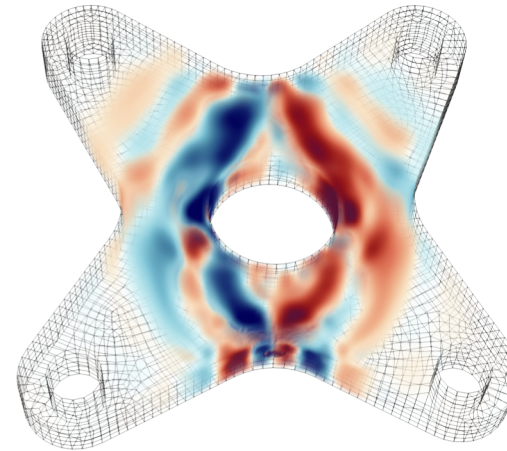
EXTENSION TO 3D

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A new, high-performance package for FWI with a focus on efficiency, reproducibility, flexibility and scale independence.

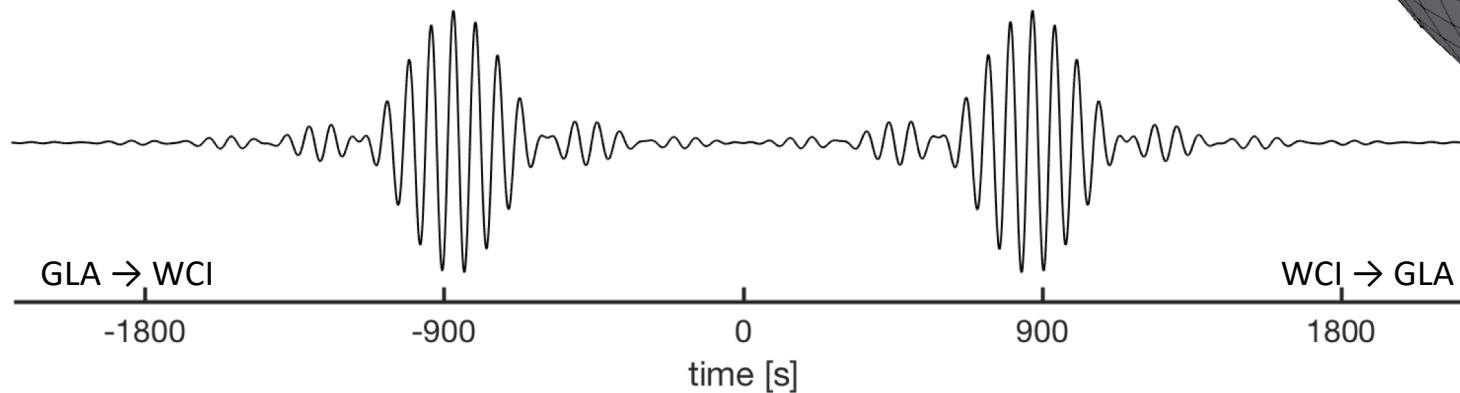
- spectral elements
- visco-elastic, acoustic, and coupled
- hexahedra, tetrahedra
- built-in mesher



Afanasiev et al.,
submitted to GJI

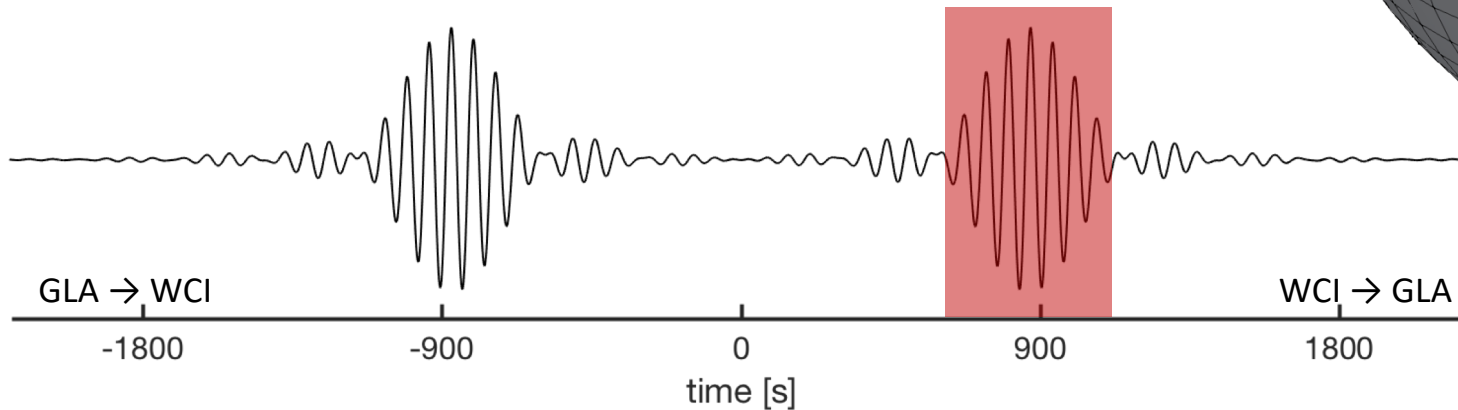
GLOBAL FORWARD MODELLING

- Velocity model: PREM
- Period band: 55-75 sec
- Homogeneous noise source distribution



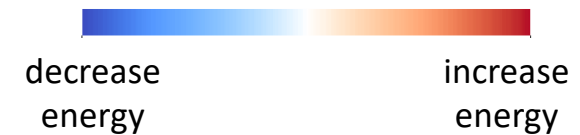
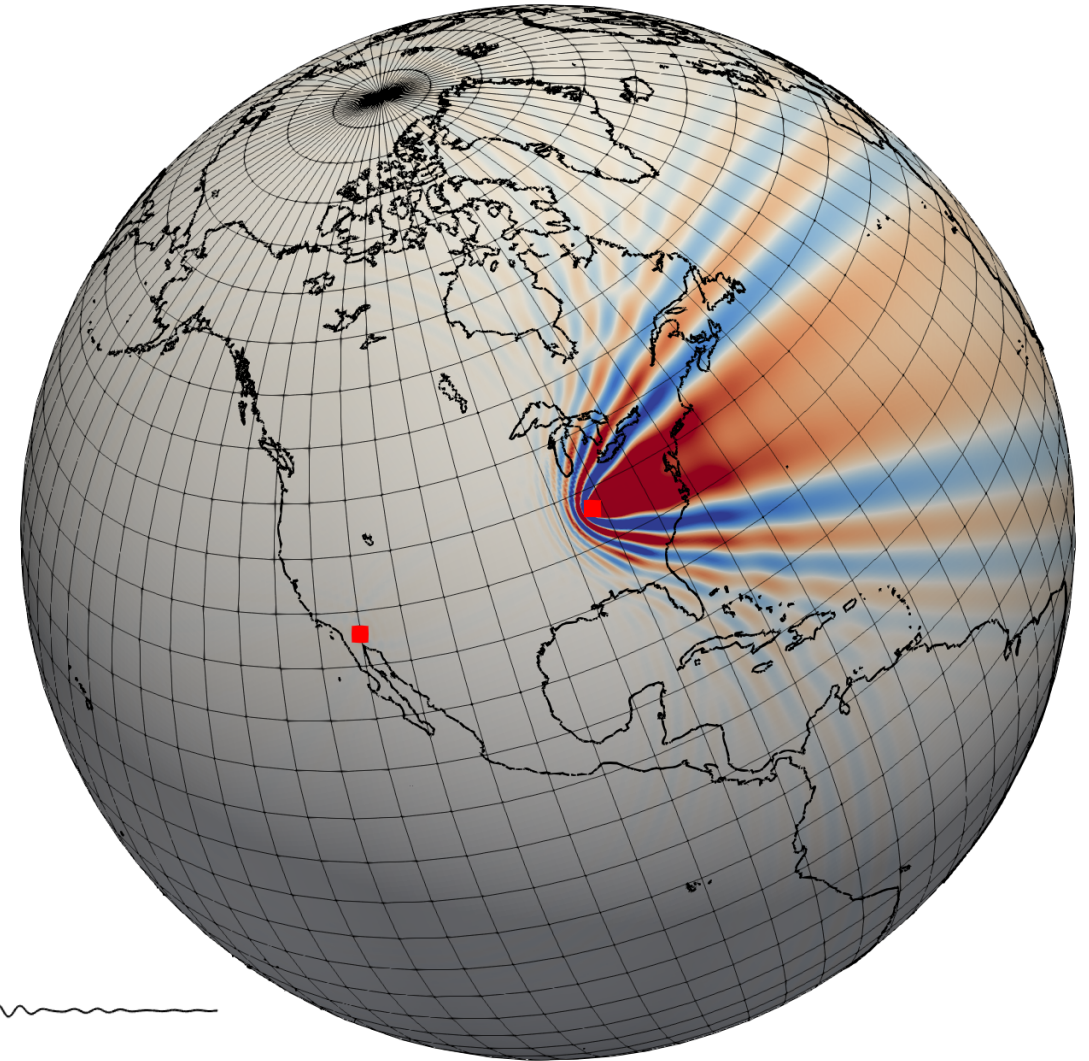
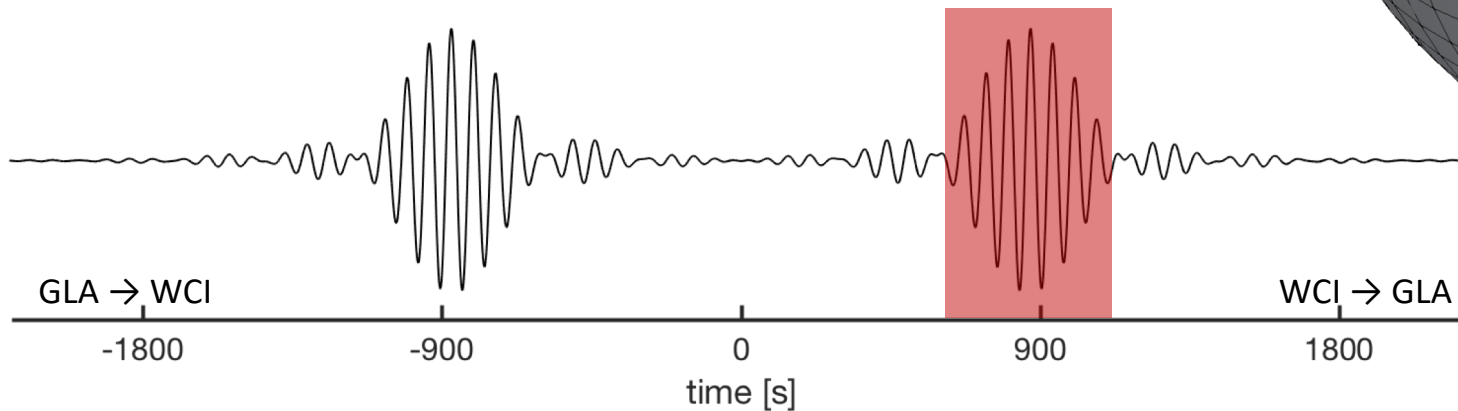
NOISE SOURCE SENSITIVITY

Which noise sources in space contribute to the waveform in the **surface wave** window?
[for an energy measurement]



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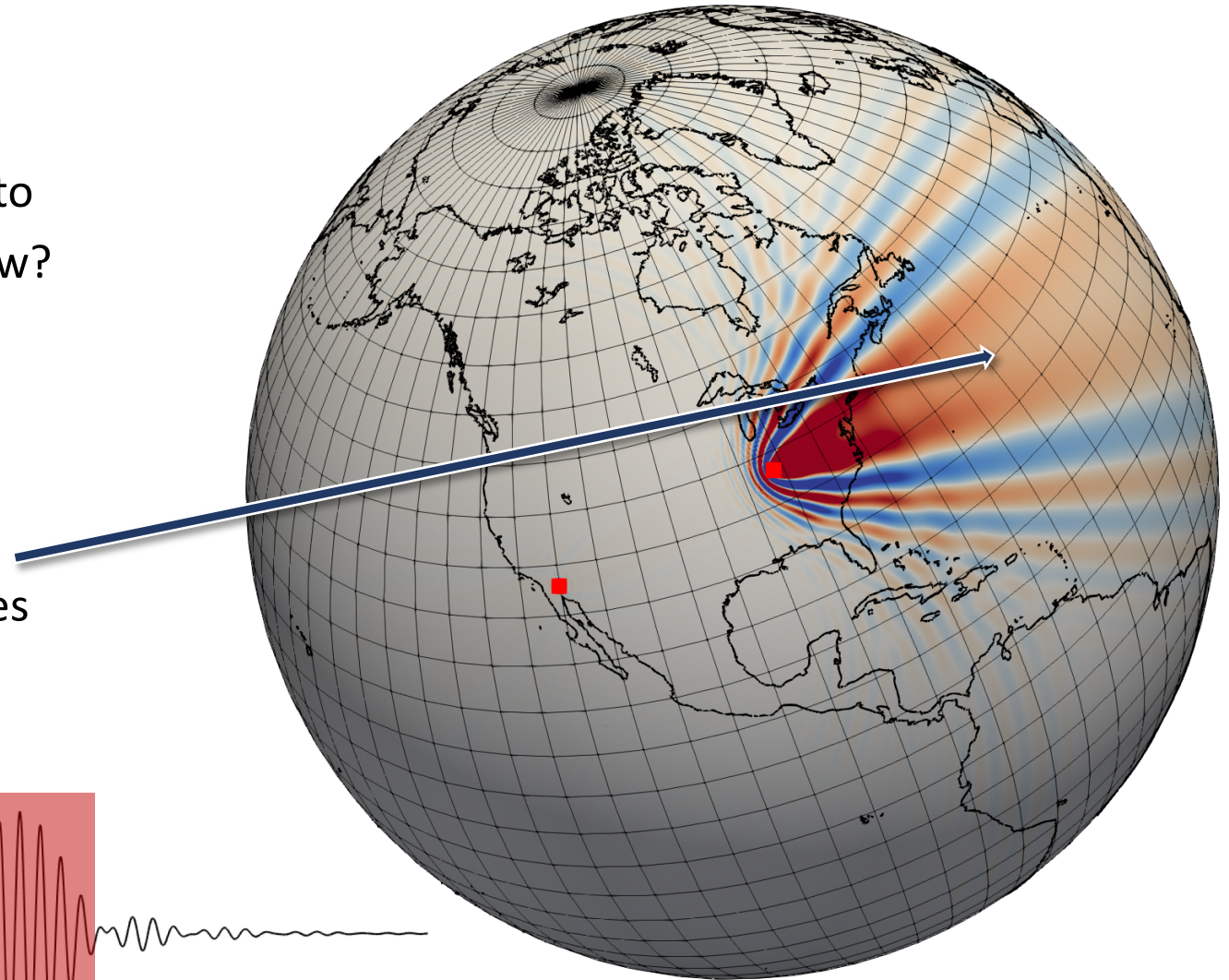
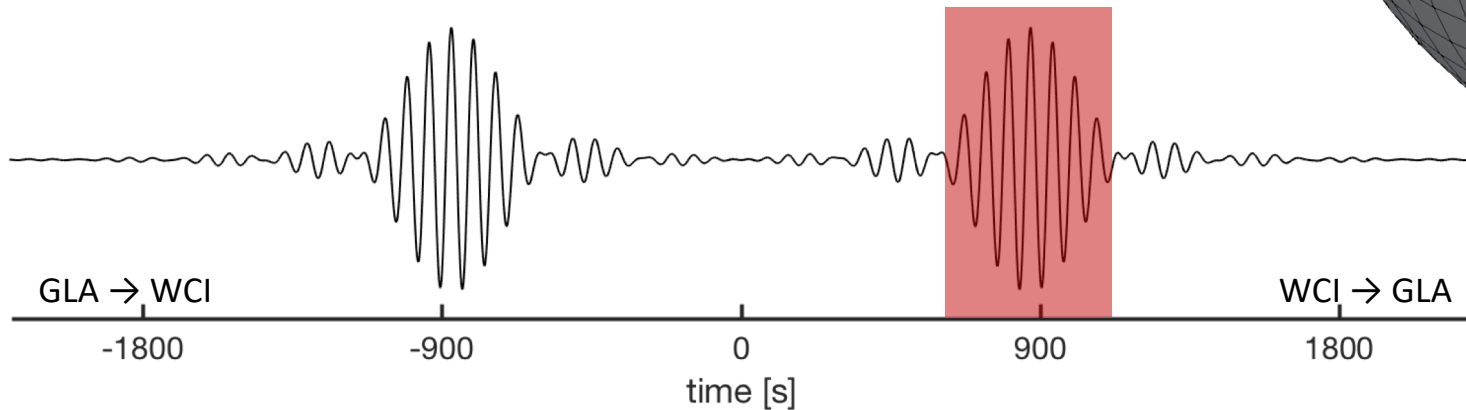
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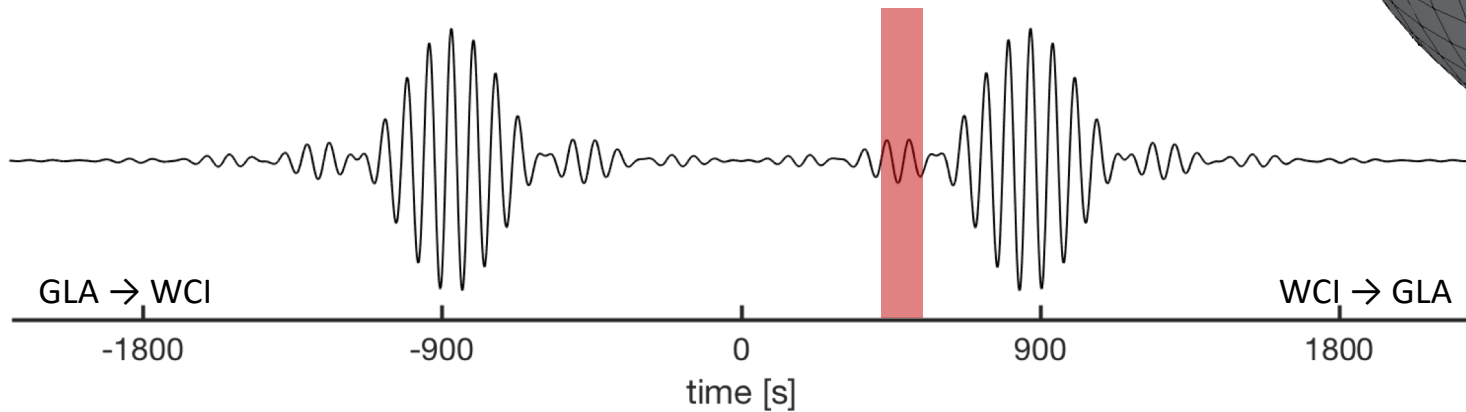
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sensitivity to
long-wavelength noise sources



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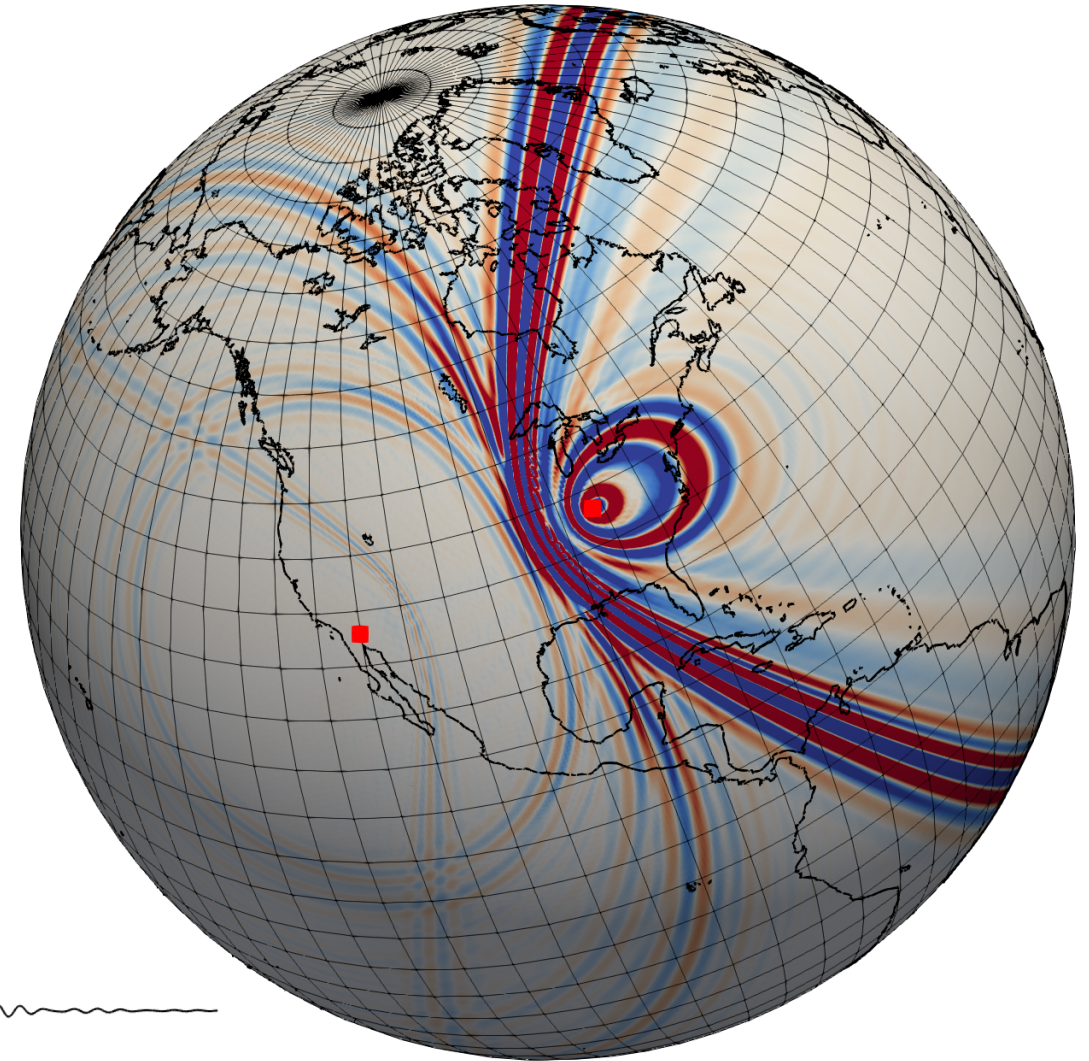
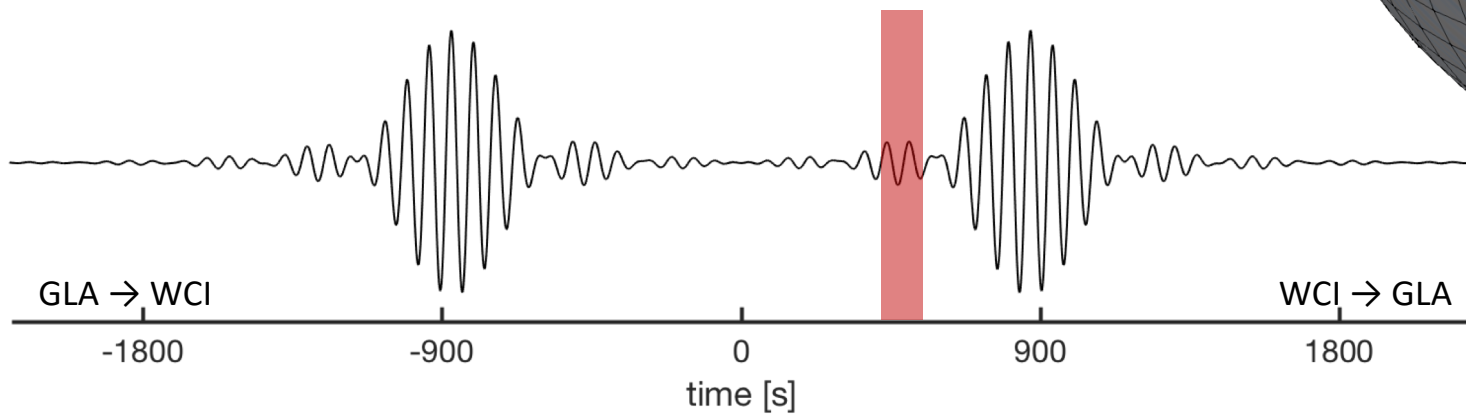
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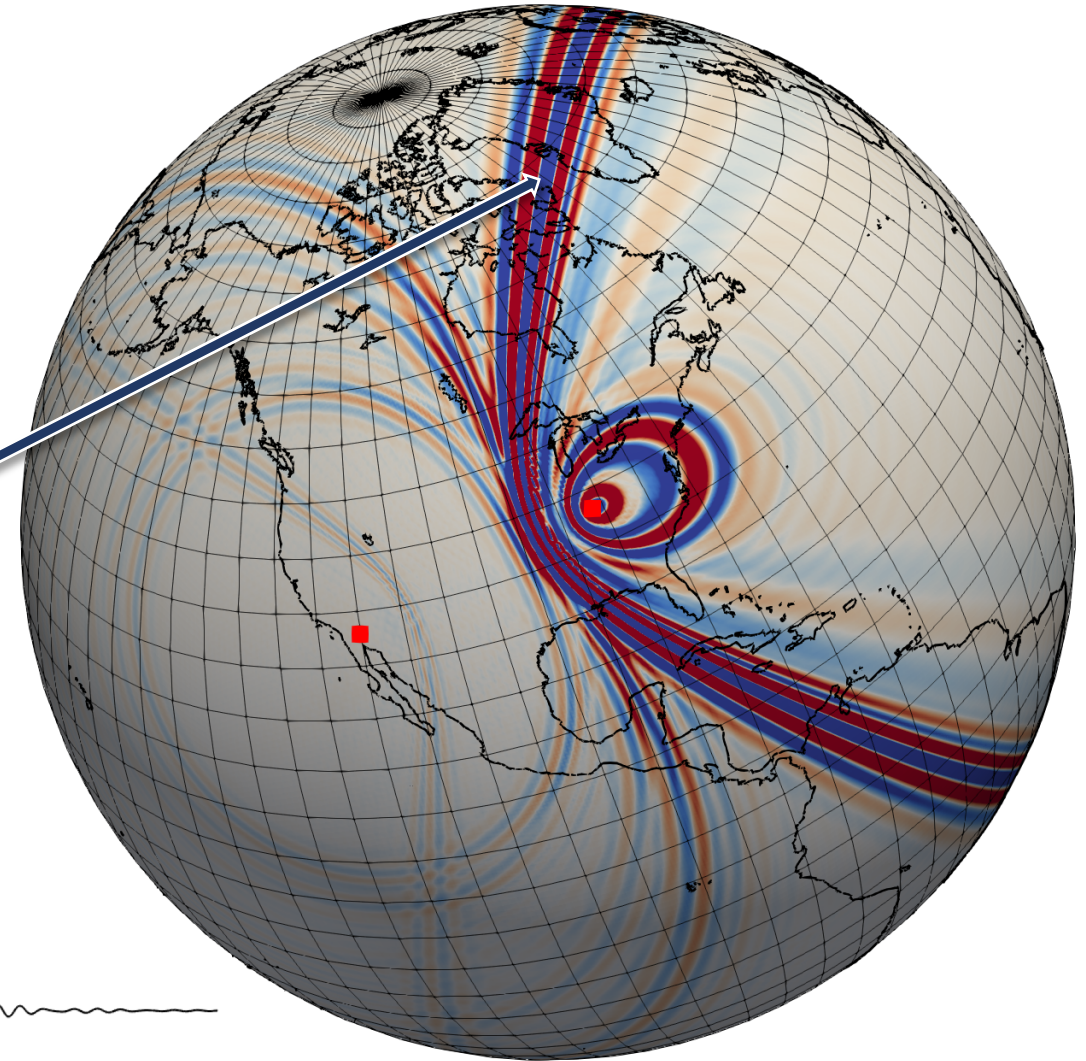
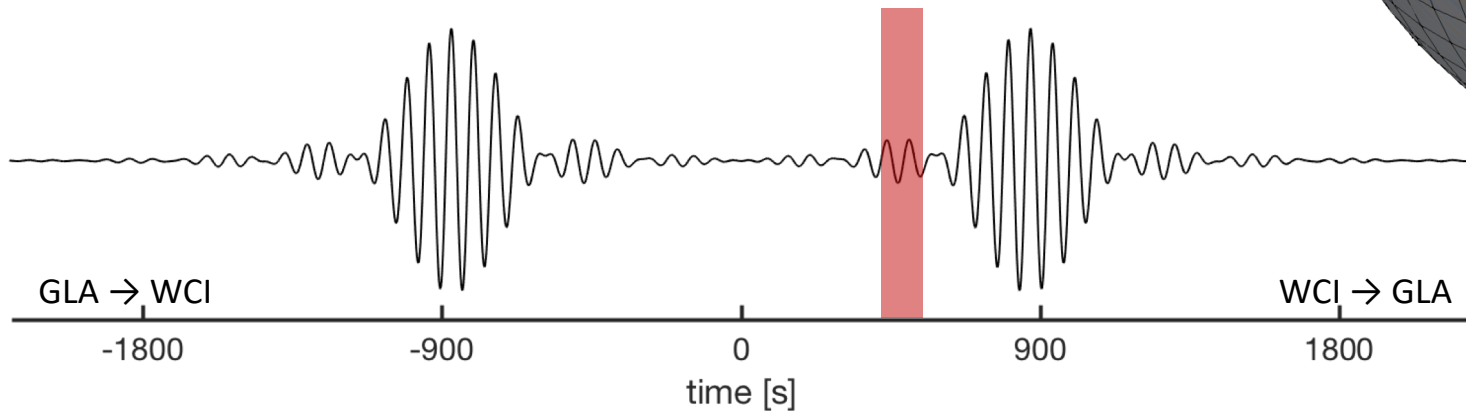
[for an energy measurement]



NOISE SOURCE SENSITIVITY

Which noise sources in space contribute to the waveform in the **S-wave** window?
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sensitivity to
short-wavelength noise sources



CONCLUSIONS & OUTLOOK

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Synthetic 2D inversions

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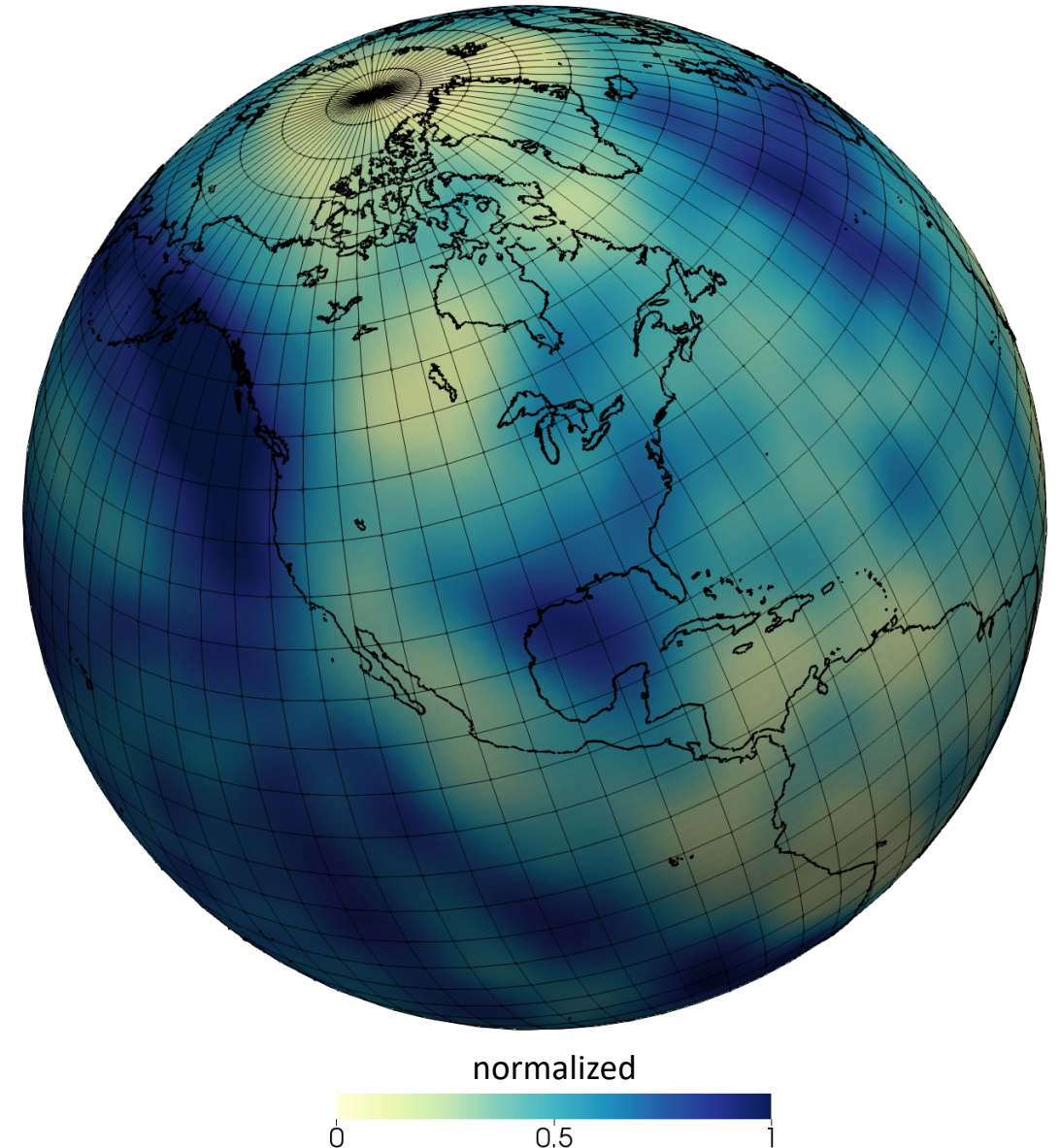
Synthetic 2D inversions

- Potential to jointly invert for sources and structure

3D source-structure inversion

- Framework for 3D media with heterogeneous noise source distributions on the surface
- In progress for the global scale
- Translation to other scales seems easily feasible

PSD for Earth's hum in winter
[Ermert et al., JGR, 2017]



Thank you for your attention!

Sager et al., *GJI* 2018. **Towards full-waveform ambient noise inversion.**

Ermert et al., *JGR* 2017. **Ambient noise source inversion in a heterogeneous Earth.**

Delaney et al., *Geophysics* 2017. **Passive seismic monitoring with nonstationary noise sources.**