

# Accuracy of finite-difference modeling

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# Overview

1. Introduction
2. Physical modeling
3. Finite-difference modeling
4. Results
5. Conclusions

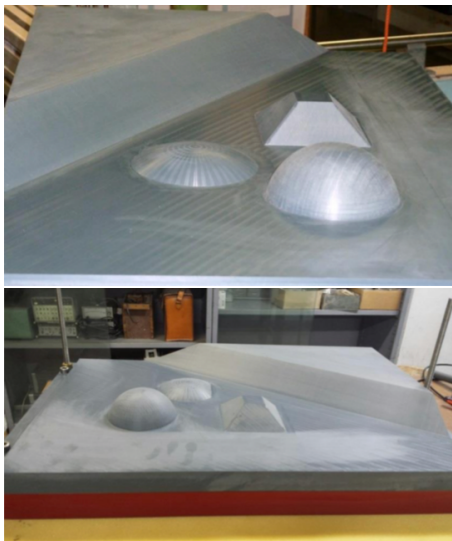
# Introduction

- ▶ Finite-difference modeling is extensively used in imaging and inversion of seismic data
- ▶ The use of high-order spatial derivatives apparently allows the use of coarse grids
- ▶ Acceptable run-times even for very large models using modern CPUs and GPUs
- ▶ Simple and efficient coding
- ▶ Models represented by simple regular grids

# Introduction

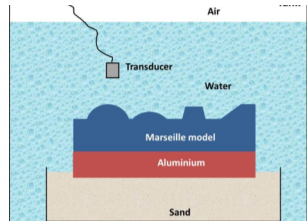
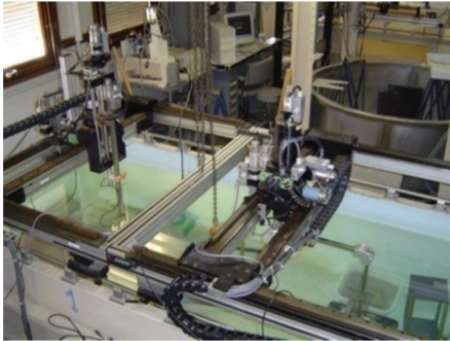
- ▶ Complex, curved interfaces are difficult to represent with regular grids
- ▶ Plane, sloping layers are known to be problematic for finite-difference methods
- ▶ There is a need for calibrating finite-difference modeling against data from known models

# The BENCHIE model



(courtesy of Favretto-Cristini, 2015,[1])

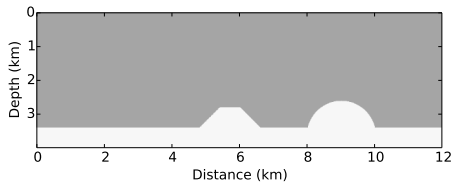
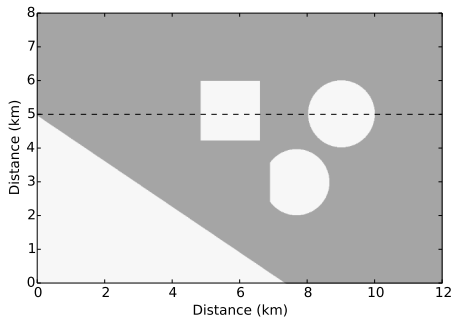
# The BENCHIE model



(courtesy of Favretto-Cristini, 2015,[1])

# The BENCHIE model

Scale factor: 20000



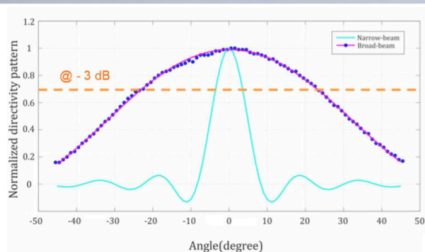
# The BENCHIE model

Physical properties

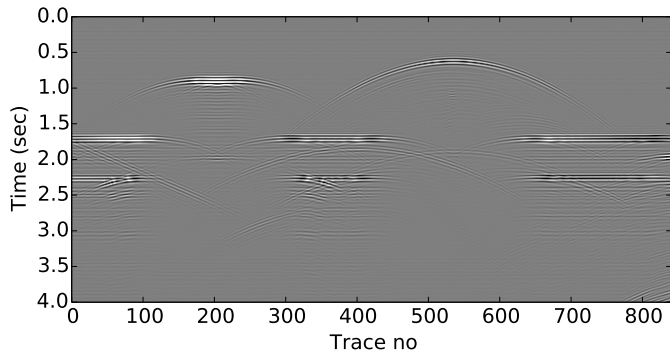
Material	$V_p$	$V_s$	Density	$Q_p$	$Q_s$
Water	1480	0.0	1000	$\infty$	$\infty$
PVC	2220	1050	1412	42	32



# The BENCHIE model



# The BENCHIE model



# Finite-difference modeling

Visco-elastic equations

$$\begin{aligned}u_i(\mathbf{x}, t) &= \partial_j \sigma_{ij}(\mathbf{x}, t) \\ \sigma_{ij}(\mathbf{x}, t) &= \lambda(\mathbf{x}, t) * e_{kk}(\mathbf{x}, t) \delta_{ij} + 2\mu(\mathbf{x}, t) * e_{ij}(\mathbf{x}, t) + q_{ij}(\mathbf{x}, t) \\ e_{ij}(\mathbf{x}, t) &= \frac{1}{2} [\partial_j u_i(\mathbf{x}, t) + \partial_i u_j(\mathbf{x}, t)]\end{aligned}\tag{1}$$

Where

- ▶  $\mathbf{x}, t$  : Space, time
- ▶  $u_i(\mathbf{x}, t)$  : Displacement vector  $i$
- ▶  $\sigma(\mathbf{x}, t)$  : Stress tensor
- ▶  $\lambda(\mathbf{x}, t), \mu(\mathbf{x}, t)$  : Lamé parameters
- ▶  $q_{ij}(\mathbf{x}, t)$ : Source tensor

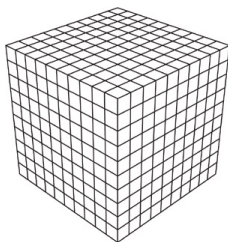
## Finite-difference modeling

The Finite-difference method solves the Visco-elastic equations by approximating derivatives with finite-differences

$$\partial_x u \approx \frac{1}{\Delta x} \sum_{l=1}^8 \alpha_l [u(\mathbf{x} + l\Delta x) - u(\mathbf{x} - (l-1)\Delta x)] \quad (2)$$

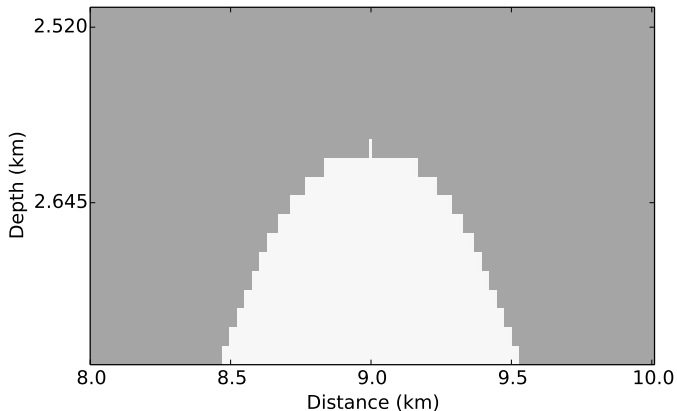
Where

- ▶  $u$ : Wavefield
- ▶  $\alpha$ : Precomputed coefficients
- ▶  $\Delta x$ : Distance between grid-points

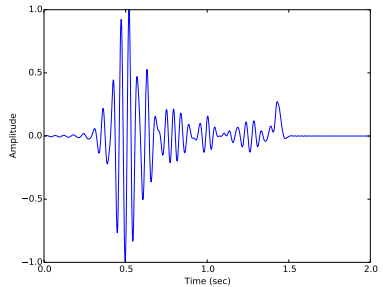
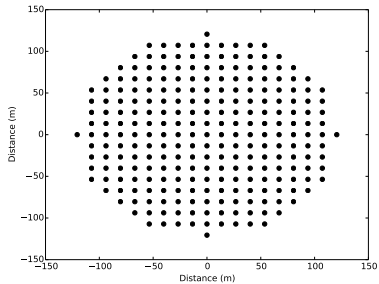


# Finite-difference modeling

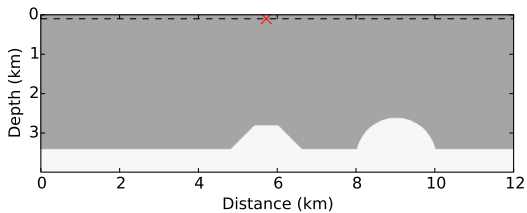
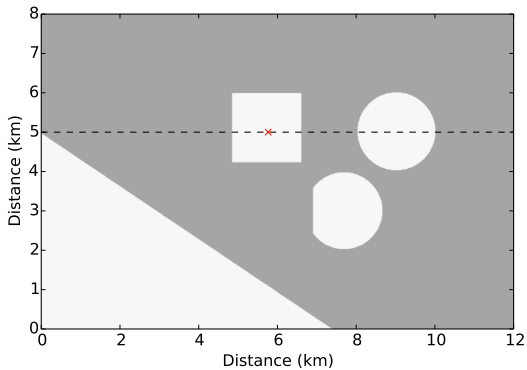
Use  $\Delta x = 13.4\text{m}$  giving grid-points/wavelength = 4.0



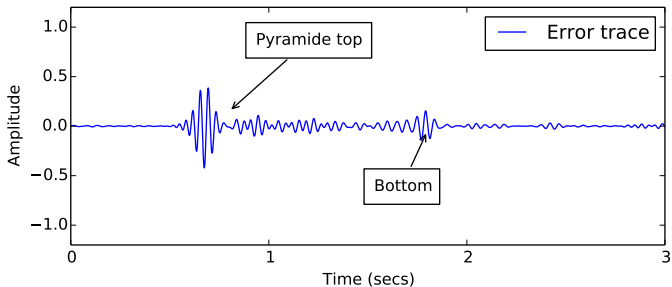
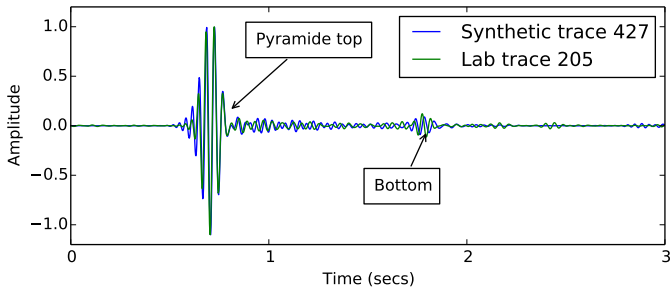
# Finite-difference modeling



# Results

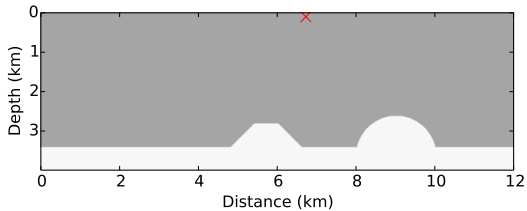
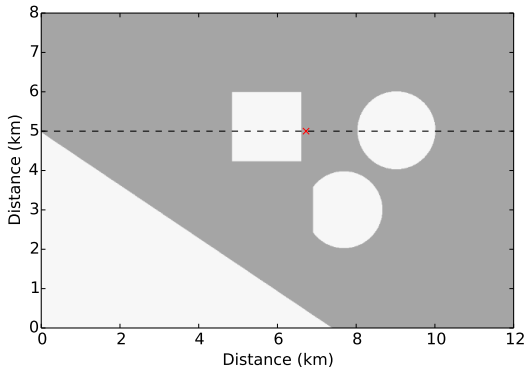


# Results

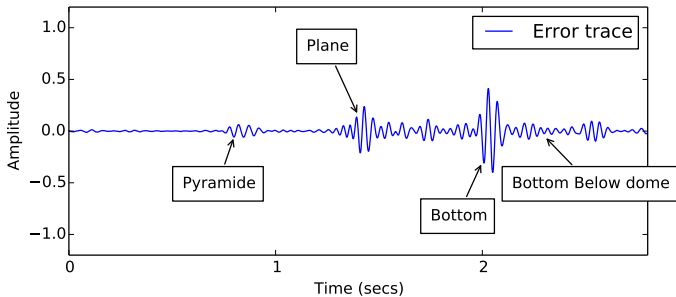
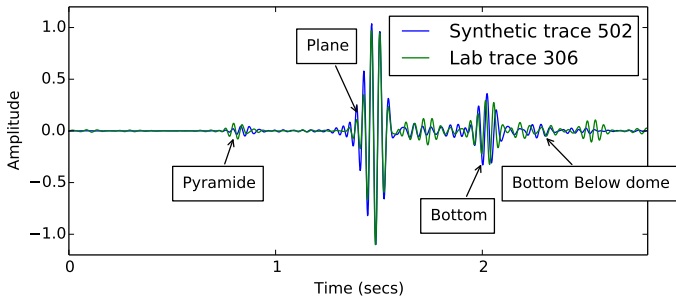




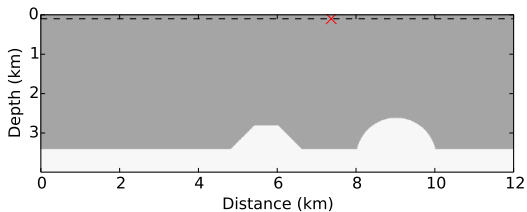
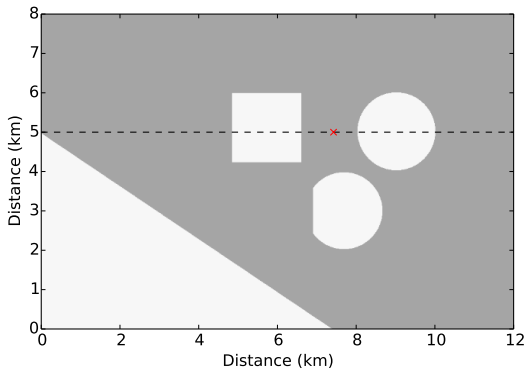
# Results



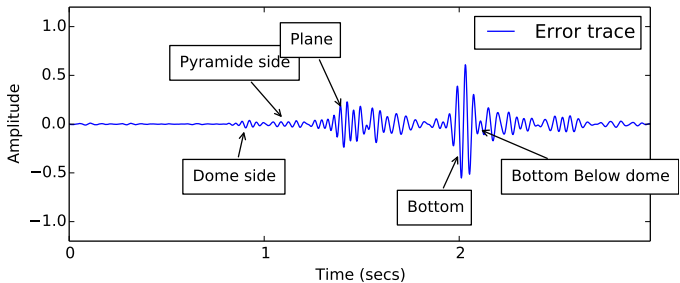
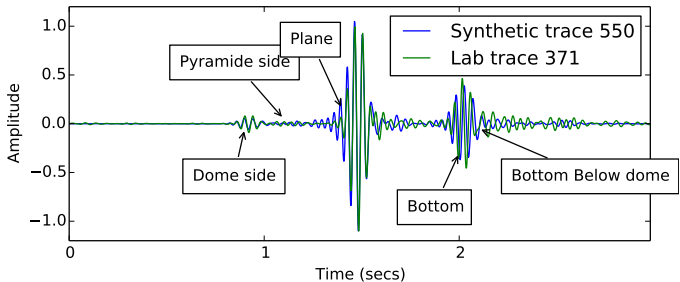
# Results



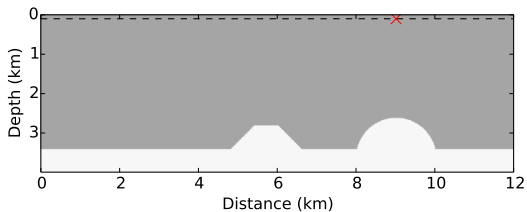
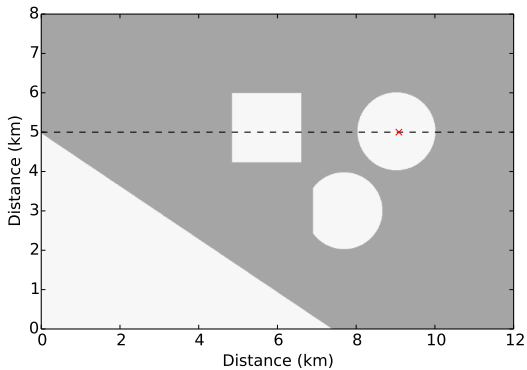
# Results



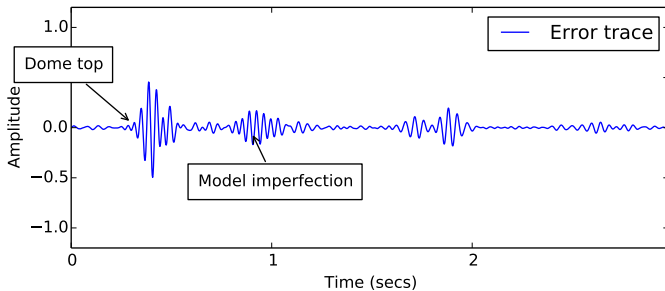
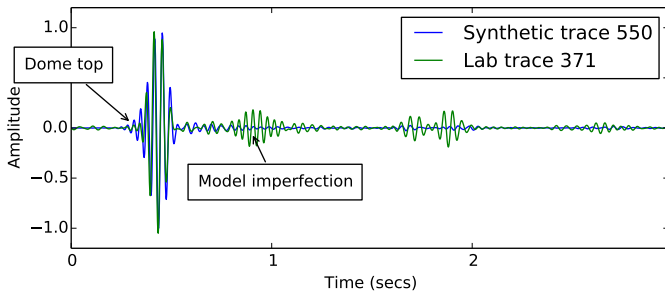
# Results



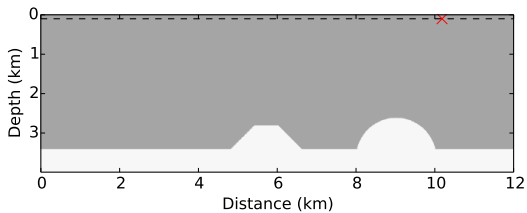
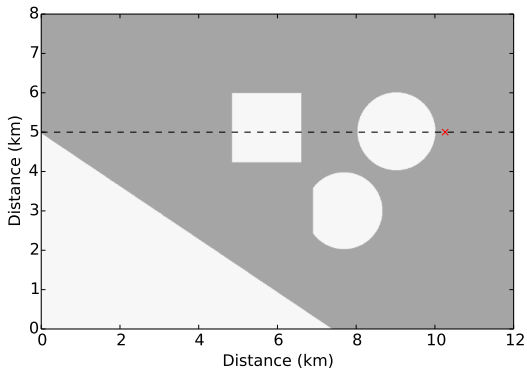
# Results



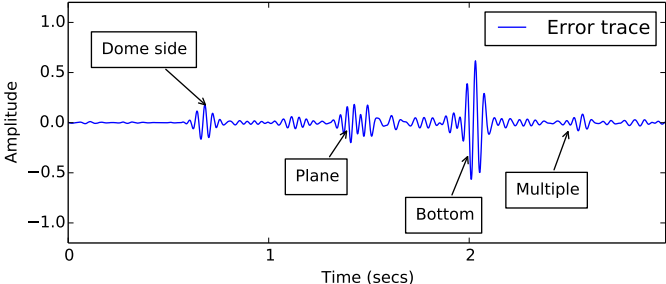
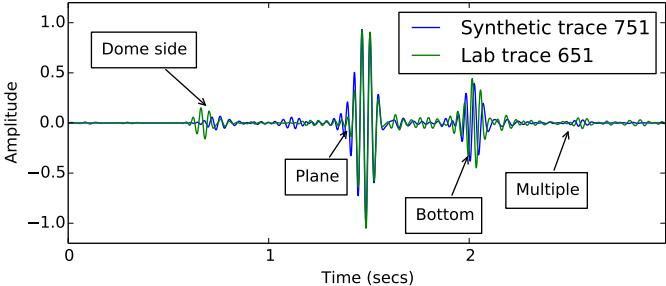
# Results



# Results



# Results





# Conclusions

- ▶ Coarse grid Finite-difference not accurate for plane surfaces
- ▶ Coarse grid Finite-difference not accurate for tilting plane
- ▶ Coarse grid Finite-difference not accurate for spherical surface

## References

- [1] Nathalie Favretto-Cristini and Paul Cristini. Benchmarking of numerical methods dedicated to wave propagation and wave-based imaging against laboratory data in complex environments description of the experimental set-up & data acquisition zero-offset & multi-offset data at 500 khz nathalie favretto-cristini & paul cristini version 1. Technical report, Laboratory of Mechanics and Acoustics-Marseilles (LMA), 2015.