

# ROSE meeting



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# Anisotropy parameters from diving waves

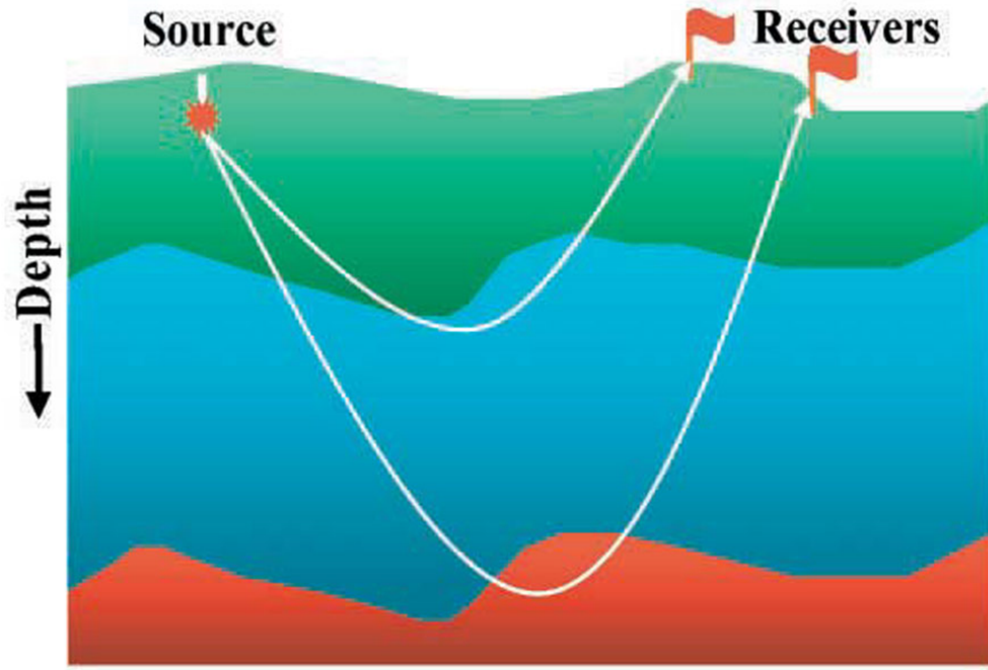
## Objectives:

- 1 Better understanding of the feature of diving wave in a factorized VTI medium
- 2 Imaging moveout approximation of the diving wave
- 3 Estimate the anisotropy parameters through semblance analysis

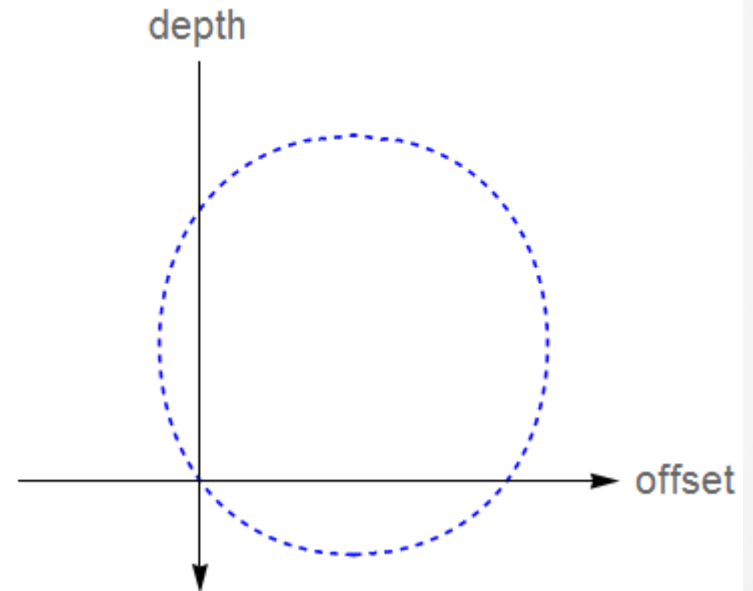
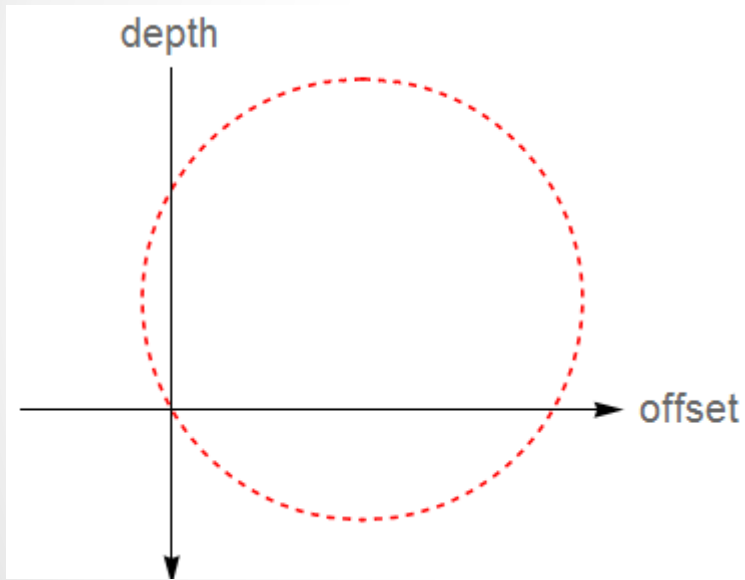
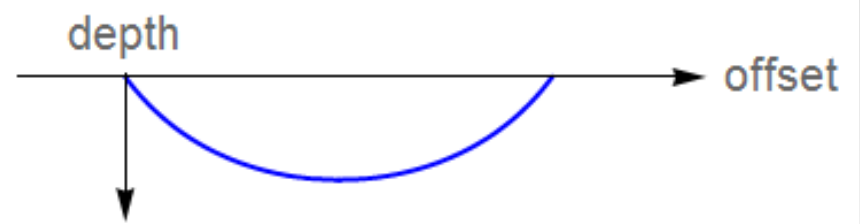
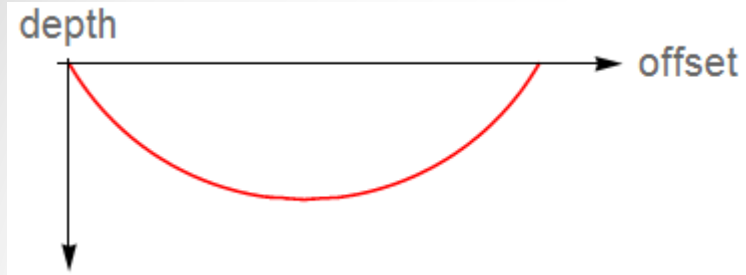
# Outline

- ✦ 1 Diving wave in a factorized VTI medium
- 2 The image moveout approximation
- 3 Semblance analysis & anisotropy estimation
- 4 Numerical examples & different parameterization
- 5 Conclusions

# Diving wave



# Diving wave in anisotropic medium



Constant-gradient isotropic model

$$v(z) = v_0 + Gz \quad \varepsilon = \delta = 0$$

Constant-gradient anisotropic model

$$v(z) = v_0 + Gz \quad \delta = 0.2, \eta = 0.1$$

# Outline

1 Diving wave in a factorized VTI medium

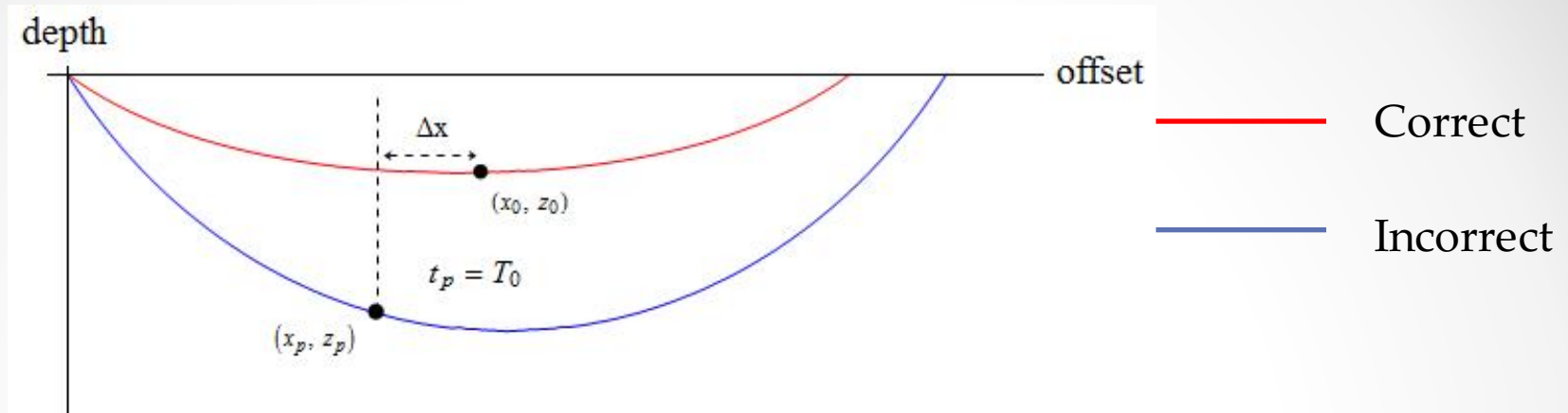
✦ 2 The image moveout approximation

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# Imaging moveout



Isotropic travelttime expression

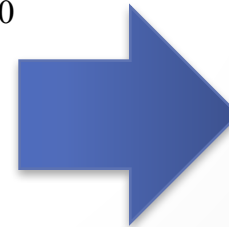
$$t_p = \frac{1}{G} \log\left(\frac{v(z_p)}{v_0} \frac{1 + \sqrt{1 - p^2 v_0^2}}{1 + \sqrt{1 - p^2 v^2(z_p)}}\right)$$

Anisotropic travelttime from source to the turning point  $T_0$

Apply for isotropic constant gradient model  $t_p = T_0$

"Turning point"

$$x_p(\varepsilon, \eta), z_p(\varepsilon, \eta)$$



$$\Delta x_p(z_p) = x_0 - x_p$$

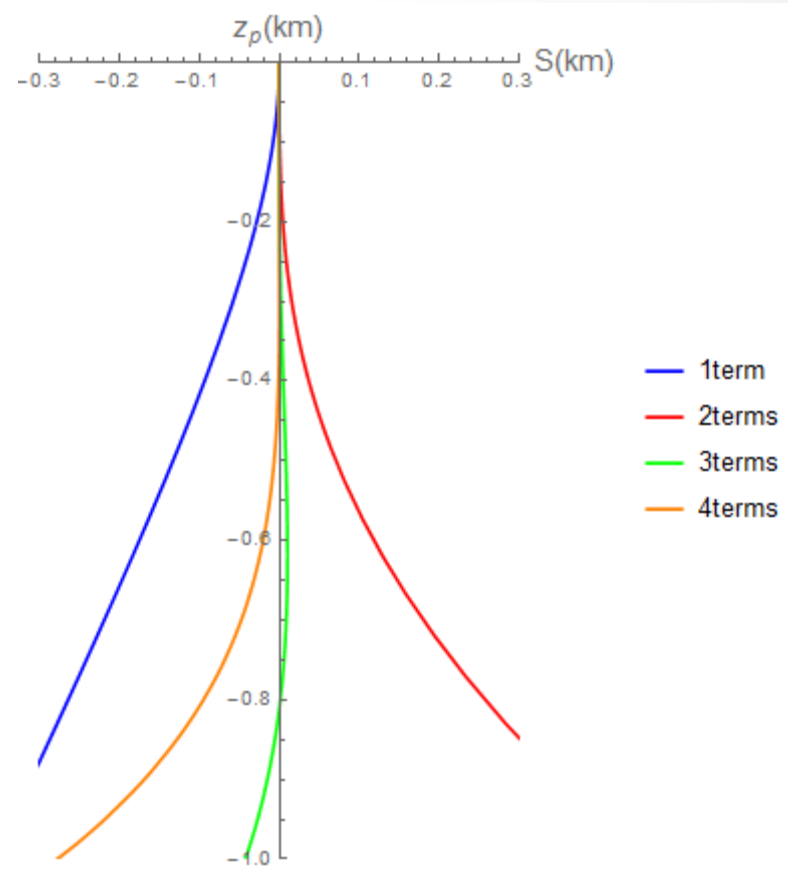
# The image moveout approximation\_(A) Taylor series

Taylor expansion

$$\Delta x_p(z_p)$$

$$\Delta x_p = a_1 z_p + a_2 z_p^2 + a_3 z_p^3 + a_4 z_p^4,$$

$$\hat{S}(z_p) = S\{\Delta x_{exact}(z_p) - \Delta x_i(z_p)\}$$



$$V_0 = 2 \text{ km/s}, G = 1.5 \text{ s}^{-1}, \varepsilon = 0.22, \eta = 0.1$$



# The image moveout approximation\_(B) Pade approximation

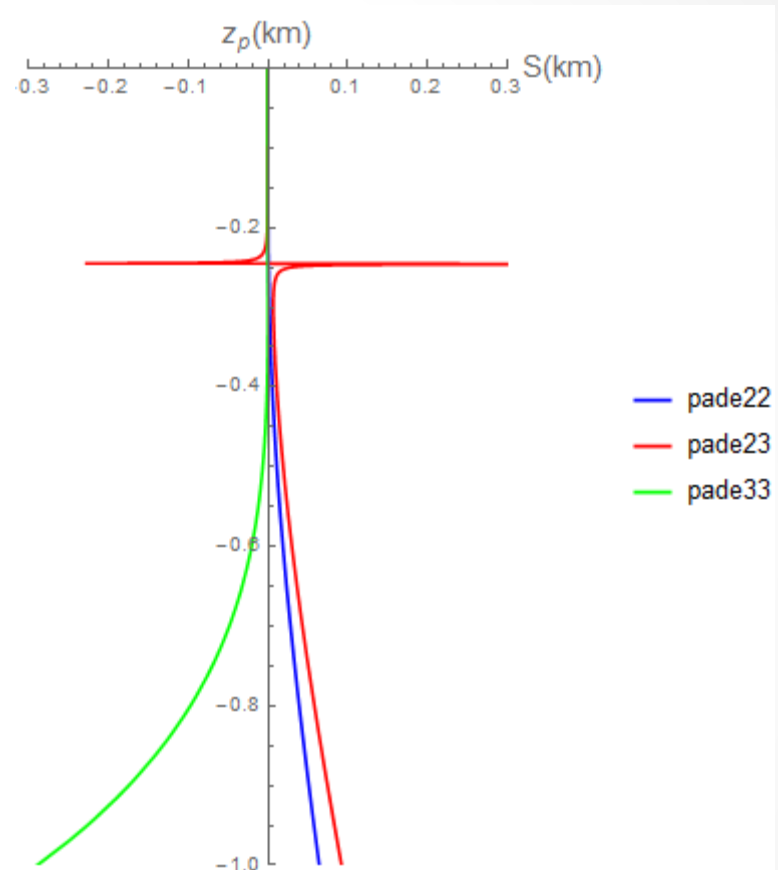
## Pade approximation

$$f(z_p) = \Delta x_p = a_1 z_p + a_2 z_p^2 + a_3 z_p^3 + a_4 z_p^4,$$

$$f(z_p) = R_{L,M}(z_p) + O(z_p),$$

$$R_{L,M}(z_p) = \frac{\sum_{k=0}^L p_k z_p^k}{1 + \sum_{k=0}^M q_k z_p^k}$$

$$R_{2,2}, R_{2,3}, R_{3,3}$$



$$V_0 = 2 \text{ km/s}, G = 1.5 \text{ s}^{-1}, \varepsilon = 0.22, \eta = 0.1$$

# The image moveout approximation\_(C) rational approximation

## Rational approximations

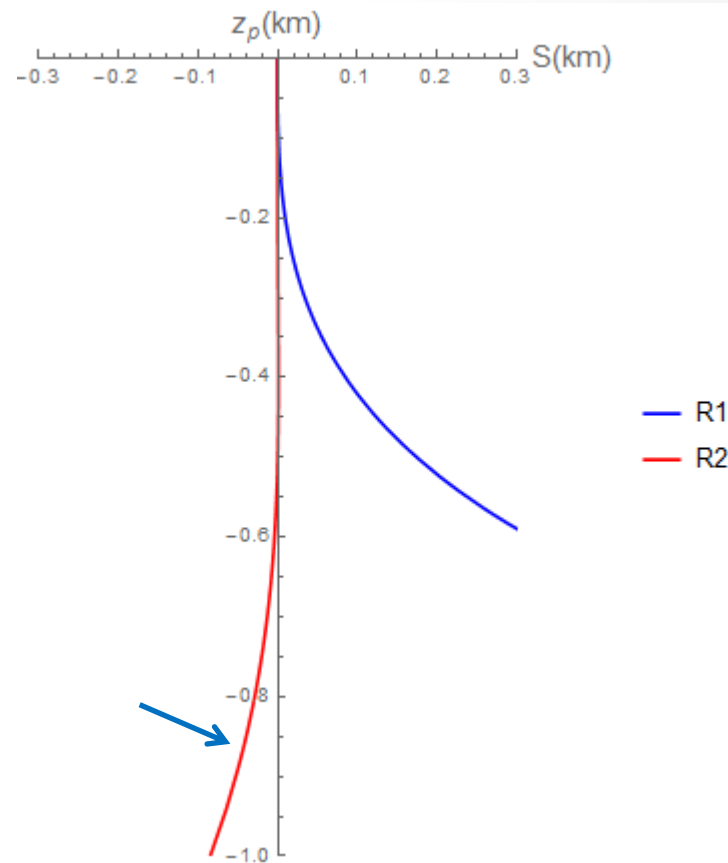
$$R(z_p) = \frac{\sum_{k=0}^L p_k z_p^k}{1 + \sum_{k=0}^M q_k z_p^k}$$

$$\Delta x_p = a_1 z_p + a_2 z_p^2 + a_3 z_p^3 + a_4 z_p^4,$$

$$a_\infty = \lim_{z_p \rightarrow \infty} \left( \frac{\Delta x_p}{z_p} \right),$$

$$R_1(z_p) = \frac{p_1 z_p + p_2 z_p^2}{1 + q_1 z_p}$$

$$R_2(z_p) = \frac{P_1 z_p + P_2 z_p^2 + P_3 z_p^3}{1 + Q_1 z_p + Q_2 z_p^2}$$



$$V_0 = 2 \text{ km/s}, G = 1.5 \text{ s}^{-1}, \varepsilon = 0.22, \eta = 0.1$$

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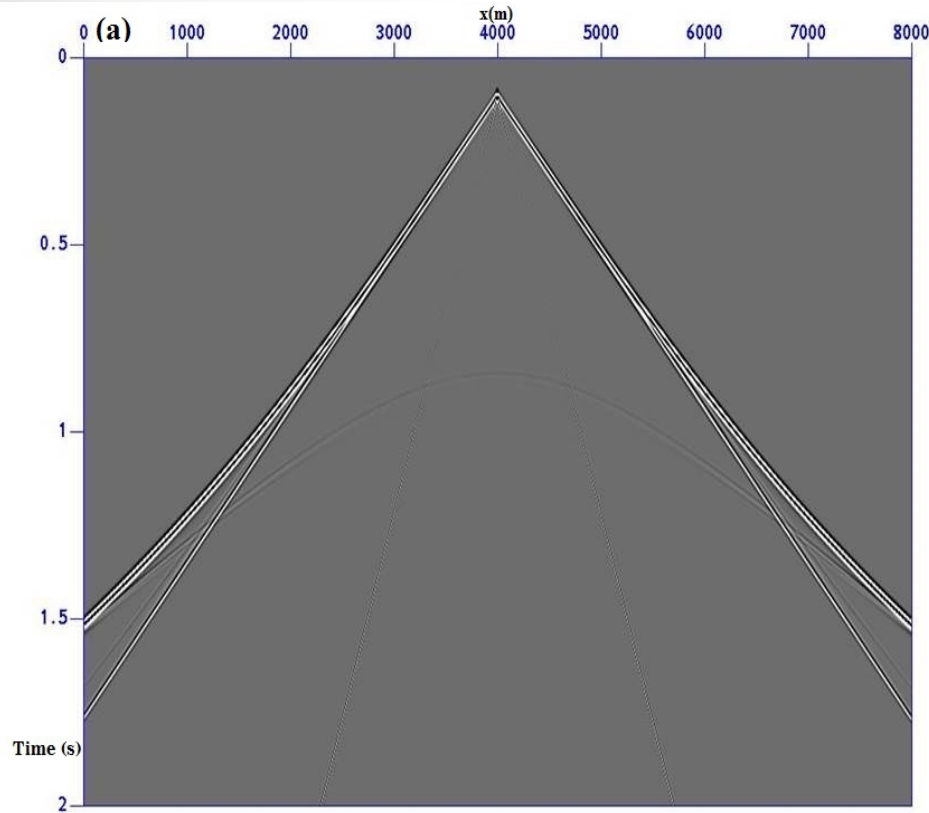
✦ 3 Semblance analysis & anisotropy estimation

4 Numerical examples & different parameterization

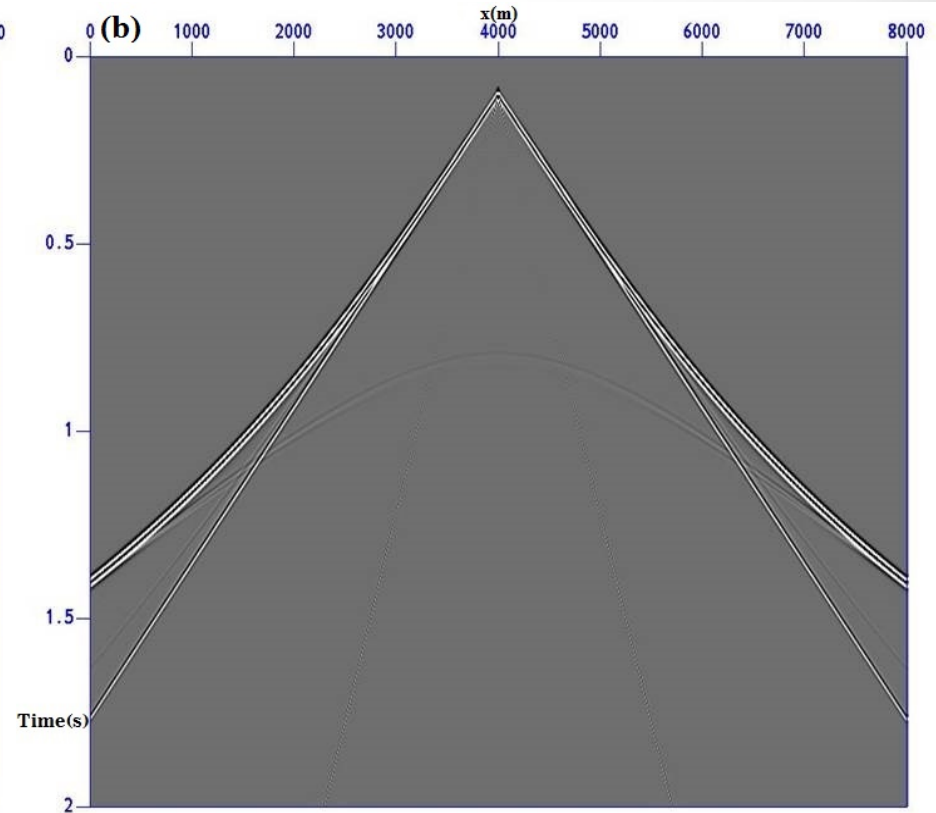
5 Conclusions

# Semblance analysis & anisotropy estimation

Smaller  $G = 1.5 \text{ s}^{-1}$



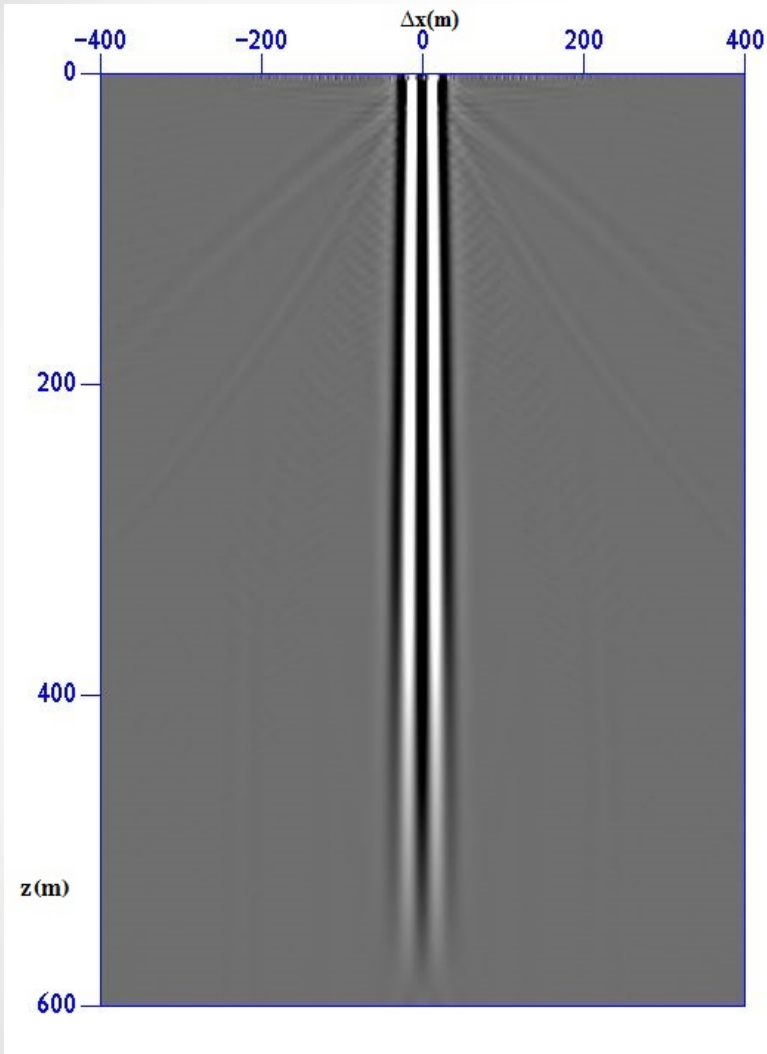
Larger  $G = 2 \text{ s}^{-1}$



Anisotropic modeling

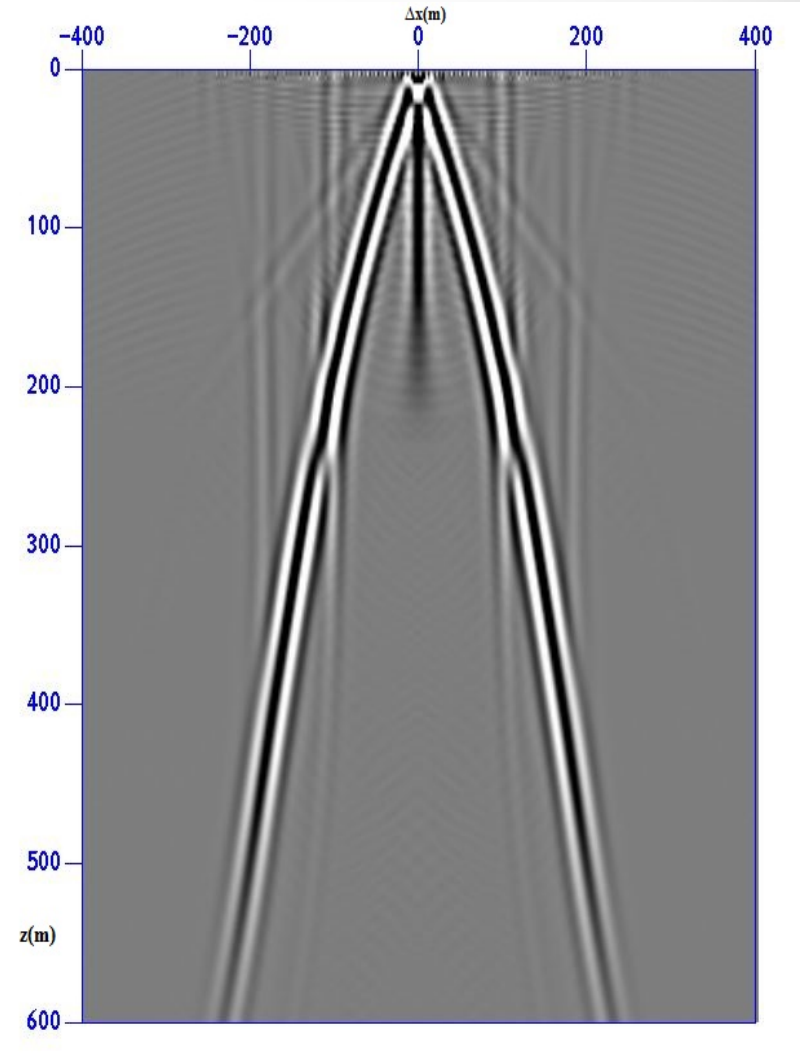
$$V_0 = 2 \text{ km/s}, \varepsilon = 0.22, \eta = 0.1$$

# Semblance analysis & anisotropy estimation



Anisotropic RTM

$$\varepsilon = 0.22, \eta = 0.1$$

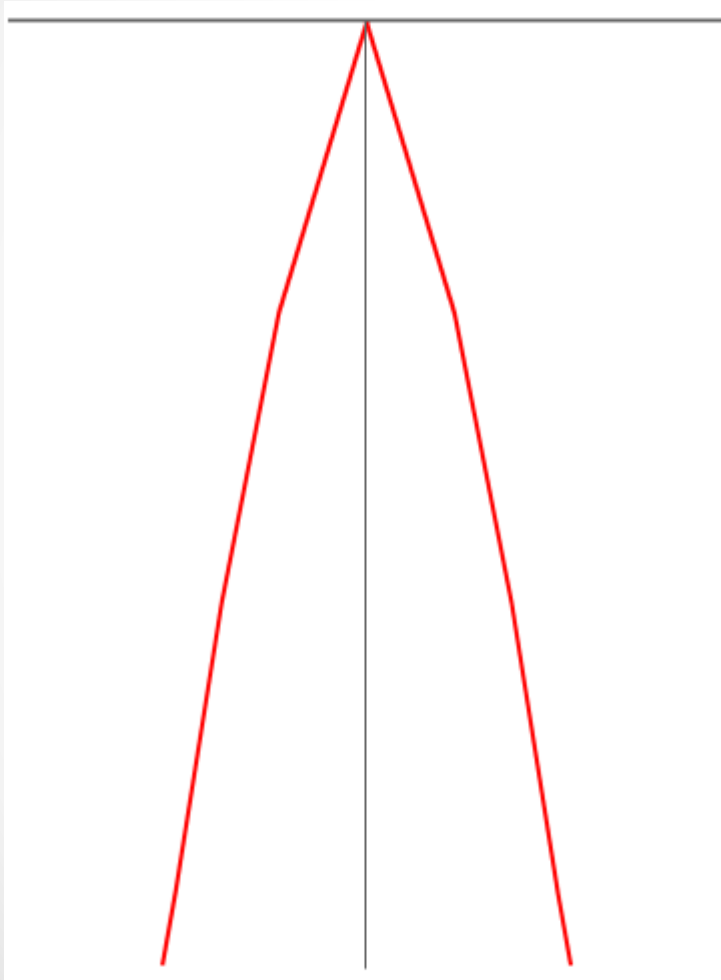


Isotropic RTM

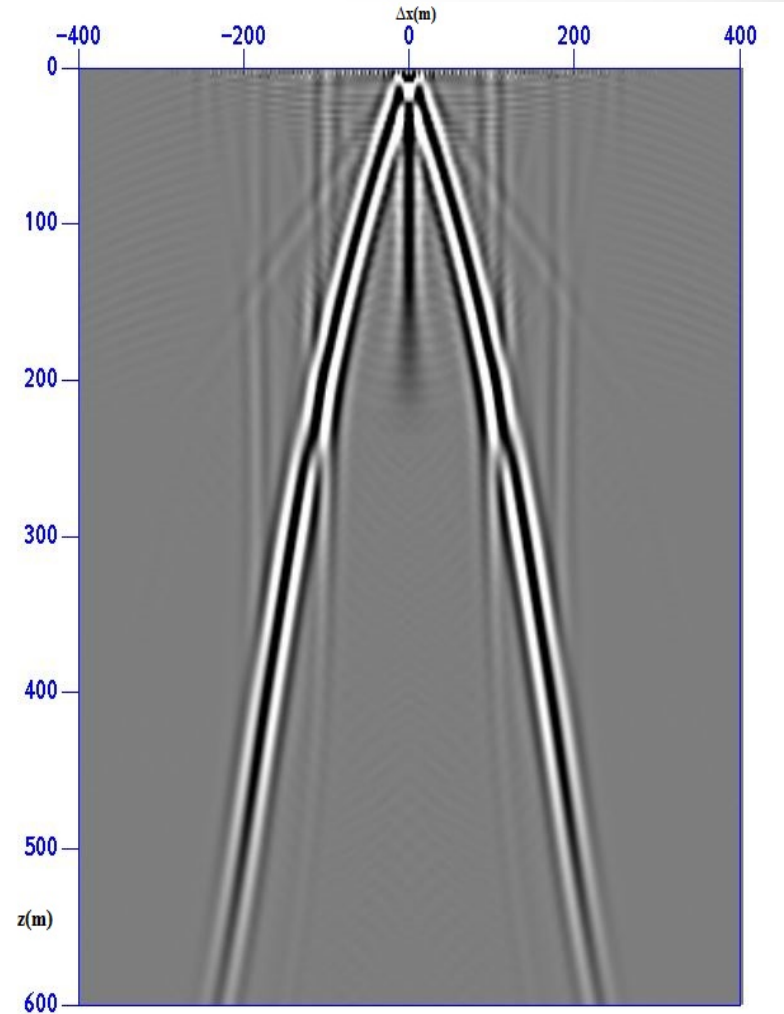
$$\varepsilon = 0, \eta = 0$$

# Semblance analysis & anisotropy estimation

Rational approximation



Synthetic seismic data

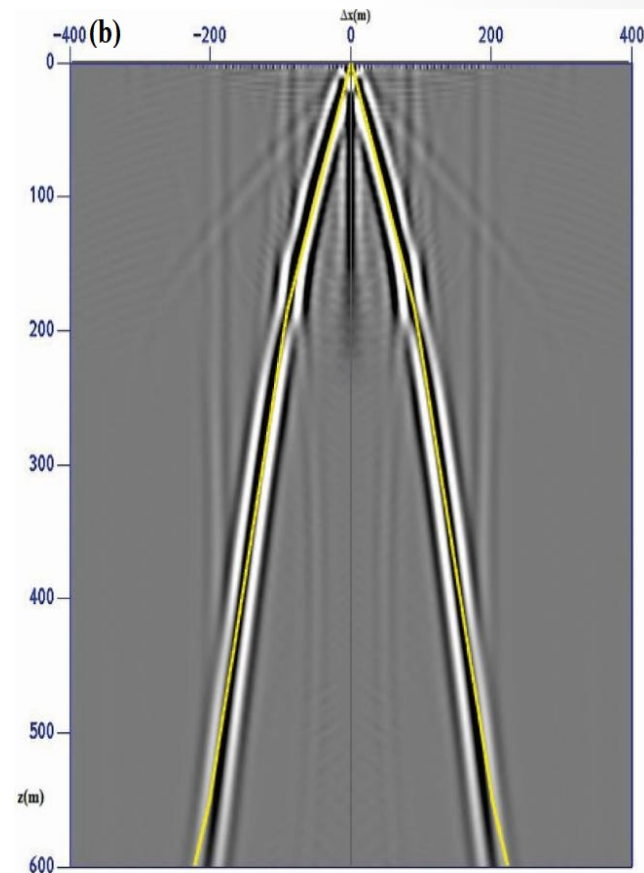
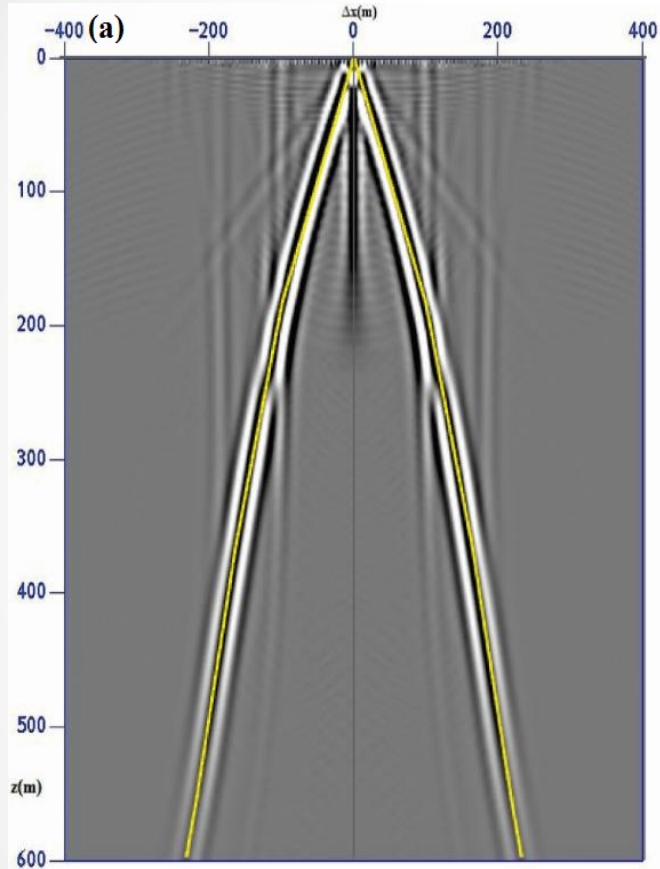


•  $V_0 = 2 \text{ km/s}, G = 1.5 \text{ s}^{-1}, \varepsilon = 0.22, \eta = 0.1$

# Semblance analysis & anisotropy estimation

$$G = 1.5 \text{ s}^{-1}$$

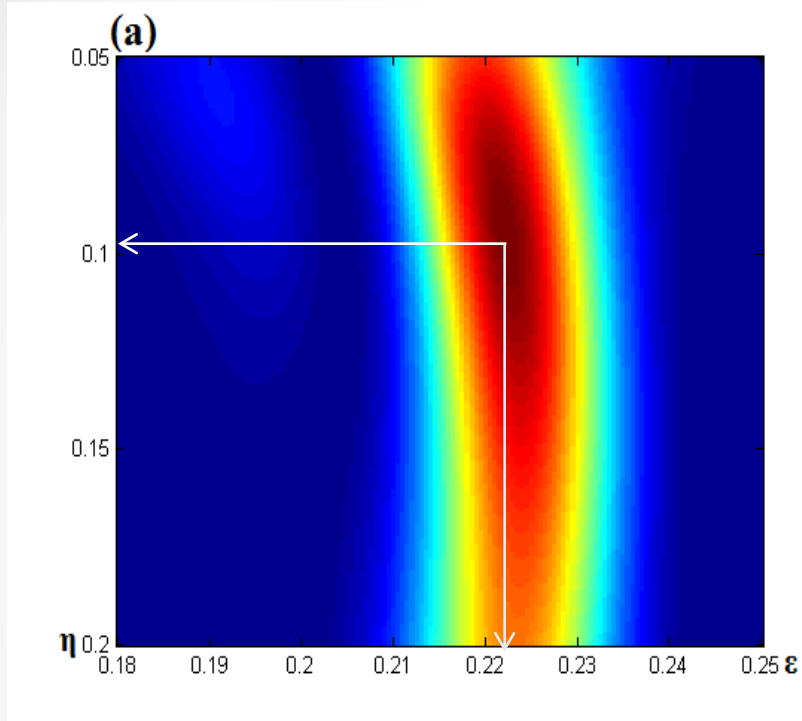
$$G = 2 \text{ s}^{-1}$$



Semblance analysis

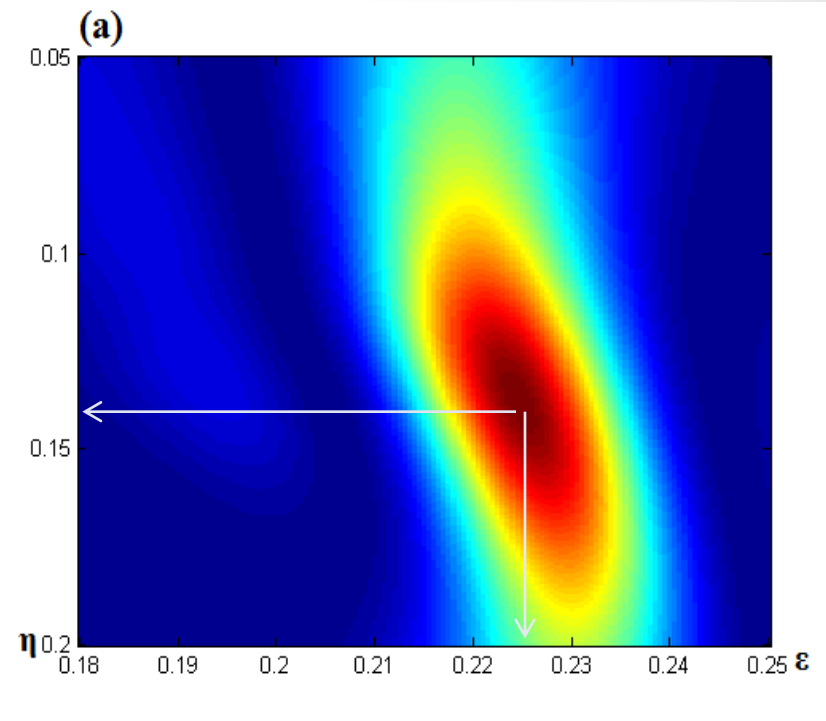
$$SB = \frac{\sum_j^{nz} A_{i(j),j}^2}{\left(\sum_j^{nz} A_{i(j),j}\right)^2},$$

$$G_1 = 1.5 \text{ s}^{-1}$$



$$\Delta \epsilon \approx 0.002, \Delta \eta \approx -0.004$$

$$G_2 = 2 \text{ s}^{-1}$$



$$\Delta \epsilon \approx 0.0075, \Delta \eta \approx 0.0385$$



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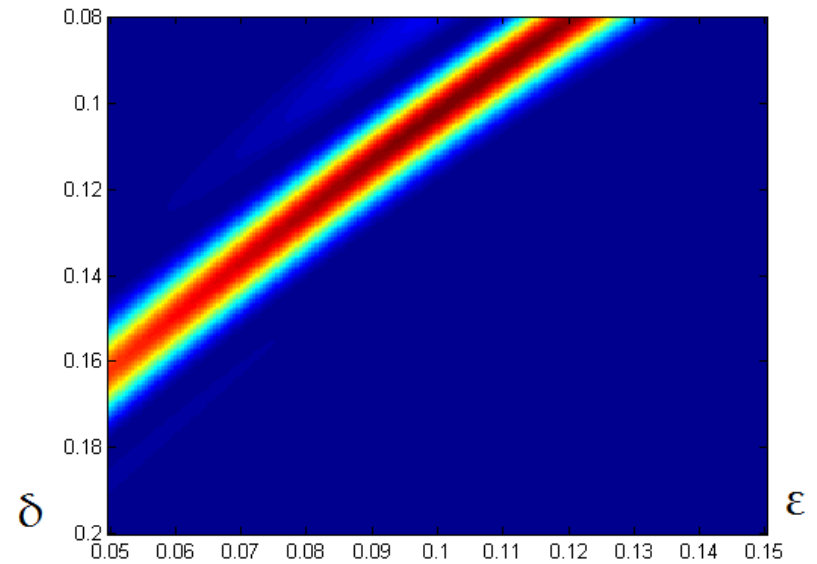
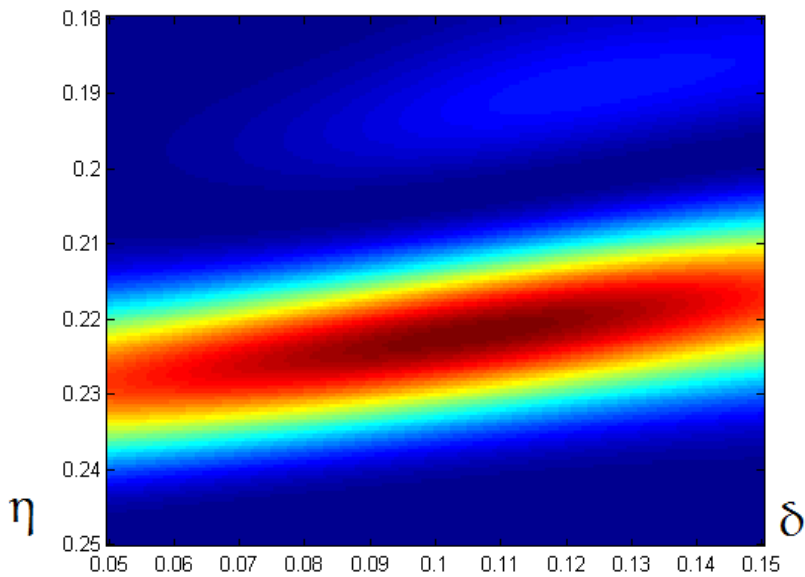
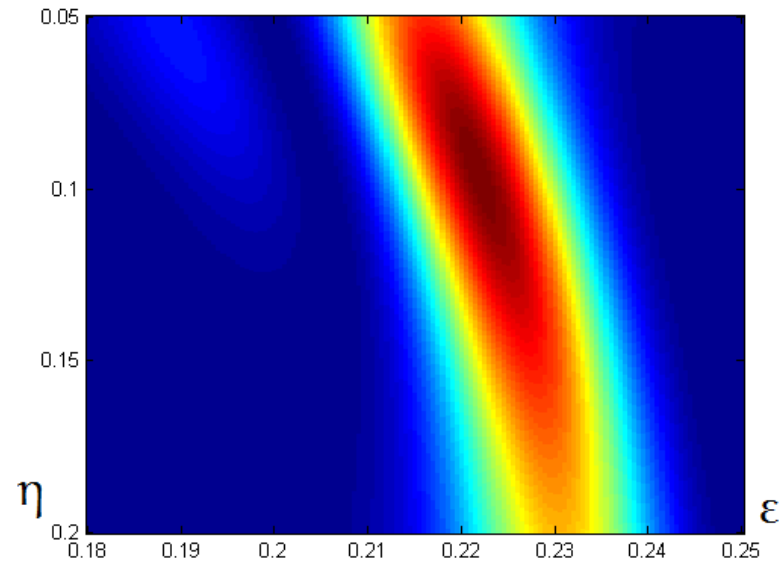
3 Semblance analysis & anisotropy estimation

✦ 4 Numerical examples & different parameterization

5 Conclusions

$\delta, \varepsilon$

$$\eta = \frac{\varepsilon - \delta}{1 + 2\delta}$$



# Different parameterization

$G_1=1.5s^{-1}$		
$V_0, \varepsilon, \eta$	$\Delta\varepsilon \approx 0.002$	$\Delta\eta \approx -0.004$
$V_0, \delta, \eta$	$\Delta\varepsilon \approx 0.0015$	$\Delta\eta \approx -0.0055$
$V_0, \delta, \varepsilon$	$\Delta\varepsilon \approx 0.002$	$\Delta\eta \approx -0.0035$

$G_2=2s^{-1}$		
$V_0, \varepsilon, \eta$	$\Delta\varepsilon \approx 0.0075$	$\Delta\eta \approx 0.0385$
$V_0, \delta, \eta$	$\Delta\varepsilon \approx 0.0080$	$\Delta\eta \approx 0.0385$
$V_0, \delta, \varepsilon$	$\Delta\varepsilon \approx 0.0075$	$\Delta\eta \approx 0.045$

# Outline

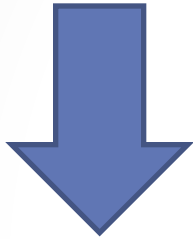
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# Conclusions

- 1 We develop the method to estimate the anisotropy parameters from the residual moveout of the diving wave in a factorized velocity model.
- 2 We analyze different approximations for the imaging moveout, and find that the second order rational approximation is the most accurate one.
- 3 We estimate the anisotropy parameters from the semblance analysis on residual moveout in the RTM image gathers.
- 4 The anisotropy estimation using semblance analysis for all parameterizations is reasonably accurate even for large values of velocity gradients.

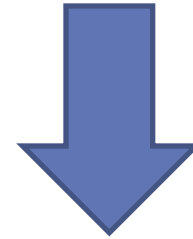
# Discussions

Fix  $V_0, G$



Estimation  $\varepsilon, \eta$

Fix  $V_0$



?

Estimation  $\varepsilon, \eta, G$

# End

Thanks for attention!