

Diffractions: Do we exploit the imaging potential?

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Wave Inversion Technology

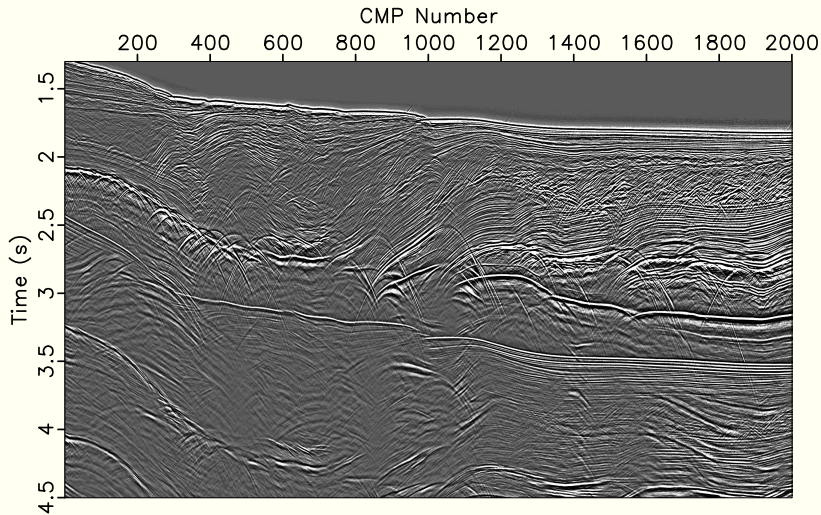


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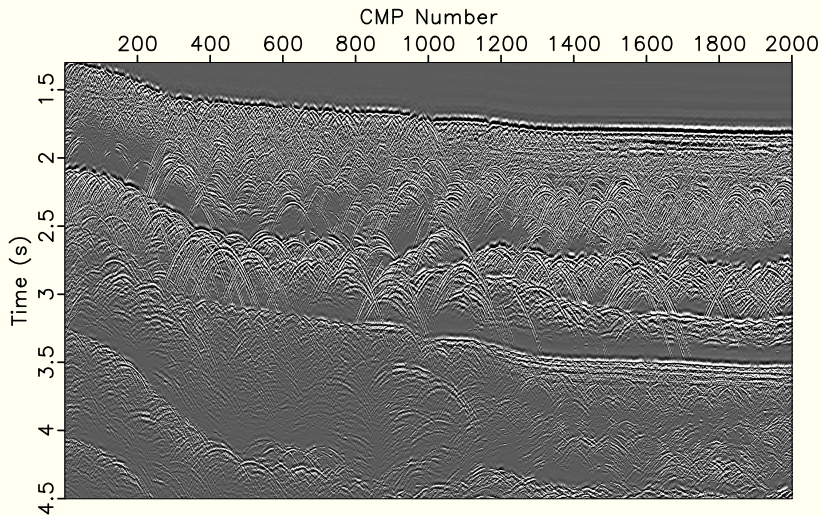


Abundance of Diffractions



Levantine Basin, Mediterranean Sea

Abundance of Diffractions



After diffraction separation



- Abundance of diffractions

Motivation



- Abundance of diffractions
- Illumination

Motivation



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- Illumination
- Small scale features

Motivation



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- Small scale features
- Super-resolution

Motivation



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- FO tomography from ZO data

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- Recipe to merge passive seismic

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Tool: Multi-parameter Processing (CRS)
Application of wavefield attributes



- Common Reflection Surface

Agenda



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- Wavefield attributes

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- Wavefield attributes
- Decomposition principle for diffractions

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- Implications

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- Pitfalls



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- FO diffraction tomography with ZO data

Common Reflection Surface



Zero-offset CRS traveltimes moveout (Müller, 1999):

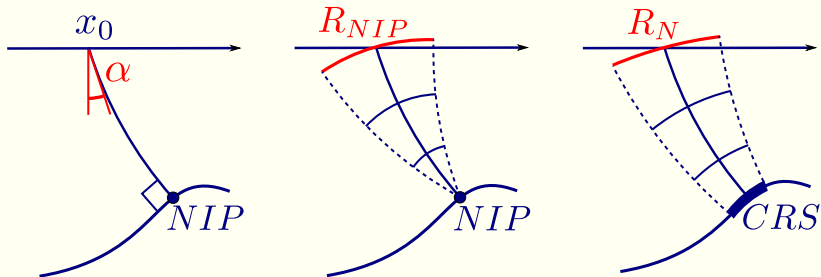
$$t_{ZO}(\Delta x_m, h) = t_0^{ZO} + \frac{2 \sin \alpha_0}{v_0} \Delta x_m + \frac{\cos^2 \alpha_0}{v_0} \left(\frac{\Delta x_m^2}{R_N} + \frac{h^2}{R_{NIP}} \right)$$

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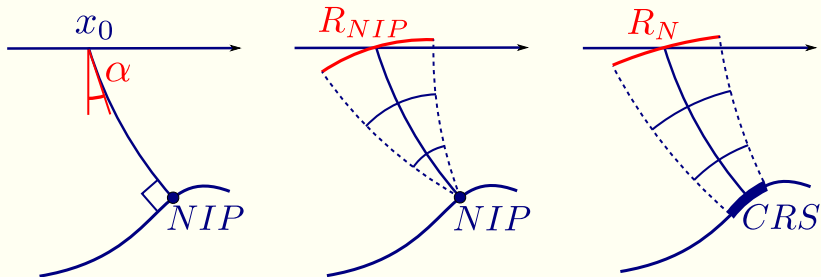


Common Reflection Surface



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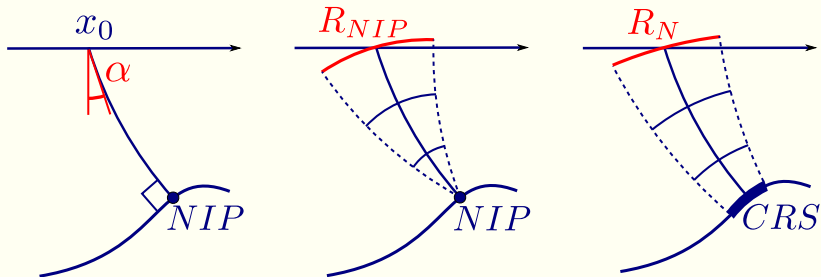
$\Delta x_m = 0 \Rightarrow$ CMP operator

Common Reflection Surface



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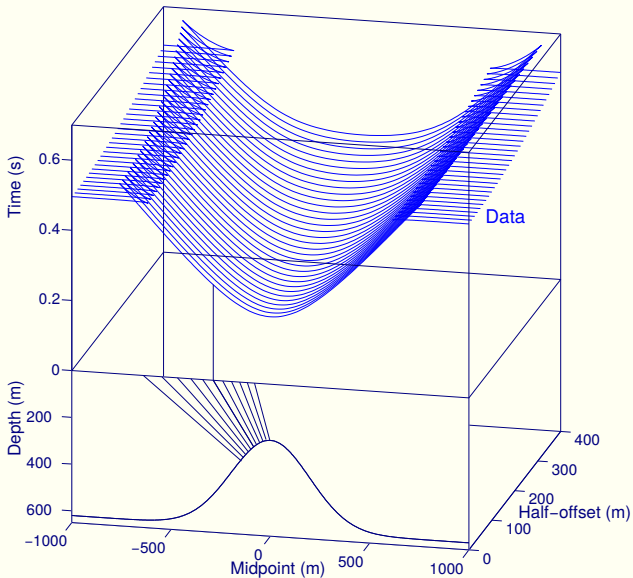
$$t_{ZO}(\Delta x_m, h) = t_0^{ZO} + \frac{2 \sin \alpha_0}{v_0} \Delta x_m + \frac{\cos^2 \alpha_0}{v_0} \left(\frac{\Delta x_m^2}{R_N} + \frac{h^2}{R_{NIP}} \right)$$



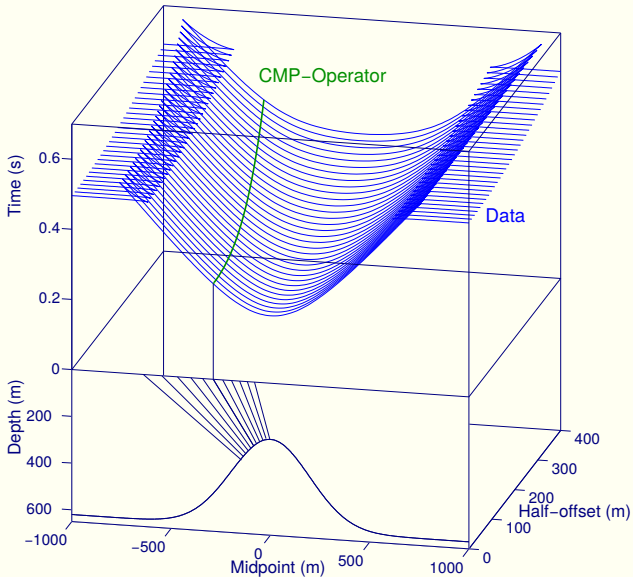
$\Delta x_m = 0 \Rightarrow$ CMP operator

For diffractions $R_N = R_{NIP}$

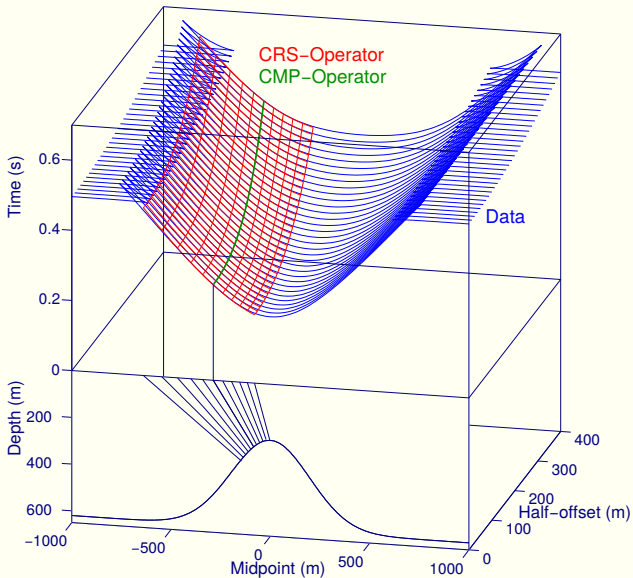
Common Reflection Surface



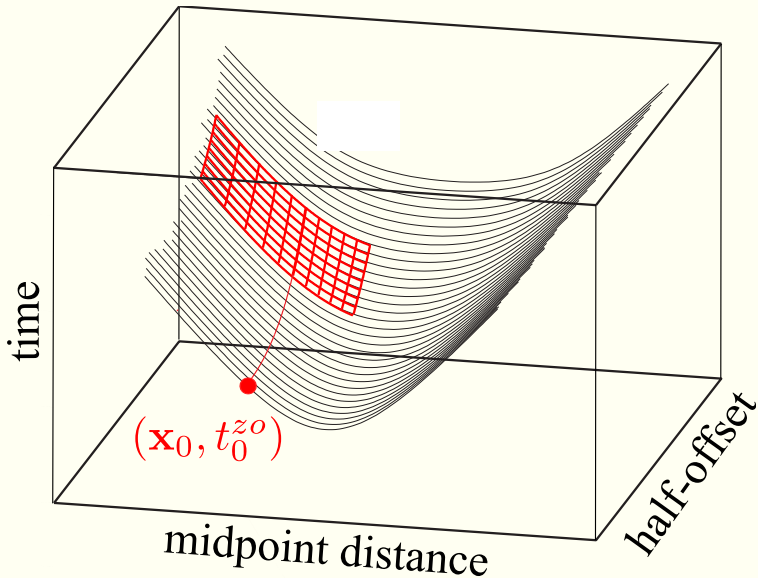
Common Reflection Surface



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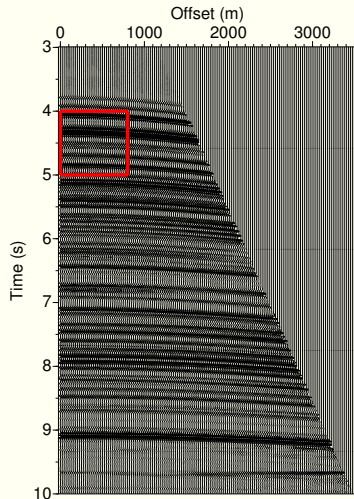
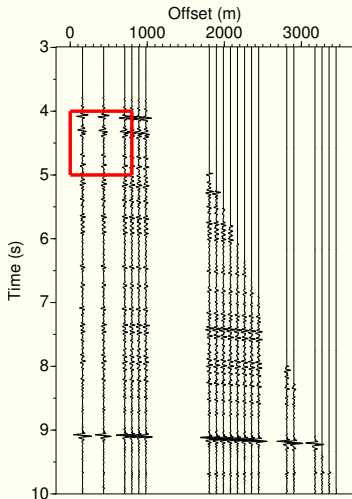
Offset Extrapolation – Partial Stacks



Application Partial Stacks



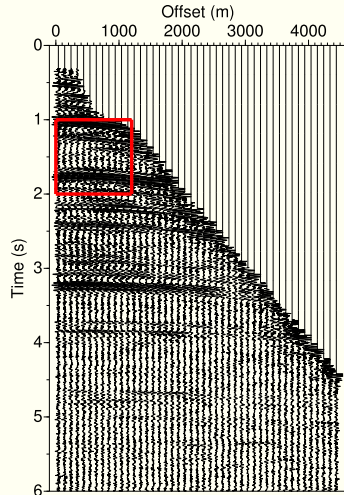
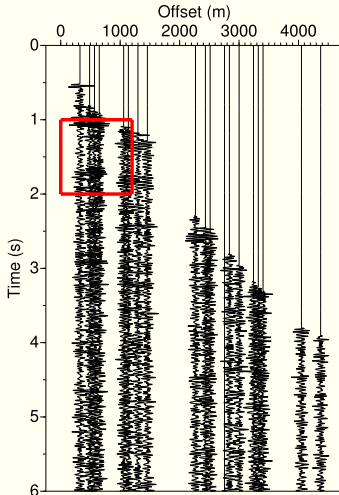
Pre-stack data enhancement and regularization (SIGSBEE):



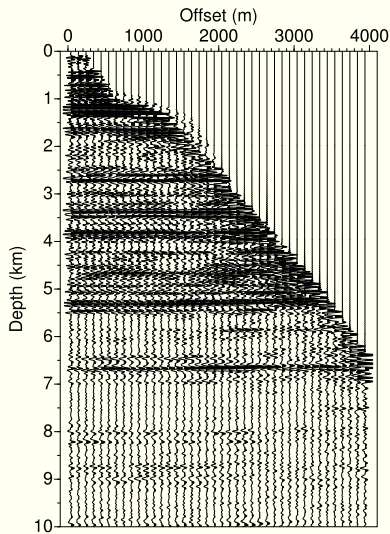
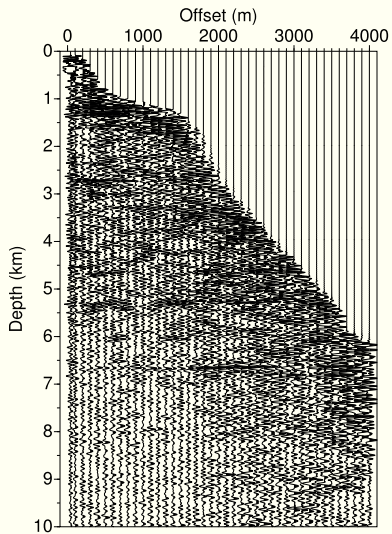
Application Partial Stacks



Pre-stack data enhancement and regularization (low fold field data):



QC Velocity Model



Reflection Traveltime Moveout



Zero-offset CRS (Müller, 1999):

$$t_{ZO}(\Delta x_m, h) = t_0^{ZO} + \frac{2 \sin \alpha_0}{v_0} \Delta x_m + \frac{\cos^2 \alpha_0}{v_0} \left(\frac{\Delta x_m^2}{R_N} + \frac{h^2}{R_{NIP}} \right)$$

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Finite-offset CRS (Zhang et al., 2001):

$$\begin{aligned} t_{FO}(\Delta x_s, \Delta x_g) = & t_0^{FO} + \frac{\sin \alpha_s}{v_s} \Delta x_s + \frac{1}{2} \frac{\cos^2 \alpha_s}{v_s R_s} \Delta x_s^2 \\ & + \frac{\sin \alpha_g}{v_g} \Delta x_g + \frac{1}{2} \frac{\cos^2 \alpha_g}{v_g R_g} \Delta x_g^2 \\ & + B^{-1} \Delta x_s \Delta x_g \end{aligned}$$

Diffraction Traveltime Moveout



Zero-Offset CRS (Müller, 1999):

$$t_{ZO}(\Delta x_m, h) = t_0^{ZO} + \frac{2 \sin \alpha_0}{v_0} \Delta x_m + \frac{\cos^2 \alpha_0}{v_0 R_{NIP}} (\Delta x_m^2 + h^2)$$

Diffraction Traveltime Moveout



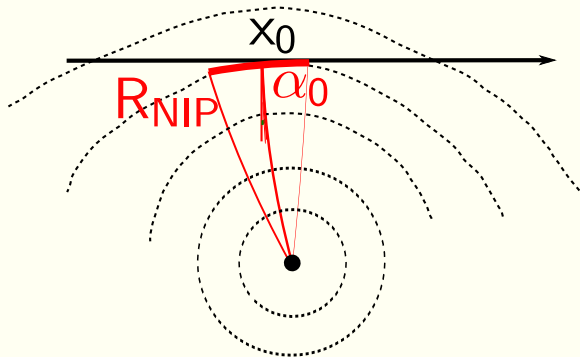
Zero-Offset CRS (Müller, 1999):

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Finite-Offset CRS (Zhang et al., 2001):

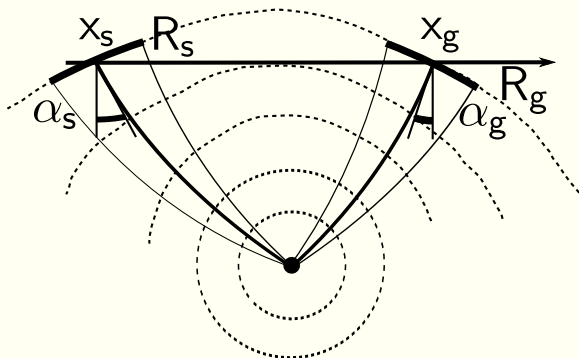
$$t_{FO}(\Delta x_s, \Delta x_g) = t_0^{FO} + \frac{\sin \alpha_s}{v_s} \Delta x_s + \frac{1}{2} \frac{\cos^2 \alpha_s}{v_s R_s} \Delta x_s^2 \\ + \frac{\sin \alpha_g}{v_g} \Delta x_g + \frac{1}{2} \frac{\cos^2 \alpha_g}{v_g R_g} \Delta x_g^2$$

Zero-Offset Diffraction Response



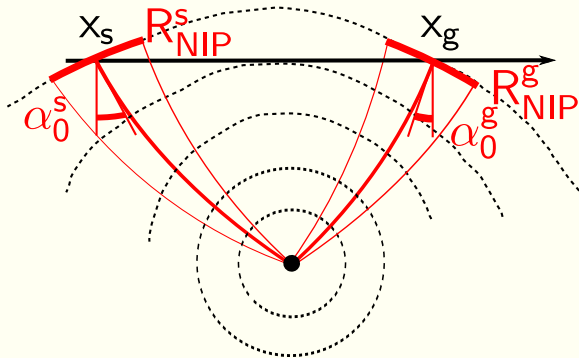
$$t_{ZO}(\Delta x_m) = t_0^{ZO} + \frac{2 \sin \alpha_0}{v_0} \Delta x_m + \frac{\cos^2 \alpha_0}{v_0 R_{NIP}} \Delta x_m^2$$

Finite-Offset Diffraction Response



$$t_{FO}(\Delta X_s, \Delta X_g) = t_0^{FO} + \frac{\sin \alpha_s}{v_s} \Delta X_s + \frac{1}{2} \frac{\cos^2 \alpha_s}{v_s R_s} \Delta X_s^2 \\ + \frac{\sin \alpha_g}{v_g} \Delta X_g + \frac{1}{2} \frac{\cos^2 \alpha_g}{v_g R_g} \Delta X_g^2$$

Decomposition Principle



$$t_{FO}(x_s, x_g, t_0^{FO}, \alpha_s, \alpha_g, R_s, R_g) = \frac{t_{ZO}(x_s, t_0^{ZO,s}, \alpha_0^s, R_{NIP}^s)}{2} + \frac{t_{ZO}(x_g, t_0^{ZO,g}, \alpha_0^g, R_{NIP}^g)}{2}$$

FO Prediction for Diffractions



Decoupling of diffraction raypaths allows to obtain FO diffraction attributes directly from ZO results by

$$\alpha_s = \alpha_0^s$$

$$\alpha_g = \alpha_0^g$$

$$R_s = R_{\text{NIP}}^s$$

$$R_g = R_{\text{NIP}}^g$$

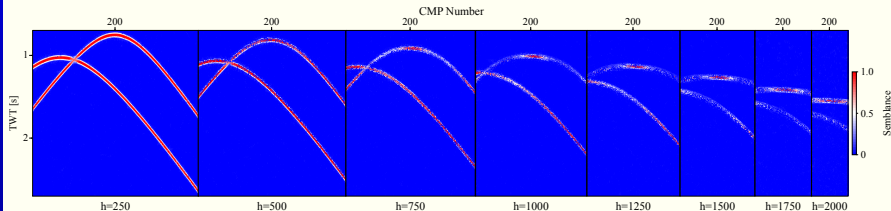
$$t_0^{\text{FO}} = \left(t_0^{\text{ZO},s} + t_0^{\text{ZO},g} \right) / 2$$

These relations are exact for diffractions in arbitrary media provided reciprocity

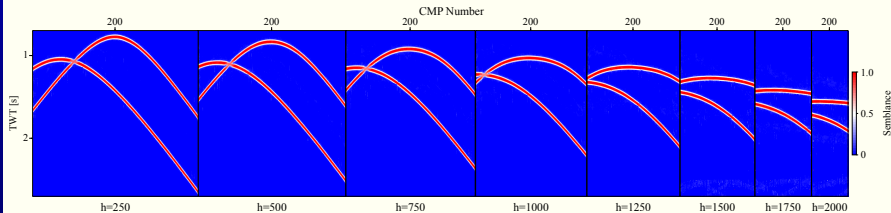
Simple Data Example



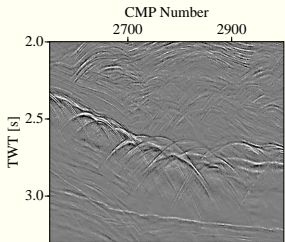
Partial CRS (offsets 500 to 4000 m):



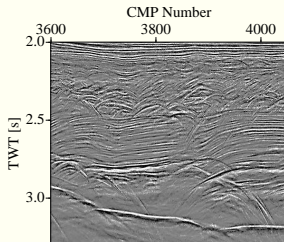
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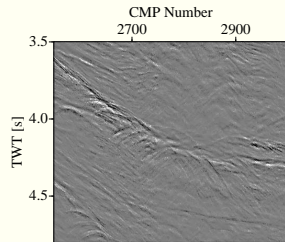
Field Data: Stack (FO 1000 m)



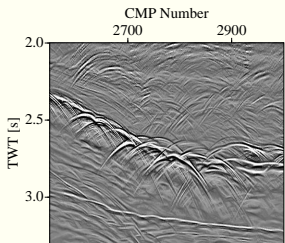
partial CRS



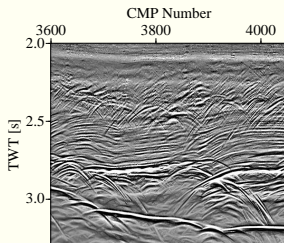
partial CRS



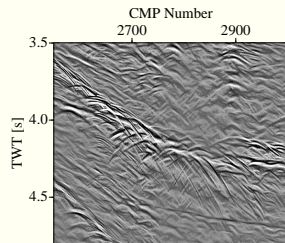
partial CRS



CO prediction

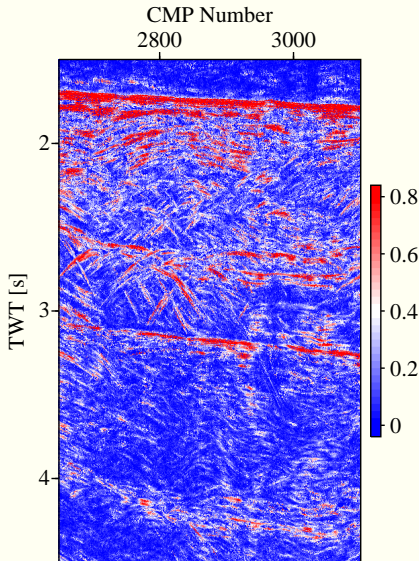


CO prediction

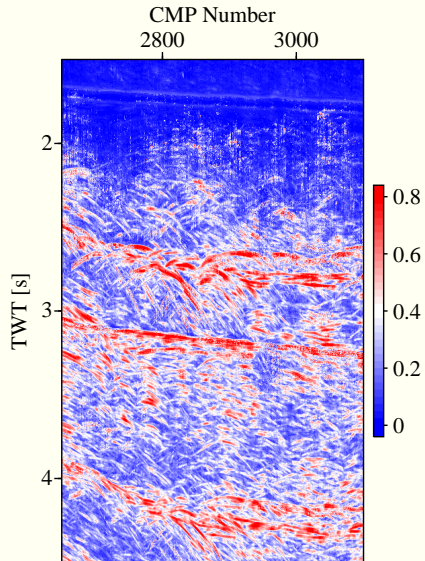


CO prediction

Field Data: Semblance (FO 1000 m)

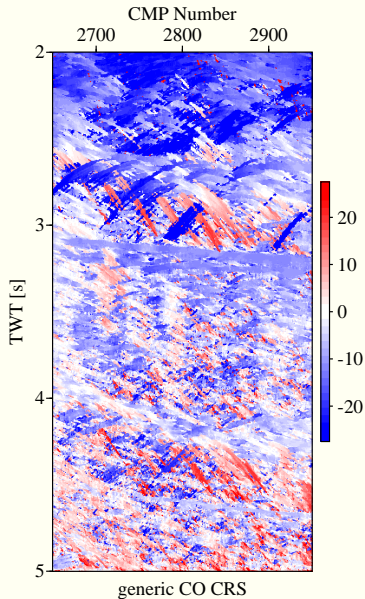
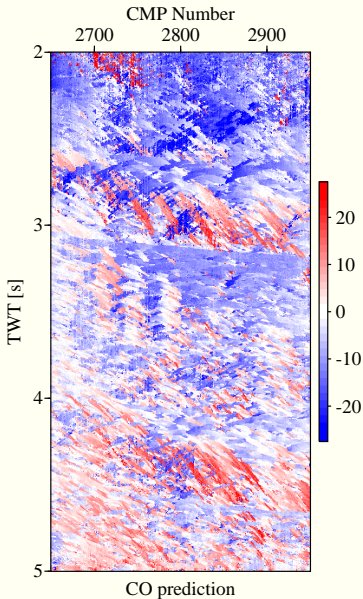


partial CRS



CO prediction

Field data: α_s [°] (FO 1000 m)



Implications



- One offset does it all

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- Accurate ZO-based prediction of FO diffraction operators



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- Accurate ZO-based prediction of FO diffraction operators
- Accurate prestack diffraction enhancement solely based on ZO CRS attributes



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- Accurate ZO-based prediction of FO diffraction operators
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- High quality FO diffraction attributes



- FO prediction results depends on quality of ZO results



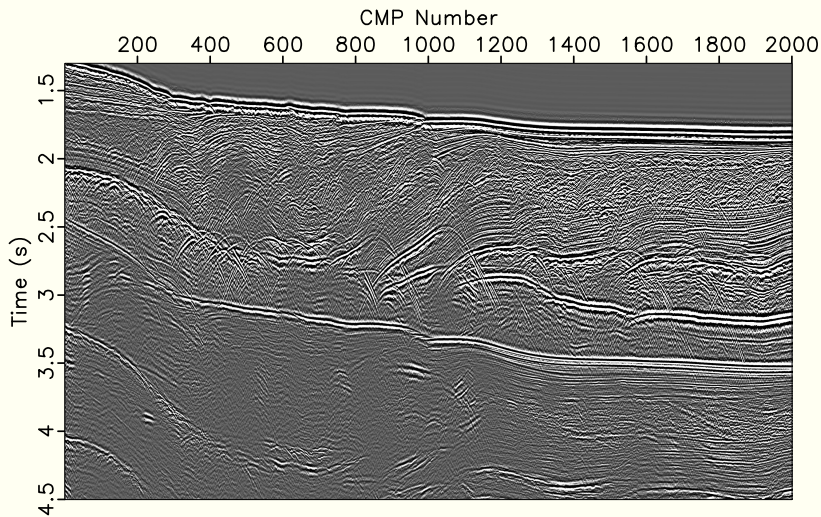
- FO prediction results depends on quality of ZO results

- Optimization

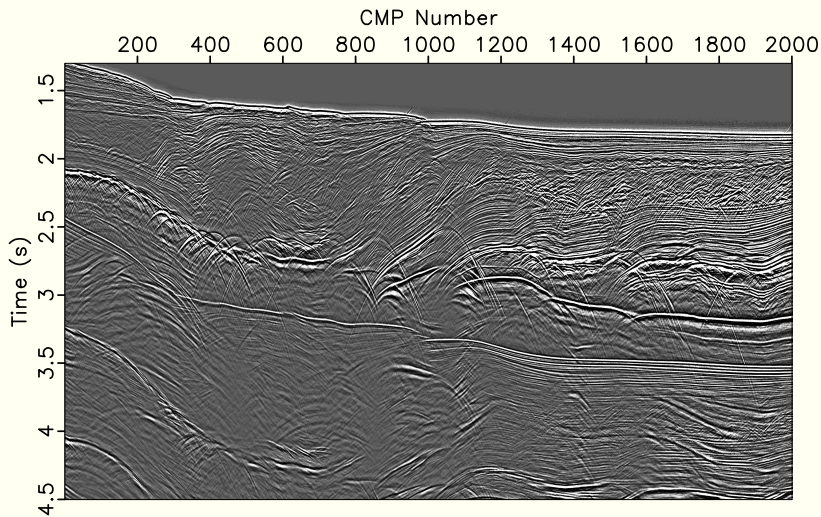


- FO prediction results depends on quality of ZO results
- Optimization
- Conflicting dips

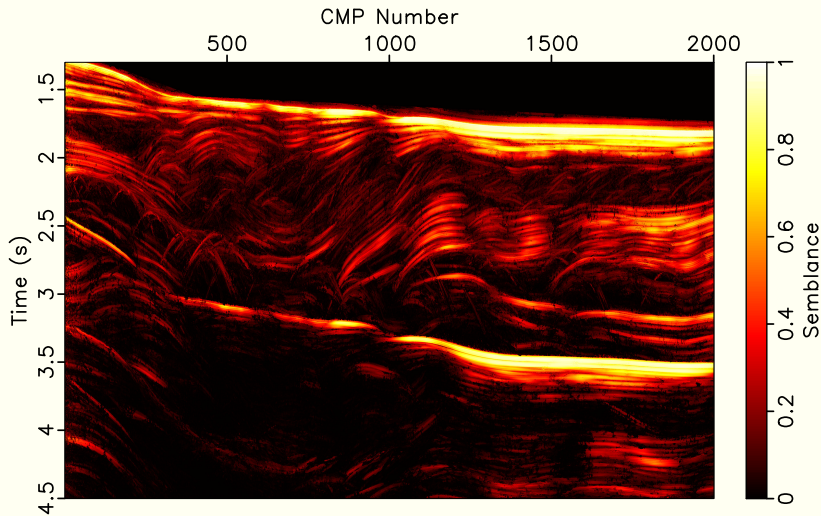
Local Optimization



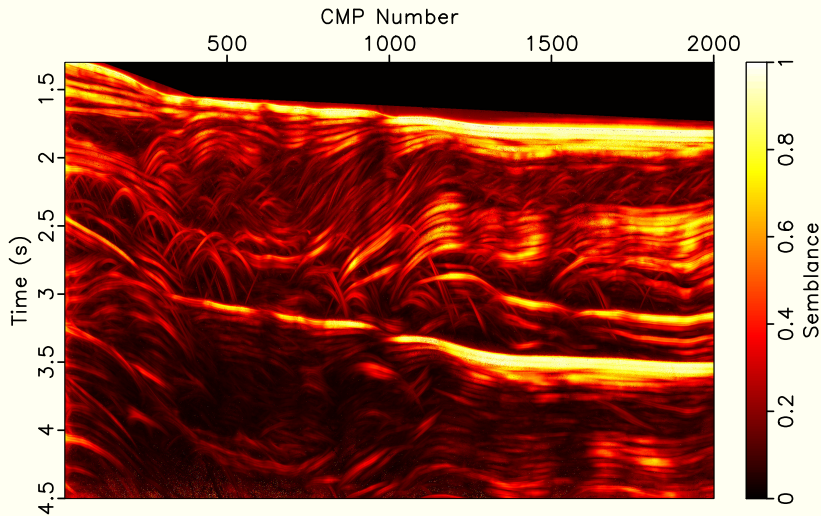
Global Optimization



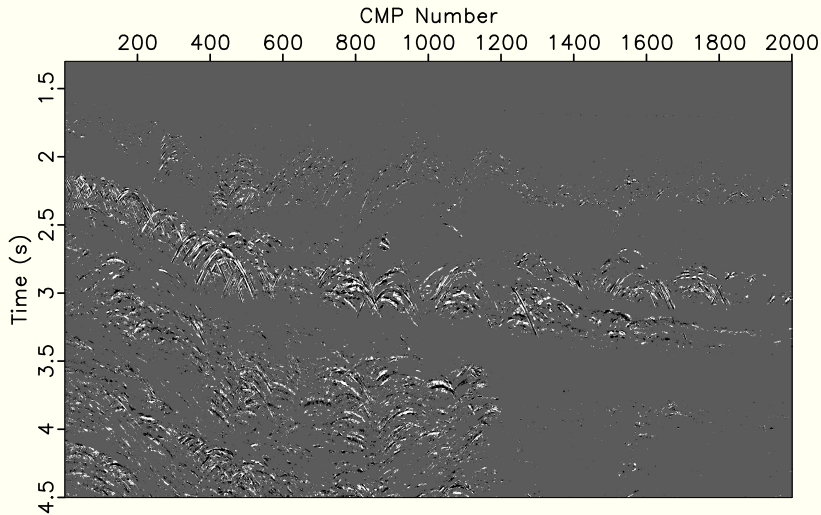
Local Optimization



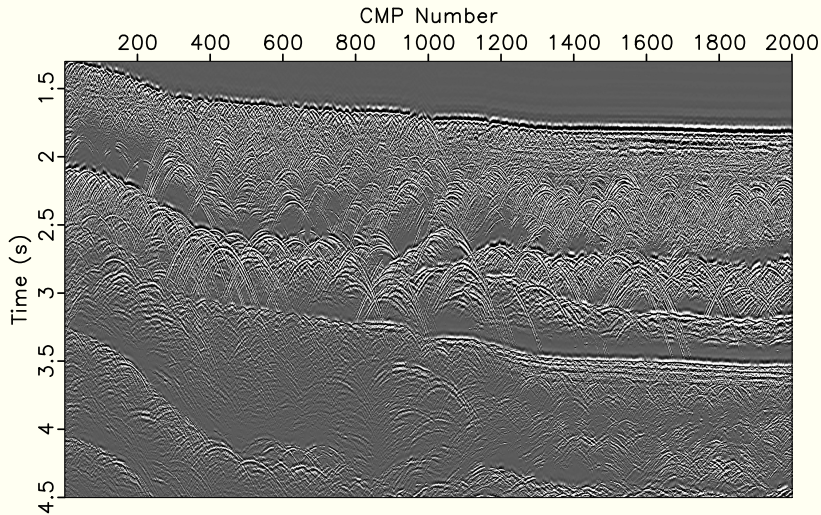
Global Optimization



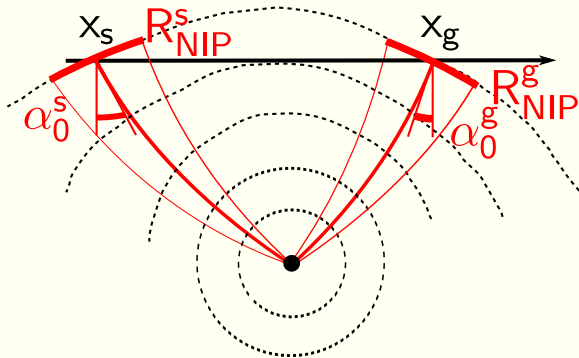
Separation Without Conflicting Dips



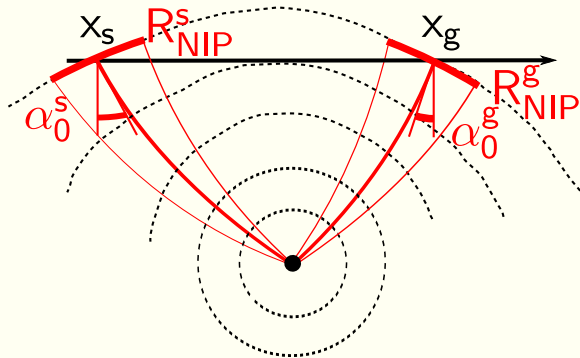
Separation With Conflicting Dips



FO Diffraction Tomography

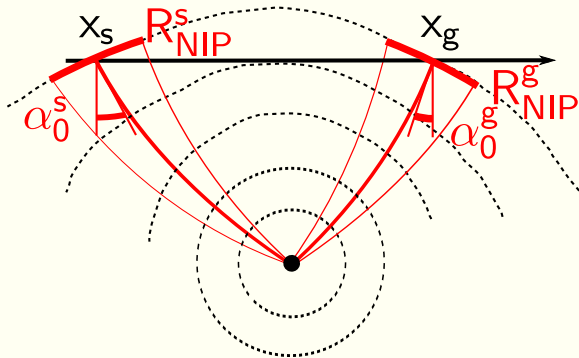


FO Diffraction Tomography



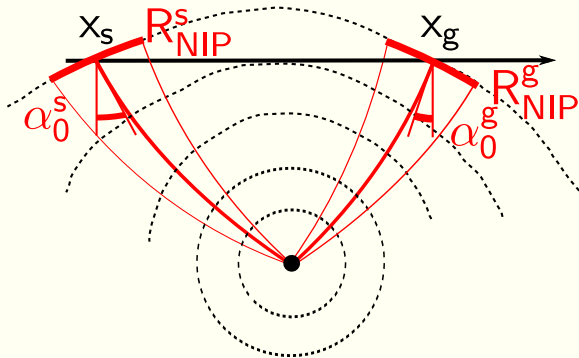
- Input form ZO data

FO Diffraction Tomography



- Input form ZO data
- Entirely based on NIP rays

FO Diffraction Tomography



- Input form ZO data
- Entirely based on NIP rays
- Uses NIP-wave tomography

Properties



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- Highly redundant (lateral resolution)

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- Can be simultaneously applied to active and passive seismic data



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- Gateway to measured Green's functions

Conclusions



Decomposition principle allows unique applications:

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Decomposition principle allows unique applications:

- Data enhancement and regularization



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- Diffraction separation (pre- and post stack)



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- FO tomography with Z0 data



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- High resolution velocity model building



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- Green's function determination



Decomposition principle allows unique applications:

- Data enhancement and regularization
- Diffraction separation (pre- and post stack)
- FO tomography with Z0 data
- High resolution velocity model building
- Green's function determination
- Imaging with full coda (super-resolution)

Acknowledgments



- Applied Seismics Group, University of Hamburg, for enlightening discussions
- TGS-NOPEC for field data
- NORSAR for ray software
- SMAART JV for SIGSBEE
- Sponsors of the WIT consortium for financial support