

Reverse-time demigration using the extended imaging condition

Wiktor Weibull and Børge Arntsen



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NTNU – Trondheim
Norwegian University of
Science and Technology

Outline

- 1 Introduction
- 2 Theory
- 3 Applications
- 4 Summary and remarks

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Introduction

- The forward and inverse process of migration and demigration or remodeling has many interesting applications in seismic data processing
- Need for a method to transform seismic reflection data from the image-domain back to the prestack reflection data domain
- We developed a method to reconstruct seismic reflection data from common image point gathers constructed with RTM using an extended imaging condition
- The method is not directly dependent on the accuracy of velocity model

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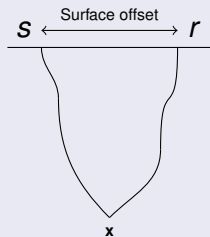
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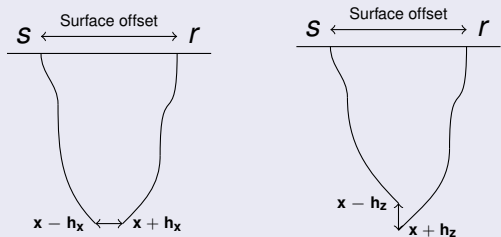
Extended imaging condition

Classical IC



[Claerbout, 1971]

Extended IC



[Rickett and Sava, 2002]

Reverse-time migration

Migration

$$R(\mathbf{x}, \mathbf{h}) = \int d\mathbf{s} \int dt W_s(\mathbf{x} - \mathbf{h}, t, \mathbf{s}) \times \\ \int d\mathbf{r} \int dt' G(\mathbf{x} + \mathbf{h}, t; \mathbf{r}, t') P(\mathbf{r}, t', \mathbf{s}) \quad (1)$$

$$W_s(\mathbf{x}, t, \mathbf{s}) = \int d\mathbf{s}' \int dt' G(\mathbf{x}, t; \mathbf{s}', t') S(\mathbf{s}', t') \quad (2)$$

Reverse-time demigration

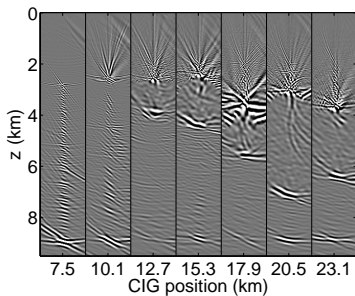
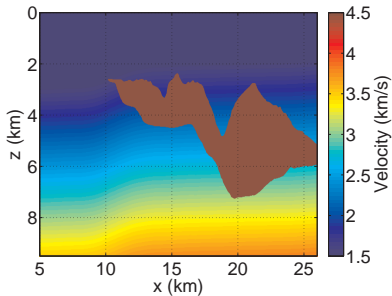
Migration

$$R(\mathbf{x}, \mathbf{h}) = \int d\mathbf{s} \int dt W_{\mathbf{s}}(\mathbf{x} - \mathbf{h}, t, \mathbf{s}) \times \int d\mathbf{r} \int dt' G(\mathbf{x} + \mathbf{h}, t; \mathbf{r}, t') P(\mathbf{r}, t', \mathbf{s}) \quad (3)$$

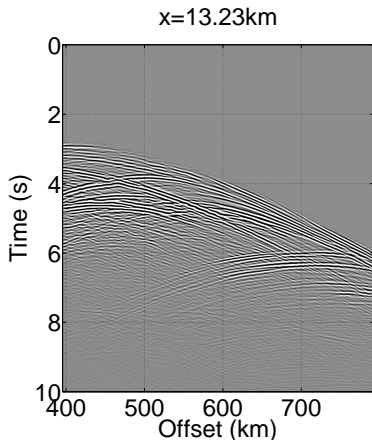
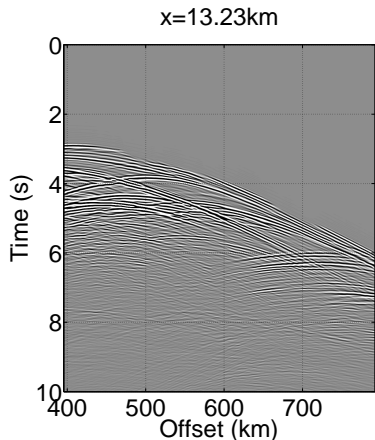
Modeling (Born)

$$P(\mathbf{r}, t, \mathbf{s}) = \int d\mathbf{x} \int dt' G(\mathbf{r}, t; \mathbf{x}, t') \times \int d\mathbf{h} \frac{\partial^2 R}{\partial z^2}(\mathbf{x} - \mathbf{h}, \mathbf{h}) W_{\mathbf{s}}(\mathbf{x} - 2\mathbf{h}, t', \mathbf{s}) \quad (4)$$

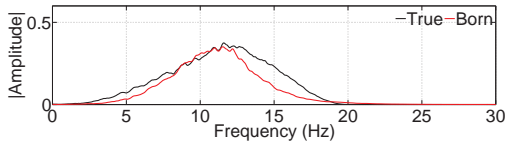
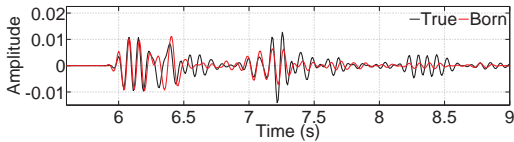
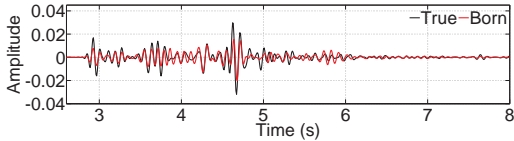
Modeling (Born)



Modeling (Born)



Modeling (Born)



Inversion

Least squares error function

$$J = \frac{1}{2} \int d\mathbf{x} \int d\mathbf{h} \left[\frac{\partial R^0}{\partial \mathbf{z}}(\mathbf{x}, \mathbf{h}) - \frac{\partial R}{\partial \mathbf{z}}(\mathbf{x}, \mathbf{h}) \right]^2 \quad (5)$$

Inversion

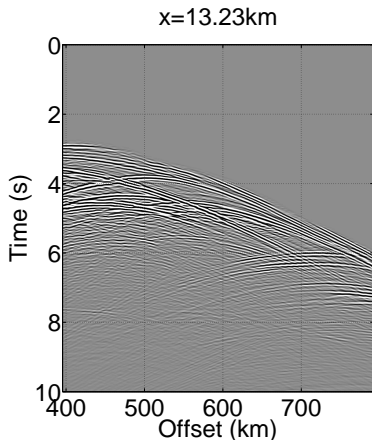
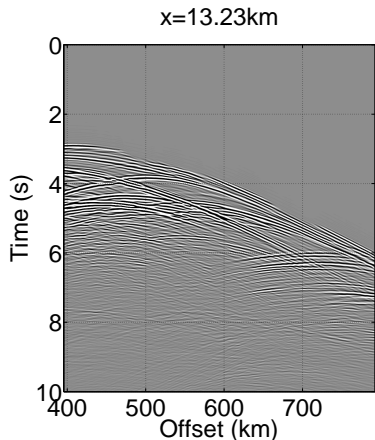
Steepest descent

$$P_{i+1}(\mathbf{x}, t, s) = P_i(\mathbf{x}, t, s) - \alpha_i \frac{\partial J}{\partial P_i}(\mathbf{x}, t, s) \quad (6)$$

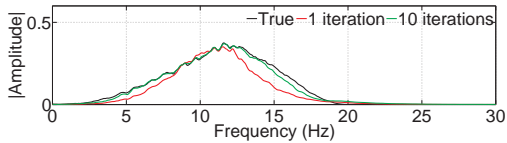
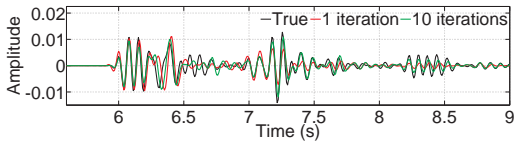
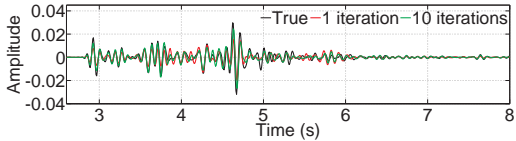
Gradient

$$\frac{\partial J}{\partial P_i}(\mathbf{x}, t, s) = \int d\mathbf{x}' \int dt' G(\mathbf{x}, t; \mathbf{x}', t') \times \int d\mathbf{h} \frac{\partial^2 \Delta R_i}{\partial z^2}(\mathbf{x}' - \mathbf{h}, \mathbf{h}) W_s(\mathbf{x}' - 2\mathbf{h}, t', s) \quad (7)$$

Inversion



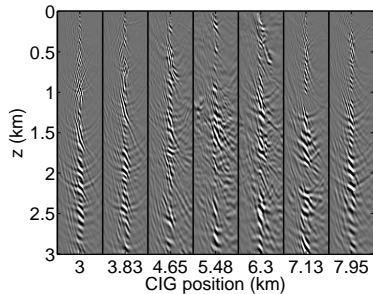
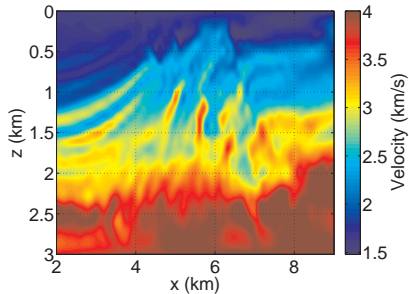
Inversion



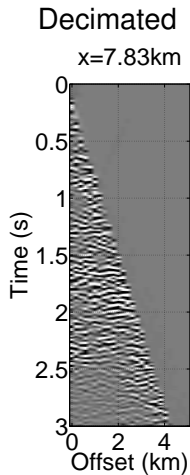
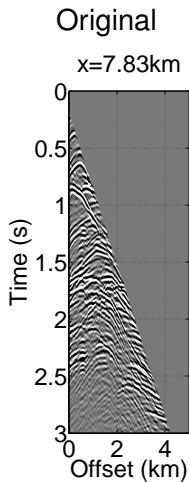
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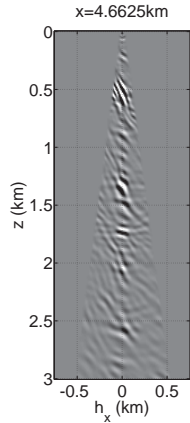
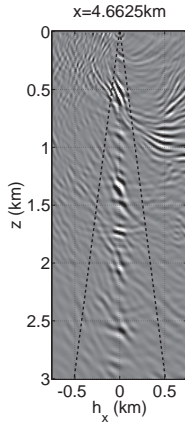
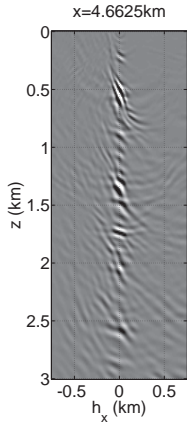
Data reconstruction



Dip aliased shot gathers

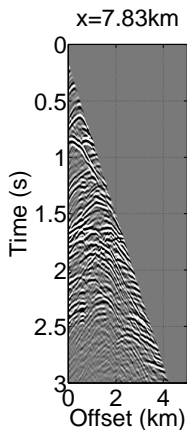


CIGs and dip aliasing

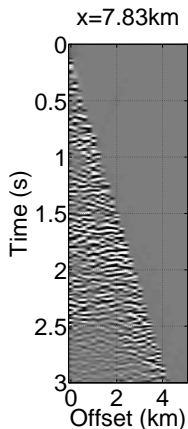


Demigration

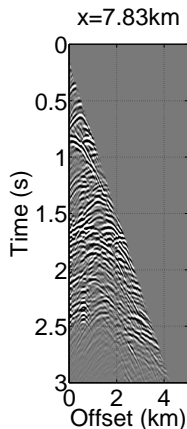
Original



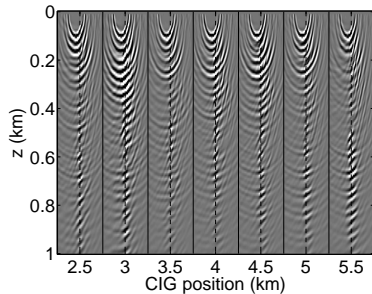
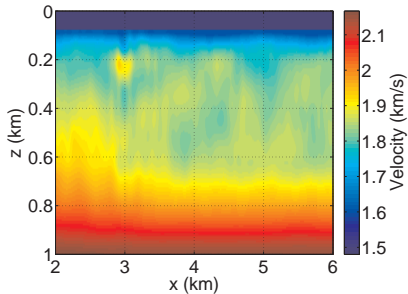
Decimated



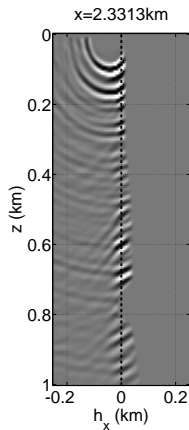
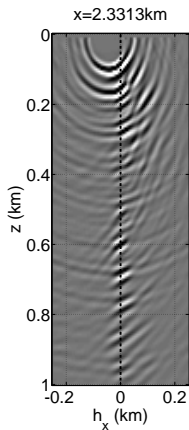
Reconstructed



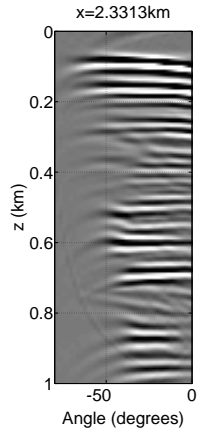
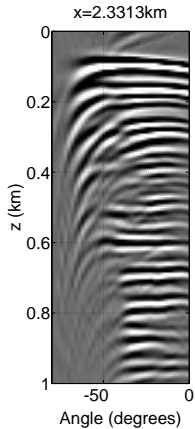
Multiple attenuation



CIGs and multiples

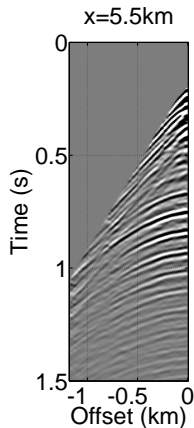


CIGs and multiples

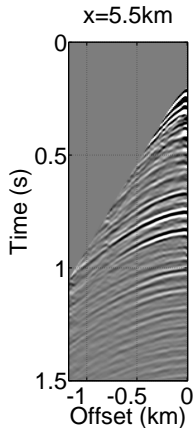


Demigration

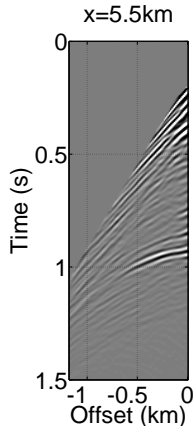
Original



Demigrated



Difference



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Summary and remarks

- We developed a method to reconstruct seismic reflection data from CIGs constructed with RTM using an extended imaging condition
- The numerical experiments show that the method allows kinematic reconstruction of the data after 1 iteration
- On the other hand, amplitude reconstruction requires many iterations
- The method can be used to process data acquired over complex geological media

Acknowledgments



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Bibliography

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