## Single-station SVD-based polarization filtering: theoretical and synthetic data investigations

Olena Tiapkina, Martin Landrø and Yuriy Tyapkin

NTNU Trondheim, Norway

## Outline

- Introduction
- Description of polarization filter
- Theoretical investigation
- Stochastic simulation of synthetic data
- Conclusions



Everypass filter Noise (ground roll) Signal (reflected waves) Frequency Polarization properties of seismic waves Linearly polarized reflected waves

$$S_{x}(\omega) = k_{x}A(\omega)e^{i\varphi(\omega)}$$
$$S_{y}(\omega) = k_{y}A(\omega)e^{i\varphi(\omega)}$$
$$S_{z}(\omega) = k_{z}A(\omega)e^{i\varphi(\omega)}$$

Elliptically polarized ground roll  $R_{x}(\omega) = q_{x}B(\omega)e^{i\psi(\omega)}$   $R_{y}(\omega) = q_{y}B(\omega)e^{i\psi(\omega)}$   $R_{z}(\omega) = q_{z}B(\omega)e^{i\left[\psi(\omega) + \frac{\pi}{2}\right]}$ 

Ground roll has relatively high energy

Ground roll has relatively low apparent velocity

## Matrix forming in a sliding window

Jackson, G.M. et.al, 1991



$$\mathbf{W} = (\mathbf{w}_{x} \ \mathbf{w}_{y} \ \mathbf{w}_{z})$$

$$Dim (\mathbf{W}) = N \times 3$$

$$\mathbf{W} = \mathbf{E}_{1} + \mathbf{E}_{2} + \mathbf{E}_{3} = \sum_{i=1}^{3} \sigma_{i} \mathbf{u}_{i} \mathbf{v}_{i}^{T}$$

$$without random noise:$$
Elliptical polarization  
(ground roll):  
rank(\mathbf{W}) = 2
$$\mathbf{W} = \mathbf{E}_{1} + \mathbf{E}_{2}$$

$$\mathbf{W} = \mathbf{E}_{1} + \mathbf{E}_{2}$$

$$\mathbf{W} = \mathbf{E}_{1}$$

 $\begin{array}{ll} \mathbf{E}_1, \, \mathbf{E}_2 \, \text{and} \, \mathbf{E}_3 & \text{eigenimages or principal components} \\ \mathbf{u}_1, \, \mathbf{u}_2 \, \text{and} \, \mathbf{u}_3 & \text{left singular vectors} \\ \mathbf{v}_1, \, \mathbf{v}_2 \, \text{and} \, \mathbf{v}_3 & \text{right singular vectors} \\ \sigma_1, \, \sigma_2 \, \text{and} \, \sigma_3 & \text{singular values} \, (\sigma_1 \! \geq \! \sigma_2 \! \geq \! \sigma_3) \end{array}$ 

# (by Jin and Ronen, 2005)





## Filtering



**F** result of filtering

- W original 3C data
- $\mathbf{E}_1$  and  $\mathbf{E}_2$  first two eigenimages of low-pass filtered original data

#### ... How much signal energy remains in the third SVD term E3?

#### Mathematical model of the record

$$\mathbf{W} = (\mathbf{w}_x \ \mathbf{w}_y \ \mathbf{w}_z)$$

with

$$\mathbf{w}_{i} = a_{i}\mathbf{D}_{i}\mathbf{g} + b_{i}\mathbf{s} + \mathbf{n}_{i}$$

$$\mathbf{D}_i = \begin{cases} \mathbf{I}, & i = x, y \\ \mathbf{H}, & i = z \end{cases}$$

- Iidentity operatorHdiscrete Hilbert transform
- $a_i$  and  $b_i$  amplitudes of ground roll and signal g and s "forms" of ground roll and signal

$$\|\mathbf{g}\| = \|\mathbf{H}\mathbf{g}\| = \|\mathbf{s}\| = 1$$
$$\|\mathbf{n}_i\| = c^2$$

#### **Cross-correlation matrix**

$$\mathbf{R} = \mathbf{W}^{T} \mathbf{W} = \begin{bmatrix} a_{x}^{2} + b_{x}^{2} + c^{2} & a_{x}a_{y} + b_{x}b_{y} & b_{x}b_{z} \\ a_{x}a_{y} + b_{x}b_{y} & a_{y}^{2} + b_{y}^{2} + c^{2} & b_{y}b_{z} \\ b_{x}b_{z} & b_{y}b_{z} & a_{z}^{2} + b_{z}^{2} + c^{2} \end{bmatrix}$$

Characteristic polynomial  $|\mathbf{R} - \lambda \mathbf{I}| = 0$ 

$$\lambda_0 = \lambda - c^2$$

$$\lambda_0^3 + q_2\lambda_0^2 + q_1\lambda_0 + q_0 = 0$$

 $q_0, q_1, q_2$  are functions of ground roll and signal amplitudes

## Cardano's formula: $\lambda_3 = \sigma_3^2 = 2\sqrt{-Q} \cos[(\theta + 2\pi)/3] + A/3 + c^2$

A, Q,  $\theta$  are functions of ground roll and signal amplitudes



If 
$$\alpha = 0$$
, then  $\lambda_3 = c^2$ 

In this case filter subtracts not only ground roll, but also signal.





**Signal** 

If ground roll is much stronger than signal, only an appreciable part of the horizontal signal component perpendicular to vector **a** remains after polarization filtering.

## Stochastic simulation of synthetic data

$$\mathbf{w}_i = a_i \mathbf{D}_i \mathbf{g} + b_i \mathbf{s}$$

"Forms" **g** and **s** are independent stochastic processes Random noise is negligible Signal has three components Ground roll has x and z components with fixed ratio of their energies:  $\frac{a_z^2}{a_x^2} = 4$ 

#### We studied the performance of polarization filtering depending on

(1) ground roll-to-signal energy ratio  $e = (a_x^2 + a_z^2)/(b_x^2 + b_y^2 + b_z^2)$ (2) vertical-to-horizontal signal component energy ratio  $p = b_z^2/(b_x^2 + b_y^2)$ (3) angle  $\alpha$  between vectors **a** and **b** 

#### We consider how much signal energy remains on y component Since P and S waves behave differently, we consider them separately.

#### P waves

the correlation coefficient with the "pure" signal



Vertical-to-horizontal signal component energy

Y component characteristics after polarisation filtering depending on ground roll-to-signal energy ratio e, vertical-to-horizontal signal component energy ratio p, and angle  $\alpha$  between vectors **a** and **b**.

#### S waves

the correlation coefficient with the "pure" signal



Horizontal-to-vertical signal component energy ratio

Y component characteristics after polarisation filtering depending on ground roll-to-signal energy ratio e, horizontal-to-vertical signal component energy ratio p, and angle  $\alpha$  between vectors **a** and **b**.

## Conclusions

• Single-station SVD-based polarization filtering has been investigated theoretically and using stochastic simulation of synthetic data

• After filter application, most of signal energy can be preserved only on horizontal component perpendicular to the plane where ground roll propagates

• For P- and SV-wave data, if  $\alpha$  is large and horizontal to vertical components energy ratio of signal is large, then application of the filter is favorable.

• For SH-wave data, application of the filter is favorable if ground roll-to-signal energy ratio is rather high.

• Influence of errors in scaling between data components is planned to be investigated

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